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A UNIFIED APPROACH TO STOCHASTIC EVOLUTION EQUATIONS USING THE SKOROKHOD INTEGRAL¹⁾

Мы изучаем стохастические эволюционные уравнения, управляемые гауссовским шумом. Основной отличительной чертой нашей модели является то, что операторы в детерминированной и стохастической частях могут иметь одинаковый порядок и шум может зависеть или только от времени, или же только от пространственной переменной, или же от того и другого. Даже простейшие уравнения такого вида не имеют квадратично-интегрируемого решения и решение нужно искать в специальных весовых пространствах. Мы доказываем, что версия Камерона–Мартина разложения винеровского хаоса приводит к естественным весам и естественной замене условия квадратичной интегрируемости.

Ключевые слова и фразы: обобщенные случайные элементы, исчисление Маллявена, произведение Вика, винеровский хаос, весовые пространства.

1. Introduction. Let W be a standard Brownian motion, $u_0 \in L_2(\mathbf{R})$, a a deterministic function, and σ , a real number. It is well known that the Itô equation

$$u(t, x) = u_0(x) + \int_0^t u_{xx}(s, x) ds + \int_0^t \sigma u(s, x) dW(s) \quad (1.1)$$

has a solution $u(t, x)$ and

$$\int_{\mathbf{R}} \mathbf{E} u^2(t, x) dx < \infty \quad (1.2)$$

for every $t > 0$ and all $\sigma \in \mathbf{R}$; see, for example, [10] or simply consider the Fourier transform of the equation. On the other hand, the solution of

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equation

$$u(t, x) = u_0(x) + \int_0^t u_{xx}(s, x) ds + \int_0^t \sigma u_x(s, x) dW(s) \quad (1.3)$$

satisfies (1.2) for an arbitrary $u_0 \in L_2(\mathbf{R})$ if and only if $|\sigma| \leq \sqrt{2}$, while equation

$$u(t, x) = u_0(x) + \int_0^t u_{xx}(s, x) ds + \int_0^t \sigma u_{xx}(s, x) dW(s) \quad (1.4)$$

hardly ever has a solution satisfying (1.2). Still, because of the Itô integral, all three equations share a common feature, namely, that the mean evolution is described by the heat equation. One of the objectives of this work is to develop a unified approach that would cover all three equations above without any special restrictions on the initial condition or the amplitude of noise.

The situation becomes even more complicated when the noise has a spacial component. As an illustration, take a standard random variable ξ and consider the equation

$$u(t) = 1 + \int_0^t u(s) ds + \int_0^t u(s) \xi ds.$$

The solution is clearly $u(t) = e^t e^{\xi t}$. The unperturbed solution is e^t , so that $\mathbf{E} u(t) \neq e^t$.

It turns out that, to preserve the mean dynamics, the usual product $u\xi$ must be replaced by the Wick product $u \diamond \xi$. In particular, the solution of

$$u(t) = 1 + \int_0^t u(s) ds + \int_0^t u(s) \diamond \xi ds \quad (1.5)$$

is $u(t) = e^t e^{\xi t - t^2/2}$ and satisfies $\mathbf{E} u(t) = e^t$. For partial differential equations of this type, such as

$$u(t, x) = u_0(x) + \int_0^t u_{xx}(s, x) ds + \int_0^t u_x(s, x) \diamond \xi ds, \quad (1.6)$$

inequality (1.2), without additional assumptions on u_0 , holds only for sufficiently small t . Moreover, the same framework that unifies equations (1.1), (1.3), (1.4) also covers (1.5), (1.6), and a wide class of other equations with space and space-time Gaussian noise.

There are three main components in the general construction presented in this paper:

- 1) use of the Skorokhod integral δ for all types of random perturbation;
- 2) separation of the time as the variable in the equation from the possible time evolution of the noise;

3) replacement of the space $L_2(\Omega; X)$ of square-integrable X -valued processes with a space $(\mathcal{L})_{Q,r}(X)$ of generalized (and not necessarily adapted) random elements as the space for both the input data and the solution.

Section 2 presents the necessary definitions and constructions related to the Skorokhod integral with respect to an abstract Gaussian white noise and Section 3 introduces the spaces $(\mathcal{L})_{Q,r}$. Section 4 presents the unified treatment of stochastic evolution equations. While the main results, Theorem 4.2, cannot be fully understood without all the preliminaries, there is a certain analogy with the corresponding result for the deterministic equations. Namely, let (V, H, V') be a normal triple of Hilbert spaces (defined precisely in Section 4) and let $\mathbf{A}(t)$, $t \in [0, T]$, be a family of bounded linear operators from V to V' . It is known from deterministic analysis that if the family of operators $\mathbf{A}(t)$ is uniformly elliptic, then the initial value problem for the equation $u(t) = u_0 + \int_0^t (\mathbf{A}(s)u(s) + f(s)) ds$ is well posed in the normal triple (V, H, V') .

Now consider the initial value problem for the stochastic equation

$$u(t) = u_0 + \int_0^t (\mathbf{A}(s)u(s) + f(s)) ds + \int_0^t \delta(\mathbf{M}(s)u(s)) ds. \quad (1.7)$$

The statement of Theorem 4.2 is essentially as follows: if the family of operators $\mathbf{A}(t)$ is uniformly elliptic and $\mathbf{M}(t)$ is a family of continuous operators from V to V' , then the initial value problem (1.7) is well posed in the normal triple $((\mathcal{L})_{Q,r}(V), (\mathcal{L})_{Q,r}(H), (\mathcal{L})_{Q,r}(V'))$. The reader should not miss Example 4.1 illustrating how many familiar equations are particular cases of (1.7).

2. Skorokhod integral with respect to Gaussian white noise.

Let $\mathbf{F} = (\Omega, \mathcal{F}, \mathbf{P})$ be a complete probability space, and let $\mathcal{U}$ be a real separable Hilbert space with inner product $(\cdot, \cdot)_{\mathcal{U}}$. On $\mathbf{F}$, consider a zero-mean Gaussian family

$$\dot{W} = \{\dot{W}(h), h \in \mathcal{U}\}$$

so that

$$\mathbf{E}(\dot{W}(h_1) \dot{W}(h_2)) = (h_1, h_2)_{\mathcal{U}}.$$

It suffices, for our purposes, to assume that $\mathcal{F}$ is the σ -algebra generated by $\dot{W}(h)$, $h \in \mathcal{U}$. Given a real separable Hilbert space X , we denote by $L_2(\mathbf{F}; X)$ the Hilbert space of square-integrable $\mathcal{F}$ -measurable X -valued random elements f . In particular,

$$(f, g)_{L_2(\mathbf{F}; X)}^2 := \mathbf{E}(f, g)_X^2.$$

When $X = \mathbf{R}$, we write $L_2(\mathbf{F})$ instead of $L_2(\mathbf{F}; \mathbf{R})$.

Definition 2.1. A formal series

$$\dot{W} = \sum_{k \geq 1} \dot{W}(u_k) u_k, \quad (2.1)$$

where $\{u_k, k \geq 1\}$ is a complete orthonormal basis in $\mathcal{U}$, is called Gaussian white noise on $\mathcal{U}$.

Example 2.1. If $\mathcal{U} = L_2((0, T))$, then $\dot{W}(h) = \int_0^T h(s) dw(s)$, where $w(t) = \dot{W}(\chi_t)$ is the standard Brownian motion; χ_t is the characteristic function of the interval $[0, t]$.

Given an orthonormal basis $u = \{u_k, k \geq 1\}$ in $\mathcal{U}$, define a collection $\{\xi_k, k \geq 1\}$ of independent standard Gaussian random variables by $\xi_k = \dot{W}(u_k)$. Let $\mathcal{J}$ be the collection of multi-indices α with $\alpha = (\alpha_1, \alpha_2, \dots)$ such that each α_k is a nonnegative integer and $|\alpha| := \sum_{k \geq 1} \alpha_k < \infty$. For $\alpha, \beta \in \mathcal{J}$, we define

$$\alpha + \beta = (\alpha_1 + \beta_1, \alpha_2 + \beta_2, \dots), \quad \alpha! = \prod_{k \geq 1} \alpha_k!.$$

By (0) we denote the multi-index with all zeroes. By ε_i we denote the multi-index α with $\alpha_i = 1$ and $\alpha_j = 0$ for $j \neq i$. With this notation, $n\varepsilon_i$ is the multi-index α with $\alpha_i = n$ and $\alpha_j = 0$ for $j \neq i$.

Define the collection of random variables $\Xi = \{\xi_\alpha, \alpha \in \mathcal{J}\}$ as follows:

$$\xi_\alpha = \prod_k \frac{H_{\alpha_k}(\xi_k)}{\sqrt{\alpha_k!}}, \quad (2.2)$$

where

$$H_n(x) = (-1)^n e^{x^2/2} \frac{d^n}{dx^n} e^{-x^2/2} \quad (2.3)$$

is Hermite polynomial of order n .

Theorem 2.1 (Cameron and Martin [1]). *The collection $\Xi = \{\xi_\alpha, \alpha \in \mathcal{J}\}$ is an orthonormal basis in $L_2(\mathbf{F}; X)$; if $\eta \in L_2(\mathbf{F}; X)$ and $\eta_\alpha = \mathbf{E}(\eta \xi_\alpha)$, then $\eta = \sum_{\alpha \in \mathcal{J}} \eta_\alpha \xi_\alpha$ and $\mathbf{E}|\eta|^2 = \sum_{\alpha \in \mathcal{J}} \eta_\alpha^2$.*

Denote by $\mathbf{D}$ the Malliavin derivative on $L_2(\mathbf{F})$ (see, e.g., [9]). In particular, if $F: \mathbf{R}^N \rightarrow \mathbf{R}$ is a smooth function and $h_i \in \mathcal{U}$, $i = 1, \dots, N$, then

$$\mathbf{D} F(\dot{W}(h_1), \dots, \dot{W}(h_N)) = \sum_{i=1}^N \frac{\partial F}{\partial x_i} (\dot{W}(h_1), \dots, \dot{W}(h_N)) h_i \in L_2(\mathbf{F}; \mathcal{U}). \quad (2.4)$$

It is known [9] that the domain $\mathbb{D}^{1,2}(\mathbf{F})$ of the operator $\mathbf{D}$ is a dense linear subspace of $L_2(\mathbf{F})$.

The adjoint of the Malliavin derivative on $L_2(\mathbf{F})$ is the Skorokhod integral and is traditionally denoted by δ [9]. The operator δ extends to a subspace $\mathbb{D}^{1,2}(\mathbf{F}; X \otimes \mathcal{U})$ of $L_2(\mathbf{F}; X \otimes \mathcal{U})$ for a Hilbert space X : given $f \in \mathbb{D}^{1,2}(\mathbf{F}; X \otimes \mathcal{U})$, $\delta(f)$ is a unique element of $L_2(\mathbf{F}; X)$ with the property

$$\mathbf{E}(\varphi \delta(f)) = \mathbf{E}(f, \mathbf{D} \varphi)_{\mathcal{U}} \quad (2.5)$$

for all $\varphi \in \mathbb{D}^{1,2}(\mathbf{F})$.

We will now derive the expressions for the operators $\mathbb{D}$ and δ in the basis Ξ . To begin, let us compute $\mathbf{D} \xi_\alpha$.

Proposition 2.1. *For each $\alpha \in \mathcal{J}$,*

$$\mathbf{D} \xi_\alpha = \sum_{k \geq 1} \sqrt{\alpha_k} \xi_{\alpha - \varepsilon_k} \mathbf{u}_k. \quad (2.6)$$

P r o o f. The result follows by direct computation using property (2.4) of the Malliavin derivative and the relation $H'_n(x) = nH_{n-1}(x)$ for the Hermite polynomials (cf. [9, Chap. 1]).

R e m a r k 2.1. The set $\mathcal{J}$ is not closed under subtraction and the expression $\alpha - \varepsilon_k$ is undefined if $\alpha_k = 0$. Everywhere in this paper when undefined expressions of this type appear, we use the following convention: if $\alpha_k = 0$, then $\sqrt{\alpha_k} \xi_{\alpha - \varepsilon_k} = 0$.

Proposition 2.2. *For $\xi_\alpha \in \Xi$, $h \in X$, and $\mathbf{u}_k \in \mathbf{u}$,*

$$\delta(\xi_\alpha h \otimes \mathbf{u}_k) = h \sqrt{\alpha_k + 1} \xi_{\alpha + \varepsilon_k}. \quad (2.7)$$

P r o o f. It is enough to verify (2.5) with $f = h \otimes \mathbf{u}_k \xi_\alpha$ and $\varphi = \xi_\beta$, where $h \in X$. By (2.6),

$$\mathbf{E}(f, \mathbf{D} \varphi)_{\mathcal{U}} = \sqrt{\beta_k} h \mathbf{E}(\xi_\alpha \xi_{\beta - \varepsilon_k}) = \begin{cases} \sqrt{\alpha_k + 1} h, & \text{if } \alpha = \beta - \varepsilon_k, \\ 0, & \text{if } \alpha \neq \beta - \varepsilon_k. \end{cases}$$

In other words,

$$\mathbf{E}(\xi_\alpha h \otimes \mathbf{u}_k, \mathbf{D} \xi_\beta)_{\mathcal{U}} = h \mathbf{E}(\sqrt{\alpha_k + 1} \xi_{\alpha + \varepsilon_k} \xi_\beta)$$

for all $\beta \in \mathcal{J}$.

R e m a r k 2.2. The operator $\delta \mathbf{D}$ is linear and unbounded on $L_2(\mathbf{F})$; it follows from Propositions 2.1 and 2.2 that the random variables ξ_α are eigenfunctions of this operator:

$$\delta(\mathbf{D} \xi_\alpha) = |\alpha| \xi_\alpha. \quad (2.8)$$

To give an alternative characterization of the operator δ , we define a new operation on the elements of Ξ .

D e f i n i t i o n 2.2. For ξ_α, ξ_β from Ξ , define the Wick product

$$\xi_\alpha \diamond \xi_\beta := \sqrt{\frac{(\alpha + \beta)!}{\alpha! \beta!}} \xi_{\alpha + \beta}. \quad (2.9)$$

In particular, taking in (2.9) $\alpha = k\varepsilon_i$ and $\beta = n\varepsilon_i$, and using (2.2), we get

$$H_k(\xi_i) \diamond H_n(\xi_i) = H_{k+n}(\xi_i). \quad (2.10)$$

An immediate consequence of Proposition 2.2 and Definition 2.2 is the following identity:

$$\delta(\xi_\alpha h \otimes \mathbf{u}_k) = h \xi_\alpha \diamond \xi_k, \quad h \in X. \quad (2.11)$$

More generally, we define the operation $\diamond$ on formal series:

$$\left(\sum_{\alpha \in \mathcal{J}} f_\alpha \xi_\alpha \right) \diamond \left(\sum_{\alpha \in \mathcal{J}} g_\alpha \xi_\alpha \right) = \sum_{\alpha \in \mathcal{J}} \left(\sum_{\beta, \gamma \in \mathcal{J} : \beta + \gamma = \alpha} \sqrt{\frac{\alpha!}{\beta! \gamma!}} f_\beta g_\gamma \right) \xi_\alpha$$

for $f_\alpha \in X$, $g_\alpha \in \mathbf{R}$.

Theorem 2.2. *If $f = \sum_{k \geq 1} f_k \otimes \mathbf{u}_k$, $f_k = \sum_{\alpha \in \mathcal{J}} f_{k,\alpha} \xi_\alpha \in L_2(\mathbf{F}; X)$, and f is in the domain of δ , then*

$$\delta(f) = \sum_{k \geq 1} f_k \diamond \xi_k, \quad (2.12)$$

and

$$(\delta(f))_\alpha = \sum_{k \geq 1} \sqrt{\alpha_k} f_{k, \alpha - \varepsilon_k}. \quad (2.13)$$

P r o o f. By linearity and (2.11),

$$\delta(f) = \sum_{k \geq 1} \sum_{\alpha \in \mathcal{J}} \delta(\xi_\alpha f_{k,\alpha} \otimes \mathbf{u}_k) = \sum_{k \geq 1} \sum_{\alpha \in \mathcal{J}} f_{k,\alpha} \xi_\alpha \diamond \xi_k = \sum_{k \geq 1} f_k \diamond \xi_k,$$

which is (2.12). On the other hand, by (2.7),

$$\delta(f) = \sum_{k \geq 1} \sum_{\alpha \in \mathcal{J}} f_{k,\alpha} \sqrt{\alpha_k + 1} \xi_{\alpha + \varepsilon_k} = \sum_{k \geq 1} \sum_{\alpha \in \mathcal{J}} f_{k, \alpha - \varepsilon_k} \sqrt{\alpha_k} \xi_\alpha,$$

and (2.13) follows. Theorem 2.2 is proved.

To proceed, we need a description of a multi-index α with $|\alpha| = n > 0$ using its characteristic set K_α , that is, an ordered n -tuple $K_\alpha = \{k_1, \dots, k_n\}$, where $k_1 \leq \dots \leq k_n$ characterize the locations and the values of the nonzero elements of α . More precisely, k_1 is the index of the first nonzero element of α , followed by $\max(0, \alpha_{k_1} - 1)$ of entries with the same value. The next entry after that is the index of the second nonzero element of α , followed by $\max(0, \alpha_{k_2} - 1)$ of entries with the same value, and so on. For example, if $n = 7$ and $\alpha = (1, 0, 2, 0, 0, 1, 0, 3, 0, \dots)$, then the nonzero elements of α are $\alpha_1 = 1$, $\alpha_3 = 2$, $\alpha_6 = 1$, $\alpha_8 = 3$. As a result, $K_\alpha = \{1, 3, 3, 6, 8, 8, 8\}$, that is, $k_1 = 1$, $k_2 = k_3 = 3$, $k_4 = 6$, $k_5 = k_6 = k_7 = 8$. Note also that, for every sequence $(b_k, k \geq 1)$ of positive numbers,

$$\prod_{k \geq 1} b_k^{\alpha_k} = b_{i_1} \cdots b_{i_n} = \prod_{i \in K_\alpha} b_i, \quad (2.14)$$

which can serve as an equivalent definition of K_α .

Using the notion of the characteristic set, we now state the following analog of the well-known result of Itô [3] connecting multiple Wiener integrals and Hermite polynomials.

Proposition 2.3. *Let $\alpha \in \mathcal{J}$ be a multi-index with $|\alpha| = n \geq 1$ and characteristic set $K_\alpha = \{k_1, \dots, k_n\}$. Then*

$$\xi_\alpha = \frac{\xi_{k_1} \diamond \dots \diamond \xi_{k_n}}{\sqrt{\alpha!}}. \quad (2.15)$$

P r o o f. This follows from (2.2) and (2.10), because by (2.10), for every i and k ,

$$H_k(\xi_i) = \xi_i \diamond \dots \diamond \xi_i \quad (k \text{ times}).$$

By induction, we define the operator $\delta^{\hat{\otimes} n}$, $n > 1$, on the space $L_2(\mathbf{F}; X \otimes \mathcal{U}^{\hat{\otimes} n})$, where $\mathcal{U}^{\hat{\otimes} n}$ is the symmetric tensor power of $\mathcal{U}$. Then relation (2.11) leads to an alternative form of (2.15):

$$\xi_\alpha = \frac{1}{|\alpha|! \sqrt{\alpha!}} \delta^{\hat{\otimes} |\alpha|}(E_\alpha), \quad (2.16)$$

where

$$E_\alpha = \sum_{\sigma \in \mathcal{P}} \mathbf{u}_{i_{\sigma(1)}} \otimes \dots \otimes \mathbf{u}_{i_{\sigma(n)}}, \quad (2.17)$$

with summation in (2.17) taken over all permutations $\mathcal{P}$ of the set $\{1, \dots, n\}$. This leads to the following generalization of the multiple Wiener integral expansion for the elements of $L_2(\mathbf{F}; X)$.

Theorem 2.3. *If $\eta \in L_2(\mathbf{F}; X)$, then there is a unique collection of the deterministic elements η_k , $k \geq 0$, with $\eta_0 = \mathbf{E}\eta \in X$ and $\eta_k \in X \otimes \mathcal{U}^{\hat{\otimes} k}$, $k \geq 1$, with the properties*

$$\eta = \eta_0 + \sum_{k \geq 1} \frac{1}{k!} \delta^{\hat{\otimes} k}(\eta_k), \quad \mathbf{E} \|\eta\|_X^2 = \|\eta_0\|_X^2 + \sum_{k \geq 1} \frac{1}{k!} \|\eta_k\|_{\mathcal{U}^{\hat{\otimes} k}}^2. \quad (2.18)$$

P r o o f. Using (2.16) and Theorem 2.1, we find that

$$\eta = \eta_0 + \sum_{k=1}^{\infty} \frac{1}{k!} \sum_{|\alpha|=k} \eta_\alpha \delta^{\hat{\otimes} k} \left(\frac{1}{\sqrt{\alpha!}} E_\alpha \right),$$

and we get the first equality in (2.18) with $\eta_k = \sum_{|\alpha|=k} ((\eta_\alpha / \sqrt{\alpha!}) \otimes E_\alpha)$. The second equality in (2.18) now follows from $\mathbf{E} \|\eta\|_X^2 = \|\eta_0\|_X^2 + \sum_{k \geq 1} \sum_{|\alpha|=k} \|\eta_\alpha\|_X^2$, because, by direct computation,

$$\|E_\alpha\|_{\mathcal{U}^{\hat{\otimes} n}}^2 = k! \alpha!. \quad (2.19)$$

3. The spaces $(\mathcal{L})_{Q,r}$.

Definition 3.1. A sequence $Q = \{q_k, k \geq 1\}$ is called a *weight sequence* if $q_k \geq 1$ for all $k \geq 1$.

For $\alpha \in \mathcal{J}$ and a real number r we write

$$q^{r\alpha} = \prod_{k \geq 1} q_k^{r\alpha_k}.$$

Given a weight sequence Q , denote by Λ_Q the following self-adjoint operator on $\mathcal{U}$:

$$\Lambda_Q u_k = q_k u_k, \quad k \geq 1.$$

Then, for every $r \in \mathbf{R}$, the operator Λ_Q^r is defined. The domain of every Λ_Q^r contains finite linear combinations of u_k and is therefore dense in $\mathcal{U}$. For f in the domain of Λ_Q^r define the norm

$$\|f\|_{Q,r} = \|\Lambda_Q^r f\|_{\mathcal{U}}. \quad (3.1)$$

The operator Λ_Q^r extends to every tensor product $X \otimes \mathcal{U}^{\otimes n}$; we will keep the same notation for this extension and, in the case $X = \mathbf{R}$, for the corresponding norm (3.1). Denote by $(\mathcal{L})^{Q,r}(\mathbf{F})$ the dual space of $(\mathcal{L})_{Q,r}(\mathbf{F})$ relative to the inner product in $L_2(\mathbf{F})$. If $\eta \in (\mathcal{L})_{Q,r}(\mathbf{F}; X)$ and $\zeta \in (\mathcal{L})^{Q,r}(\mathbf{F})$, then the duality $\langle\langle \eta, \zeta \rangle\rangle$ is defined and is an element of X .

Definition 3.2. The space $(\mathcal{L})_{Q,r}(\mathbf{F}; X)$ is the closure of the set of random elements of the form

$$\eta = \eta_0 + \sum_{k=1}^N \frac{1}{k!} \delta^{\hat{\otimes} k}(\eta_k), \quad N \geq 1,$$

where $\eta_0 \in X$, $\eta_k \in X \otimes \mathcal{U}^{\hat{\otimes} k}$, and each η_k is in the domain of Λ_Q^r , with respect to the norm

$$\|\eta\|_{Q,r;X}^2 = \|\eta_0\|_X^2 + \sum_{k=1}^N \frac{1}{(k!)^2} \|\eta_k\|_{Q,r}^2. \quad (3.2)$$

Theorem 3.1. A formal series $\eta = \sum_{\alpha \in \mathcal{J}} \eta_\alpha \xi_\alpha$ is an element of $(\mathcal{L})_{Q,r}(\mathbf{F}; X)$ if and only if

$$\sum_{\alpha \in \mathcal{J}} \frac{1}{|\alpha|!} q^{2r\alpha} \|\eta_\alpha\|_X^2 < \infty. \quad (3.3)$$

The left-hand side of (3.3), if finite, is equal to $\|\eta\|_{Q,r;X}^2$.

Proof. By orthonormality of ξ_α , it is enough to consider $\eta = f\xi_\alpha$, $f \in X$. Then (2.18) implies

$$\|\eta\|_{Q,r;X}^2 = \frac{1}{(|\alpha|!)^2 \alpha!} \|E_\alpha\|_{Q,r}^2 \|f\|_X^2 = \frac{q^{2r\alpha}}{|\alpha|!} \|f\|_X^2,$$

since the definition of E_α implies $\|E_\alpha\|_{Q,r}^2 = q^{2r\alpha} |\alpha|! \alpha!$.

Corollary 3.1. *A formal series $\zeta = \sum_{\alpha \in \mathcal{J}} \zeta_\alpha \xi_\alpha$ is an element of the dual space $(\mathcal{L})^{Q,r}(\mathbf{F})$ if and only if*

$$\sum_{\alpha \in \mathcal{J}} |\alpha|! q^{-2r\alpha} |\zeta_\alpha|^2 < \infty.$$

In this case,

$$\langle\langle \eta, \zeta \rangle\rangle = \sum_{\alpha \in \mathcal{J}} \eta_\alpha \zeta_\alpha.$$

For $h \in \mathcal{U}$ define the stochastic exponential

$$\mathcal{E}_h = \exp \left(\dot{W}(h) - \frac{1}{2} \|h\|_{\mathcal{U}}^2 \right). \quad (3.4)$$

Proposition 3.1. $\mathcal{E}_h \in (\mathcal{L})^{Q,r}(\mathbf{F})$ if and only if $\|h\|_{Q,-r} < 1$.

P r o o f. We apply Corollary 3.1. If $h = \sum_{k \geq 1} h_k u_k$, $h_k \in \mathbf{R}$, then by direct computation using the generating function of the Hermite polynomials,

$$\mathcal{E}_h = \sum_{\alpha \in \mathcal{J}} \frac{h^\alpha}{\sqrt{\alpha!}} \xi_\alpha, \quad h^\alpha = \prod_{k \geq 1} h_k^{\alpha_k}. \quad (3.5)$$

Then, by the multinomial expansion,

$$\sum_{\alpha \in \mathcal{J}} \frac{|\alpha|!}{\alpha!} h^{2\alpha} q^{-2r\alpha} = \sum_{n \geq 0} \left(\sum_{k \geq 1} h_k^2 q_k^{-2r} \right)^n = \sum_{n \geq 0} \left(\|h\|_{Q,-r}^2 \right)^n$$

and the result follows.

In applications to evolutions equations, the number r in the solution space $(\mathcal{L})_{Q,r;X}$ is usually *negative*, as we want to help the series in (3.3) to converge. As a result, the following definition is appropriate.

D e f i n i t i o n 3.3. We say that the element h of $\mathcal{U}$ is *sufficiently small relative to the sequence Q* if there exists a positive number r such that $\|h\|_{r,Q} < 1$.

4. The evolution equation and main result.

D e f i n i t i o n 4.1. The triple (V, H, V') of Hilbert spaces is called *normal* if and only if

- 1) $V \hookrightarrow H \hookrightarrow V'$ and both embeddings $V \hookrightarrow H$ and $H \hookrightarrow V'$ are dense and continuous;
- 2) the space V' is the dual of V relative to the inner product in H ;
- 3) there exists a constant $C > 0$ such that $|(f, v)_H| \leq C \|v\|_V \|f\|_{V'}$ for all $v \in V$ and $f \in H$.

For example, the Sobolev spaces $(H_2^{\ell+\gamma}(\mathbf{R}^d), H_2^\ell(\mathbf{R}^d), H_2^{\ell-\gamma}(\mathbf{R}^d))$, $\gamma > 0$, $\ell \in \mathbf{R}$, form a normal triple.

Denote by $\langle v', v \rangle$, $v' \in V'$, $v \in V$, the duality between V and V' relative to the inner product in H . The properties of the normal triple imply that $|\langle v', v \rangle| \leq C \|v\|_V \|v'\|_{V'}$, and, if $v' \in H$ and $v \in V$, then $\langle v', v \rangle = (v', v)_H$.

We will also use the following notation:

$$\mathcal{V}(T) = L_2((0, T); V), \quad \mathcal{H}(T) = L_2((0, T); H), \quad \mathcal{V}'(T) = L_2((0, T); V'). \quad (4.1)$$

Given a normal triple (V, H, V') , let $\mathbf{A}(t): V \rightarrow V'$ and $\mathbf{M}(t): V \rightarrow V' \otimes \mathcal{U}$ be bounded linear operators for every $t \in [0, T]$.

Definition 4.2. The solution of the stochastic evolution equation

$$u(t) = u^0 + \int_0^t \left(\mathbf{A}(s)u(s) + f(s) + \delta(\mathbf{M}(s)u(s)) \right) ds, \quad 0 \leq t \leq T, \quad (4.2)$$

with $f \in \bigcup_r (\mathcal{L})_{Q,r}(\mathbf{F}; \mathcal{V}'(T))$ and $u^0 \in \bigcup_r (\mathcal{L})_{Q,r}(\mathbf{F}; H)$, is an object with the following properties:

1) There exist a weight sequence Q' and a real number r' such that

$$u \in (\mathcal{L})_{Q',r'}(\mathbf{F}; \mathcal{V}(T));$$

2) for every $h \in \mathcal{U}$ which is sufficiently small relative to the sequence Q' , the function $u_h(t) = \langle u(t), \mathcal{E}_h \rangle$ satisfies

$$u_h(t) = u_h(0) + \int_0^t \left(\mathbf{A}(s)u_h(s) + f_h(s) + (\mathbf{M}(s)u_h(s), h)_{\mathcal{U}} \right) ds \quad (4.3)$$

in $\mathcal{V}'(T)$.

Remark 4.1. The solution described by Definition 4.2 belongs to the class of «variational solutions», which is quite typical for partial differential equations (see [5], [7], [8], [10], etc.). Indeed, direct computations show that $\mathbf{D} \mathcal{E}_h = h \mathcal{E}_h$, and then (4.3) is the result of a (formal) application of the duality $\langle u, \mathcal{E}_h \rangle$ to both sides of (4.2).

Fix an orthonormal basis $\mathfrak{U} = \{u_k, k \geq 1\}$ in $\mathcal{U}$. Then, for every $v \in V$, there exists a collection $v_k \in V'$, $k \geq 1$, such that

$$\mathbf{M}v = \sum_{k \geq 1} v_k \otimes u_k.$$

We therefore define the operators $\mathbf{M}_k: V \rightarrow V'$ by setting $\mathbf{M}_k v = v_k$ and write

$$\mathbf{M}v = \sum_{k \geq 1} (\mathbf{M}_k v) \otimes u_k.$$

Then

$$\delta(\mathbf{M}(s)u(s)) = \sum_{k \geq 1} \mathbf{M}_k(s)u(s) \diamond \xi_k, \quad \xi_k = \dot{W}(u_k), \quad (4.4)$$

and equation (4.2) becomes

$$u(t) = u^0 + \int_0^t \left(\mathbf{A}(s)u(s) + f(s) + \sum_{k \geq 1} \mathbf{M}_k(s)u(s) \diamond \dot{W}(u_k) \right) ds. \quad (4.5)$$

If the noise $\dot{W}$ itself depends on time, this dependence is encoded in the operator $\mathbf{M}$. As a result, (4.2) includes many popular evolution equations as particular cases.

Example 4.1. 1) Let us see how the elementary Itô equation $u(t) = 1 + \int_0^t u(s) dw(s)$, where w is a standard Brownian motion, is a particular case of (4.2). We take $V = H = V' = \mathbf{R}$, $\mathcal{U} = L_2((0, T))$, so that $\dot{W} = \dot{w}(t) = \sum_{k \geq 1} u_k(t) \xi_k$ is the Gaussian white noise in time. Next, put $\mathbf{A} = 0$, $\mathbf{M}_k(t)u(t) = u(t)u_k(t)$. Then $\delta(\mathbf{M}_k(t)u(t)) = u(t) \diamond \sum_{k \geq 1} u_k(t) \xi_k = u(t) \diamond \dot{w}(t)$. The equivalence of $u(t) = 1 + \int_0^t \delta(\mathbf{M}(s)u(s)) ds$ and $u(t) = 1 + \int_0^t u(s) dw(s)$ now follows from the equality $\int_0^t u(s) \diamond \dot{w}(s) ds = \int_0^t u(s) dw(s)$; see [2, Section 2.5].

2) Equations with space-time white noise correspond to $\mathcal{U} = L_2((0, T)) \times L_2(G)$, $G \subseteq \mathbf{R}^d$, so that the basis in $\mathcal{U}$ is naturally indexed by a pair of indices i, k : $u_{ik} = m_i(t)h_k(x)$. Thus, equation $du(t, x) = u_{xx} dt + u dW(t, x)$ is a particular case of (4.2) with $\mathbf{M}_{ik}(t)u(t, x) = m_i(t)h_k(x)u(t, x)$.

3) Equations with fractional noise are also covered by (4.2). For example, consider $u(t) = 1 + \int_0^t u(s) dW^H(s)$, where W^H is fractional Brownian motion and $H > \frac{1}{2}$. With the appropriate interpretation of the stochastic integral, we have

$$\int_0^t u(s) dW^H(s) = \int_0^t u(s) \diamond \dot{w}^H(s) ds,$$

where

$$\dot{w}^H(t) = \sum_{k \geq 1} m_k^H(t) \xi_k$$

and m_k^H are suitable elements of $L_2((0, T))$ (see, for example, [9, Chap. 5]). Then, in (4.2), we take $\mathcal{U} = L_2((0, T))$ and $\mathbf{M}_k(t)u(t) = m_k^H(t)u(t)$.

Let us fix an orthonormal basis $\mathfrak{U}$ in $\mathcal{U}$ so that equation (4.2) becomes (4.5). With $\xi_k = \dot{W}(\mathfrak{U}_k)$, define ξ_α , $\alpha \in \mathcal{J}$, according to (2.2). Given a Hilbert space X , every element η of $(\mathcal{L})_{Q,r}(\mathbf{F}; X)$ can be written as a formal series $\sum_\alpha \eta_\alpha \xi_\alpha$ with $\eta_\alpha \in X$ satisfying (3.3). The following theorem provides a necessary and sufficient condition for the formal series $\sum_\alpha u_\alpha(t) \xi_\alpha$ to be a solution of (4.5).

Theorem 4.1. *Let $u = \sum_{\alpha \in \mathcal{J}} u_\alpha \xi_\alpha$ be an element of $(\mathcal{L})_{Q',r'}(\mathbf{F}; \mathcal{V}(T))$. The process u is a solution of equation (4.5) if and only if the functions u_α have the following properties:*

- 1) every u_α is an element of $\mathbf{C}([0, T]; H)$;
- 2) the system of equalities

$$u_\alpha(t) = u_\alpha^0 + \int_0^t \left(\mathbf{A}(s)u_\alpha(s) + f_\alpha(s) + \sum_{k \geq 1} \sqrt{\alpha_k} \mathbf{M}_k(s)u_{\alpha - \varepsilon_k}(s) \right) ds \quad (4.6)$$

holds in $\mathcal{V}'(T)$ for all $\alpha \in \mathcal{J}$.

P r o o f. If $h = \sum_k h_k u_k$, then, by (3.5) and Corollary 3.1, $u_h = \sum_{\alpha \in \mathcal{J}} u_\alpha h^\alpha / \sqrt{\alpha!}$. With no loss of generality we can assume that $\sum_{k \geq 1} (q'_k)^2 < \infty$. Then, by a general result from functional analysis [4], the mapping $u_h: \mathcal{U} \rightarrow \mathcal{V}(T)$ is analytic at zero. By direct computation,

- 1) if u_h satisfies (4.3), then

$$u_\alpha = \frac{1}{\sqrt{\alpha!}} \frac{\partial^{|\alpha|} u_h}{\partial h_1^{\alpha_1} \partial h_2^{\alpha_2} \dots} \Big|_{h=0}$$

and each u_α satisfies (4.6);

- 2) if u_α satisfies (4.6) and $u_h = \sum_\alpha u_\alpha h^\alpha$, then u_h satisfies (4.3).

Theorem 4.1 is proved.

This simple but very helpful result establishes the equivalence of the «physical» (4.5) and the (stochastic) Fourier (4.6) forms of equation (4.2). The system of equations (4.6) is often referred in the literature as the *propagator* of equation (4.5). Note that the propagator is lower-triangular and can be solved by induction on $|\alpha|$.

To prove existence and uniqueness of solution of (4.2), we make the following assumptions about the operators $\mathbf{A}$ and $\mathbf{M}$.

(A): For every $U_0 \in H$ and $F \in \mathcal{V}'(T)$, there exists a unique function $U \in \mathcal{V}$ that solves the deterministic equation

$$\partial_t U(t) = \mathbf{A}(t)U(t) + F(t), \quad U(0) = U_0 \quad (4.7)$$

and there exists a constant $C_A = C_A(\mathbf{A}, T)$ such that

$$\|U\|_{\mathcal{V}(T)} \leq C_A (\|U_0\|_H + \|F\|_{\mathcal{V}'(T)}). \quad (4.8)$$

In particular, the operator $\mathbf{A}$ generates a semigroup $\Phi = (\Phi_{t,s}, t \geq s \geq 0)$ and

$$U(t) = \Phi_{t,0}U_0 + \int_0^t \Phi_{t,s}F(s) ds.$$

(M): For every $v \in \mathcal{V}(T)$ and $k \geq 1$,

$$\int_0^T \left\| \int_0^t \Phi_{t,s} \mathbf{M}_k(s)v(s) ds \right\|_V^2 dt \leq C_k^2 \|v\|_{\mathcal{V}(T)}^2, \quad (4.9)$$

with numbers C_k which do not depend on v .

R e m a r k 4.2. There are various types of assumptions on the operator $\mathbf{A}$ that yield the statement of the assumption (A). In particular, (A) holds if the operator $\mathbf{A}$ is coercive in (V, H, V') :

$$\langle \mathbf{A}(t)v, v \rangle + \gamma \|v\|_V^2 \leq C \|v\|_H^2$$

for every $v \in V$, $t \in [0, T]$, where neither $\gamma > 0$ nor $C \in \mathbf{R}$ depends on v, t .

The following theorem is the main result of this paper.

Theorem 4.2. *In addition to (A) and (M), assume that, for some positive number r and a weight sequence Q , $u^0 \in (\mathcal{L})_{Q, -r}(\mathbf{F}; H)$ and $f \in (\mathcal{L})_{Q, -r}(\mathbf{W}; \mathcal{V}'(T))$. If*

$$\sum_{k \geq 1} \frac{1}{q_k^{2r}} \leq \frac{1}{2}, \quad (4.10)$$

then there exist a weight sequence Q° and a negative real number r° such that equation (4.2) has a unique solution $u \in (\mathcal{L})_{Q^\circ, r^\circ}(\mathbf{F}; \mathcal{V}(T))$ and

$$\|u\|_{Q^\circ, r^\circ; \mathcal{V}(T)}^2 \leq C \left[\|u^0\|_{Q, r; H}^2 + \|f\|_{Q, r; \mathcal{V}'(T)}^2 \right]. \quad (4.11)$$

The number $C > 0$ depends only on Q, r, T and the operators $\mathbf{A}, \mathbf{M}$.

P r o o f. The proof consists of two steps: first, we prove the result for deterministic functions u^0, f and then use linearity to extend the result to the general case.

S t e p 1.

Proposition 4.1. *Assume that the functions $u^0 \in H$, $f \in \mathcal{V}'(T)$ are deterministic so that $u_h^0 = u^0$, $f_h = f$. Then there exist a weight sequence $Q^* = \{q_k^*, k \geq 1\}$ and a number $r^* > 0$ such that*

$$\|u\|_{Q^*, -r^*; \mathcal{V}(T)}^2 \leq 2C_A \left[\|u^0\|_H^2 + \|f\|_{\mathcal{V}'(T)}^2 \right]. \quad (4.12)$$

P r o o f. By assumptions (4.8) and (4.9) the evolution equation

$$u_h(t) = u^0 + \int_0^t \left(\mathbf{A}(s)u_h(s) + f(s) + \sum_{k=1}^{\infty} \mathbf{M}_k(s)u_h(s)h_k \right) ds \quad (4.13)$$

has a unique solution in $\mathcal{V}(T)$ as long as $\sum_{k \geq 1} h_k^2$ is small enough; since the equation is linear, the solution is an analytic function of h_k .

Next,

$$u(t) = \sum_{\alpha \in \mathcal{J}} u_\alpha(t) \xi_\alpha \quad (4.14)$$

and, by (4.6), the coefficients u_α satisfy

$$\begin{aligned} u_{(0)}(t) &= u^0 + \int_0^t (\mathbf{A}(s)u_{(0)}(s) + f(s)) ds, & |\alpha| = 0; \\ u_{\varepsilon_k}(t) &= \int_0^t \mathbf{A}(s)u_{\varepsilon_k}(s) ds + \int_0^t \mathbf{M}_k(s)u_{(0)}(s) ds, & |\alpha| = 1; \\ u_\alpha(t) &= \int_0^t \mathbf{A}(s)u_\alpha(s) ds + \sum_k \sqrt{\alpha_k} \int_0^t \mathbf{M}_k(s)u_{\alpha-\varepsilon_k}(s) ds, & |\alpha| > 1. \end{aligned} \quad (4.15)$$

As above, denote by $\Phi = (\Phi_{s,t}, t \geq s \geq 0)$, the semigroup generated by the operator $\mathbf{A}(t)$. It follows by induction on $|\alpha|$ that

$$\begin{aligned} u_{(0)}(t) &= \Phi_{t,0}u^0(x) + \int_0^t \Phi_{t,s}f(s) ds, & |\alpha| = 0; \\ u_{\varepsilon_k}(t) &= \int_0^t \Phi_{t,s} \mathbf{M}_k(s)u_{(0)}(s) ds, & |\alpha| = 1; \\ u_\alpha(t) &= \frac{1}{\sqrt{\alpha!}} \int_0^t \int_0^{s_n} \cdots \int_0^{s_2} \Phi_{t,s_n} \mathbf{M}_{i_n} \Phi_{s_n,s_{n-1}} \mathbf{M}_{i_{n-1}} \\ &\quad \cdots \Phi_{s_2,s_1} \mathbf{M}_{i_1} u_{(0)} ds_1 \cdots ds_n, \\ &|\alpha| = n > 1, \quad K_\alpha = \{i_1, \dots, i_n\}. \end{aligned} \quad (4.16)$$

By assumptions (4.8) and (4.9),

$$\|u_\alpha(t)\|_{\mathcal{V}(T)}^2 \leq \frac{(|\alpha|!)^2}{\alpha!} \left(\|u^0\|_H^2 + \|f\|_{\mathcal{V}'(T)}^2 \right) C_A \prod_{k \geq 1} C_k^{2\alpha_k}. \quad (4.17)$$

By multinomial formula,

$$\sum_{n \geq 1} \sum_{|\alpha|=n} \frac{n!}{\alpha!} \prod_{k \geq 1} ((q_k^\circ)^{r^\circ} C_k)^{2\alpha_k} = \sum_{n \geq 1} \left(\sum_{k \geq 1} (q_k^\circ)^{2r^\circ} C_k^2 \right)^n. \quad (4.18)$$

Thus, if we choose Q^* and r^* so that

$$\sum_{k \geq 1} \frac{C_k^2}{(q_k^*)^{2r^*}} \leq \frac{1}{2}, \quad (4.19)$$

then

$$\sum_{\alpha \in \mathcal{J}} \frac{\|u_\alpha(t)\|_{\mathcal{V}(T)}^2 (q^*)^{-2r^*|\alpha|}}{|\alpha|!} \leq 2C_A (\|u^0\|_H^2 + \|f\|_{\mathcal{V}'(T)}^2). \quad (4.20)$$

Then (3.3) and (4.20) imply (4.12). Proposition 4.1 is proved.

Note that there are many ways to choose Q^* and r^* satisfying (4.19). For example, $q_k^* = 2k(1 + C_k)$, $r^* = 2$ or $q_k^* = (2k(1 + C_k^2))^{1/2}$, $r^* = -1$.

Step 2.

Proposition 4.2. *Given $v \in H$, $F \in \mathcal{V}'(T)$, and $\gamma \in \mathcal{J}$, denote by $u(t; v, F, \gamma)$ the solution of (4.2) with $u^0 = v\xi_\gamma$, $f = F\xi_\gamma$. Then there exist a weight sequence Q° and a number $r^\circ > 0$ such that*

$$\|u(\cdot; v, F, \gamma)\|_{Q^*, -r^*; \mathcal{V}(T)}^2 \leq \frac{2C_A}{\gamma!} (\|v\|_H^2 + \|F\|_{\mathcal{V}'(T)}^2). \quad (4.21)$$

P r o o f. It follows from (4.15) that $u_\alpha(t; v, F, \gamma) = 0$ if $|\alpha| < |\gamma|$ and

$$\frac{u_{\alpha+\gamma}(t; v, F, \gamma)}{\sqrt{(\alpha+\gamma)!}} = \frac{u_\alpha(t; v/\sqrt{\gamma!}, F/\sqrt{\gamma!}, (0))}{\sqrt{\alpha!}} = \frac{u_\alpha(t; v, F, (0))}{\sqrt{\alpha!} \gamma!}. \quad (4.22)$$

Take Q^* and r^* from Proposition 4.1 and define

$$q_k^\circ = 2kq_k^*, \quad r^\circ = r^*. \quad (4.23)$$

Then

$$\begin{aligned} \|u(\cdot; v, F, \gamma)\|_{Q^\circ, -r^\circ; \mathcal{V}(T)}^2 &= \sum_{\alpha \in \mathcal{J}} \frac{\|u_{\alpha+\gamma}(\cdot; v, F, \gamma)\|_{\mathcal{V}(T)}^2}{(q^\circ)^{2r^\circ(\alpha+\gamma)} |\alpha+\gamma|!} \\ &= \frac{1}{\gamma!} \sum_{\alpha \in \mathcal{J}} \frac{\|u_\alpha(\cdot; v, F, (0))\|_{\mathcal{V}(T)}^2 (\alpha+\gamma)!}{(q^*)^{2r^\circ(\alpha+\gamma)} (2\mathbf{N})^{2(\alpha+\gamma)} \alpha! |\alpha+\gamma|!} \leq \frac{1}{\gamma!} \sum_{\alpha} \frac{\|u_\alpha(\cdot; v, F, (0))\|_{\mathcal{V}(T)}^2}{(q^*)^{2r^*\alpha} (2\mathbf{N})^{2\alpha} \alpha!} \\ &\leq \frac{1}{\gamma!} \sum_{\alpha \in \mathcal{J}} \frac{\|u_\alpha(\cdot; v, F, (0))\|_{\mathcal{V}(T)}^2}{(q^*)^{2r^*\alpha} |\alpha|!} \leq \frac{2C_A}{\gamma!} (\|v\|_H^2 + \|F\|_{\mathcal{V}'(T)}^2), \end{aligned}$$

where the first inequality is trivial, the second follows from $|\alpha|! \leq (2\mathbf{N})^{2\alpha} \alpha!$ (see [2]) and the third from Proposition 4.1. Proposition 4.2 is proved.

We can now complete the proof of the theorem. If $u^0 = \sum_{\alpha \in \mathcal{J}} u_\alpha^0 \xi_\alpha$, $f = \sum_{\alpha \in \mathcal{J}} f_\alpha \xi_\alpha$, then, by linearity,

$$u(t) = \sum_{\gamma \in \mathcal{J}} u(t; u_\gamma^0, f_\gamma, \gamma). \quad (4.24)$$

Therefore, we use the triangle inequality followed by (4.2) and the Cauchy–Schwarz inequality to get

$$\begin{aligned} \|u\|_{Q^\circ, -r^\circ; \mathcal{V}(T)} &\leq \sum_{\gamma \in \mathcal{J}} \|u(\cdot; u_\gamma^0, f_\gamma, \gamma)\|_{Q^*, -1; \mathcal{V}(T)} \\ &\leq \sum_{\gamma \in \mathcal{J}} \frac{\sqrt{2C_A}}{\sqrt{\gamma!}} (\|u_\gamma^0\|_H + \|f_\gamma\|_{\mathcal{V}'(T)}) \\ &\leq \sqrt{2C_A} \left(\sum_{\gamma \in \mathcal{J}} \frac{|\gamma|!}{\gamma!} q_k^{-2r\gamma} \right)^{1/2} \cdot 2 \left(\sum_{\gamma \in \mathcal{J}} \frac{q_k^{2r\gamma}}{|\gamma|!} (\|u_\gamma^0\|_H^2 + \|f_\gamma\|_{\mathcal{V}'(T)}^2) \right)^{1/2}. \end{aligned}$$

The result now follows because $\sum_{\gamma \in \mathcal{J}} (|\gamma|!/\gamma!) q_k^{-2r\gamma} = \sum_{n \geq 0} (\sum_{k \geq 1} q_k^{-2r})^n \leq 2$. This completes the proof of Theorem 4.2.

Corollary 4.1 (a generalization of the Krylov–Veretennikov formula from [6]). *Assume that u^0 and f are deterministic and take q_k° from (4.19). Define the sequence $U_n = U_n(t)$, $n \geq 0$, by induction*

$$U_0(t) = u_{(0)}(t), \quad U_{n+1}(t) = \int_0^t \Phi_{t,s} \delta(\mathbf{M}^\circ(s) U_n(s)) ds, \quad n > 0, \quad (4.25)$$

where $\mathbf{M}^\circ = (q_1^\circ \mathbf{M}_1, q_2^\circ \mathbf{M}_2, \dots)$. Then

$$\sum_{|\alpha|=n} (q^\circ)^\alpha u_\alpha(t) \xi_\alpha = U_n(t).$$

P r o o f. By (4.15),

$$(q^\circ)^\alpha u_\alpha(t) = \int_0^t \mathbf{A}(q^\circ)^\alpha u_\alpha(s) ds + \sum_{k \geq 1} \int_0^t q_k \sqrt{\alpha_k} \mathbf{M}_k(q^\circ)^{\alpha - \varepsilon_k} u_{\alpha - \varepsilon_k}(s) ds.$$

Therefore, $(U_n(t))_\alpha = \sum_{k \geq 1} \sqrt{\alpha_k} \int_0^t \Phi_{t-s} \mathbf{M}_k^\circ(U_{n-1}(s))_{\alpha - \varepsilon_k} ds$. By (2.13), $U_n(t) = \int_0^t \Phi_{t,s} \delta(\mathbf{M}^\circ(s) U_{n-1}(s)) ds$ and the result follows.

R e m a r k 4.3. The main goal of Theorem 4.2 is universality: to cover the largest possible class of equations. It is therefore inevitable, and natural, that, for many particular equations, there are much better regularity results than (4.11).

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