

TOWARDS THE THEORY OF SOLUTIONS OF THE FLOW EQUATIONS OF INCOMPRESSIBLE LIQUID

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The Euler system of equations

$$\vec{U}_t + (\vec{U} \cdot \vec{\nabla})\vec{U} + \vec{\nabla}P = 0, \quad (\vec{\nabla} \cdot \vec{U}) = 0, \quad (1)$$

where $\vec{U} = [U(\vec{x}, t), V(\vec{x}, t), W(\vec{x}, t)]$ and $P = P(\vec{x}, t)$ are the velocity and, respectively, the pressure of liquid, after change of the variables $x = x + \alpha t$, $y = y + \beta t$, $z = z + \gamma t$ and the functions $U(x, y, z, t) = \alpha + U(x - \alpha t, y - \beta t, z - \gamma t)$, $V(x, y, z, t) = \beta + V(x - \alpha t, y - \beta t, z - \gamma t)$, $W(x, y, z, t) = \gamma + W(x - \alpha t, y - \beta t, z - \gamma t)$, $P(x, y, z, t) = P_0 + P(x - \alpha t, y - \beta t, z - \gamma t)$, takes the form

$$\begin{aligned} P_x + UU_x + VU_y + WU_z &= 0, \quad P_y + UV_x + VV_y + WV_z = 0, \\ P_z &= UW_x + VW_y + WW_z = 0, \quad U_x + V_y + W_z = 0. \end{aligned} \quad (2)$$

To integrate the system (2) we transform it into the system of equations (in new variables)

$$\begin{aligned} VW P_x + UW P_y + UV P_z - V^2(WU)_y - W^2(VU)_z - U^2(WV)_x &= 0, \\ (UU_x)_y + (VU_y)_y + (WU_z)_y - (UV_x)_x - (VV_x)_x - (WV_z)_x &= 0, \\ (UU_x)_z + (VU_y)_z + (WU_z)_z - (UW_x)_x - (VW_y)_x - (W_z W)_x &= 0, \\ (UV_x)_z + (VV_y)_z + (WV_z)_z - (UW_x)_y - (VW_y)_y - (WW_z)_y &= 0, \end{aligned} \quad (3)$$

using the relations $UU_x = P_x - VU_y - WU_z$, $VV_y = (P_y - UV_x - WV_z)$, $WW_z = (P_z - UW_x - VW_y)$, and conditions of their compatibility.

As a result we find that the simplest non singular solution (1-soliton) of the system (3) has the form

$$W(\vec{x}, t) = c + \frac{e^{\alpha(x-at) + \beta(y-bt) + \delta(z-ct)}}{1 + e^{\alpha(x-at) + \beta(y-bt) + \delta(z-ct)}},$$

$$V(\vec{x}, t) = b + \frac{e^{\alpha(x-at) + \beta(y-bt) + \delta(z-ct)}}{1 + e^{\alpha(x-at) + \beta(y-bt) + \delta(z-ct)}},$$

$$U(\vec{x}, t) = a - \frac{(\beta + \delta) e^{\alpha(x-at) + \beta(y-bt) + \delta(z-ct)}}{\alpha (1 + e^{\alpha(x-at) + \beta(y-bt) + \delta(z-ct)})}$$

where (a, b, c) and α, β, δ are the parameters.

More complicate solution (2-soliton) of the system (3) is

$$W(\vec{x}, t) = c$$

$$+ \frac{e^{-x+at-(x-at)\beta+\beta(y-bt)+z-ct} + e^{-x+at-(x-at)\beta+\beta(y-bt)+2z-2ct-y+bt}}{(1 + e^{-x+at-(x-at)\beta+\beta(y-bt)+z-ct})(1 + e^{-y+bt+z-ct})},$$

$$V(\vec{x}, t) = b$$

$$+ \frac{e^{-x+at-(x-at)\beta+\beta(y-bt)+z-ct} + e^{-x+at-(x-at)\beta+\beta(y-bt)+2z-2ct-y+bt}}{(1 + e^{-x+at-(x-at)\beta+\beta(y-bt)+z-ct})(1 + e^{-y+bt+z-ct})},$$

$$U(\vec{x}, t) = a$$

$$+ \frac{e^{-x+at-(x-at)\beta+\beta(y-bt)+z-ct} + e^{-x+at-(x-at)\beta+\beta(y-bt)+2z-2ct-y+bt}}{(1 + e^{-x+at-(x-at)\beta+\beta(y-bt)+z-ct})(1 + e^{-y+bt+z-ct})}.$$

In given examples of the flows the condition $P(\vec{x}, t) = \text{const}$ is satisfied.

As the flows with condition $P(x, y, z, t) \neq \text{const}$ may be considered following example

$$W(x, y, z, t) = c - 1/2 \sin(x - at) - \sin(y - bt),$$

$$V(x, y, z, t) = b - 1/2 \cos(x - at) + \cos(z - ct),$$

$$U(x, y, z, t) = a + \cos(y - bt) - \sin(z - ct),$$

$$P(x, y, z, t) = P_0 - 1/4 \cos(-y + bt + x - at)$$

$$+ 1/4 \cos(y - bt + x - at) + 1/4 \cos(x - at - z + ct)$$

$$+ 1/4 \cos(x - at + z - ct) + 1/2 \sin(y - bt + z - ct) - 1/2 \sin(y - bt - z + ct).$$

More general consideration of the system (3) allow as to formulate the

Theorem 1. *Non singular and non stationary solution of the system (1) has the form*

$$U(x, y, z, t) = a + A \sin(z - ct) + C \cos(y - bt),$$

$$V(x, y, z, t) = b + B \sin(x - at) + A \cos(z - ct),$$

$$W(x, y, z, t) = c + C \sin(y - bt) + B \cos(x - at),$$

$$\begin{aligned} P(x, y, z, t) = & 1/2 CB \sin(-y + bt + x - at) - 1/2 CB \sin(y - bt + x - at) \\ & - 1/2 BA \sin(-z + ct + x - at) - 1/2 BA \sin(z - ct + x - at) \\ & + 1/2 AC \sin(-z + ct + y - bt) - 1/2 AC \sin(z - ct + y - bt) + F_2(t), \end{aligned} \quad (4)$$

which is a generalization of the famous stationary ABC-flow.

Theorem 2. *Non singular and non stationary solution of the system (3) has the form*

$$\begin{aligned} U(x, y, z, t) = & a + 1/2 C_1 \sin(y - bt) + 1/2 E_1 \cos(y - bt) + 1/2 F_1 \cos(z - ct) \\ & + 1/2 H_1 \sin(z - ct), \end{aligned}$$

$$\begin{aligned} V(x, y, z, t) = & b + 1/2 F_1 \sin(z - ct) - 1/2 H_1 \cos(z - ct) - A_1 \sin(x - at) \\ & + B_3 \cos(x - at), \end{aligned}$$

$$\begin{aligned} W(x, y, z, t) = & c + A_3 \cos(x - at) + B_3 \sin(x - at) \\ & + 1/2 C_1 \cos(y - bt) - 1/2 E_1 \sin(y - bt), \end{aligned}$$

Remark. To integrate the Navier-Stokes system of equations

$$\vec{U}_t + (\vec{U} \cdot \vec{\nabla})\vec{U} + \vec{\nabla}P = \mu\Delta\vec{U}, \quad (\vec{\nabla} \cdot \vec{U}) = 0, \quad (5)$$

the approach described above can be applied, where the condition

$$\begin{aligned} VW P_x + UW P_y + UV P_z - V^2(WU)_y - W^2(VU)_z - U^2(WV)_x + \\ + \mu(VW\Delta U + UW\Delta V + UV\Delta W) = 0, \end{aligned}$$

is used, which is consequence of the condition of incompressibility of liquid $(\vec{\nabla} \cdot \vec{U}) = 0$.

References

1. *Dryuma V.* On solving equations of flows of incompressible liquids // Abstr. Int. Conf. "Mathematics and Information Technologies: Research and Education (MITRE-2016)", Chisinau, June 23–26, 2016. P. 28–29.