

# Stochastic Delay Differential Equations

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# Outline

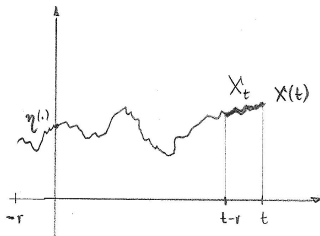
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# Stochastic Delay Differential Equations (SDDE)

$$dX(t) = \mu(t, X_t)dt + \sigma(t, X_t)dW(t), \quad t \geq 0. \quad (1)$$

- $X_t = (X(t+s), s \in [-r, 0])$ : **segment** of  $X(\cdot)$  at time  $t$ ,
- $r \in [0, \infty]$ : **length of the memory**,



- $\mu(t, x), \sigma(t, x) : [0, \infty) \times C([-r, 0]) \rightarrow \mathbb{R}^1$  **drift- and diffusion coefficients**
- $W = (W(t), t \geq 0)$ : standard Wiener process,
- $X_0 = (\eta(s), s \in [-r, 0])$ : **initial process**.

# Existence and Uniqueness of Solutions

(1) and (1') mean:

$$\begin{aligned} X(t) &= \eta(0) + \int_0^t \mu(s, X_s) ds + \int_0^t \sigma(s, X_s) dW(s), \quad t \geq 0, \\ X(s) &= \eta(s), \quad s \in [-r, 0]. \end{aligned} \tag{2}$$

## Theorem (Mohammed (1984), Mao (2007))

*Assume*

- *some local Lipschitz conditions on  $\mu(t, x)$  and  $\sigma(t, x)$ ,*
- *some linear growth conditions on  $\mu(t, x)$  and  $\sigma(t, x)$ ,*
- *integrability of the initial process  $\eta(\cdot)$ .*

*Then there exists a uniquely determined solution*

$$(X(t), t \in [-r, \infty))$$

*of (2).*

*diffusion-type processes*

# Stochastic Ordinary Differential Equations (SODE)

$$dX(t) = \mu(X(t))dt + \sigma(X(t))dW(t), \quad t \geq 0. \quad (3a)$$

$$X(0) = \eta \quad \text{initial value.} \quad (3b)$$

Available tools:

- $T_t f(x) := \mathbb{E}_x f(X_t)$  defines a semigroup  $(T_t, t \geq 0)$  with infinitesimal operator  $A = \frac{\sigma^2(x)}{2} \frac{d^2}{dx^2} + \mu(x) \frac{d}{dx}$ ,
- Feynman–Kac–formula,
- harmonic functions  $h$ :  $Ah = 0$ , Potential theory of  $A$
- $(h(X(t)), t \geq 0)$  continuous local martingales,
- Itô–formula,
- Connections to parabolic and elliptic differential equations (Kolmogorov's differential equations).

Well developed:

Numerics and statistics of SODE

Kloeden, Platen (1999); Gilsing, Shadlow (2007); Kutoyants (2004)



# Examples

## 1 Affine SODE, Ornstein-Uhlenbeck-Process

$$dX(t) = aX(t)dt + \sigma dW(t), \quad X(0) = X_0,$$

$$X(t) = X_0 \exp(at) + \int_0^t \exp[a(t-s)] dW(s), \quad t \geq 0.$$

## 2 Linear SODE, Geometric Brownian Motion

$$dX(t) = \mu X(t)dt + \sigma X(t)dW(t), \quad X(0) = X_0,$$

$$X(t) = X_0 \exp \left[ \sigma W(t) + \left( \mu - \frac{\sigma^2}{2} \right) t \right], \quad t \geq 0.$$

## 3 Stochastic logistic growth model

$$dX(t) = bX(t)(K - X(t))dt + \sigma X(t)dW(t),$$

$$X(0) = X_0 \in (0, K), \quad K > 0,$$

$$X(t) = \frac{X_0 \exp \left[ \left( bK - \frac{\sigma^2}{2} \right) t + \sigma W(t) \right]}{1 + bX_0 \int_0^t \exp \left[ \left( bK - \frac{\sigma^2}{2} \right) s + \sigma W(s) \right] ds}.$$

This great variety of mathematical tools to treat Stochastic Ordinary Differential Equations is paid by the assumption that the drift  $\mu(X(t))$  and the diffusion  $\sigma(X(t))$  depend on the present state  $X(t)$  of  $X$  only, i.e. that  $X$  has no memory, with other words,

$X$  is a Markov process.

But: Many real phenomena include a memory or simply a time delay.



**Financial industry:** time between

- a claim occurs and the moment of settlement by an insurance company (settling delay),
- time lag for getting information.

**Economics:** time between

- taking a decision and occurrence of the feedback,
- time to build, to transport, to store.

**Biology and Population dynamics:**

- time to maturity,
- time to educate,
- incubation period.

**Ecology:** time between

- causing and occurring of damages, e.g. air pollution and changing of climate.

**Delay and Memory are everywhere!**





Instead of choosing a Markov model one can try to accept the memory. Then several questions arise:

- 1 How to model memories, and how to treat them mathematically?
- 2 Are there new effects caused by a memory?
- 3 Are there classes of memories, which can be treated mathematically in a reasonable way?

# Two Examples of differential equations with time delay

## Growth Models

### T. Malthus (1798)

$$N(t) = N(0) \exp[at], \quad \frac{dN(t)}{N(t)} = a dt.$$

$a$  ... Malthusian coefficient of linear growth, **growth rate**.

### P. F. Verhulst (1838)

$$\dot{N}(t) = a \left( 1 - \frac{N(t)}{K} \right) N(t),$$
$$\frac{dN(t)}{N(t)} = a \left( 1 - \frac{N(t)}{K} \right) dt.$$

$K$  ... capacity of the habitat, determined by the food and the area of the habitat.

$$N(t) = \frac{N(0) K e^{at}}{K + N(0)(e^{at} - 1)}, \quad t \geq 0, \quad N(0) \in (0, K).$$

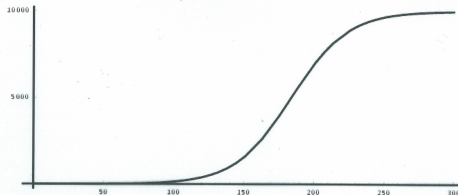
## Logistische Gleichung

$$\dot{N}(t) = rN(t) \left(1 - \frac{1}{K}N(t)\right)$$

- $N$  Populationsgröße der Fliegen
- $r$  Wachstumsrate
- $K$  Parameter für bereitgestellte Nahrungsmenge



*Lucilia cuprina*



Quelle: A.J. Nicholson, 1954

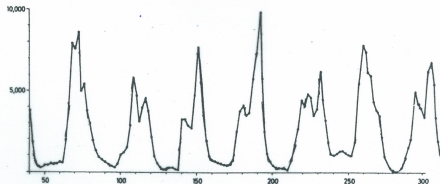
## Australische Schmeißfliege (1)

$$\dot{N}(t) = rN(t) \left(1 - \frac{1}{K}N(t)\right)$$

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- $r$  Wachstumsrate
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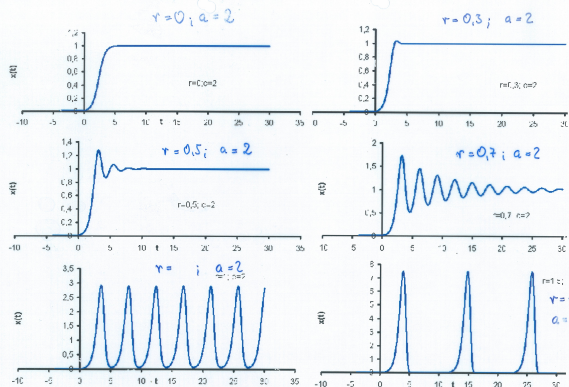
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Fig. from Riedle (2005)

## G. E. Hutchinson (1948)

$$\frac{dN(t)}{N(t)} = a \left[ 1 - \frac{N(t-r)}{K} \right] dt.$$

$r$ ...average age of sexually mature females.



Time delay may generate oscillations, Fig. from Riedle (2005)

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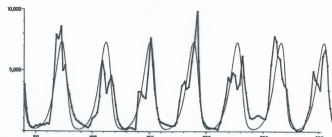
### Australische Schmeißfliege (2)

$$\dot{N}(t) = rN(t) \left( 1 - \frac{1}{K}N(t-\alpha) \right)$$

- $N$  Populationsgröße der Fliegen
- $r$  Wachstumsrate
- $K$  Parameter für bereitgestellte Nahrungsmenge
- $\alpha$  Entwicklungszeit von Larve zur Fliege (ca. 11 Tage)



Lucilia cuprina



Quelle: A.J. Nicholson, 1954

Time delay may generate oscillations, Fig. from Riedle (2005)

More realistic models take into account, that the birth rate underlies random fluctuations.

Thus leads e.g. to the randomized growth rate

$$a\left[1 - \frac{N(t-r)}{K}\right] + \sigma \dot{W}(t).$$

Therefore, we get

$$dN(t) = a\left[1 - \frac{N(t-r)}{K}\right] N(t)dt + \sigma N(t)dW(t).$$

If the age of sexually mature females is considered to be distributed with probability distribution  $\beta(\cdot)$  say, then we obtain

$$dN(t) = a\left[1 - \frac{1}{K} \int_0^r N(t-s)\beta(ds)\right] N(t)dt + \sigma N(t)dW(t).$$

Stable point:  $N(t) \equiv K$

Introducing  $n(t) = N(t) - K$  and neglecting terms of higher order we get

$$dn(t) = a(K + n(t)) \left[ -K^{-1} \int_0^r n(t-s) \beta(ds) \right] dt + \sigma K dW(t),$$

$$dn(t) = -a \int_0^r n(t-s) \beta(ds) dt + \sigma K dW(t).$$

This is an example of an

## Affine SDDE



# Discontinuous dependence of the solution from the initial process

## Geometric Brownian Motion

$$\begin{aligned}dX(t) &= X(t)dW(t), \quad t \geq 0, \\ X(0) &= \eta \in \mathbb{R},\end{aligned}$$

$$X^\eta(t, \omega) = \eta \exp \left[ W(t, \omega) - \frac{t}{2} \right], \quad t \geq 0.$$

The mapping

$$\eta \mapsto X^\eta(t, \omega), \quad \eta \in \mathbb{R}^1$$

is for every fixed pair  $(t, \omega)$  ( $t > 0, \omega \in \Omega$ ) a continuous function of the initial value  $\eta$ .

## Delay in the diffusion: $r > 0$

$$\begin{aligned}dX(t) &= X(t-r)dW(t), & t \geq 0, \\X(s) &= \eta(s), & s \in [-r, 0],\end{aligned}$$

$\eta \in \mathcal{C}([-r, 0])$ , continuous function.

$$X^\eta(t) = \int_0^t \eta(s-r)dW(s), \quad t \in [0, r].$$

The mapping  $\eta \longrightarrow X^\eta(t, \omega)$  is discontinuous in the following sense:

Choose any  $\delta > 0$  and define

$$\eta_k(s) = \delta \sin\left(2k\pi \frac{s}{r}\right), \quad s \in [-r, 0],$$

$$X_k(\omega) = X^{\eta_k}(r, \omega) = \int_0^r \eta_k(s-r) dW(s).$$

Then,  $(X_k, k \geq 1)$  are centered, mutually independent Gaussian random variables having identical positive variance  $\frac{\delta^2}{2}$

$$\left( \mathbb{E} X_k X_l = \mathbb{E} \int_0^r \eta_k(s-r) dW_s \int_0^r \eta_l(s-r) dW_s = \int_{-r}^0 \eta_k(s) \eta_l(s) ds = 0, \quad k \neq l \right).$$

Thus for every  $M > 0$

$$C_M := \mathbb{IP}(|X_k| > M) > 0, \quad k \geq 1,$$

and Borel–Cantelli lemma yields

$$\mathbb{IP}(\sup_k |X_k| > M) = 1 \text{ for all } M > 0, \quad \text{i.e.,}$$

$$\sup_{k \geq 1} |X_k(\omega)| = \infty \quad \mathbb{IP}\text{-a. s.}$$

(See Mohammed (1998).)

# Affine SDDE

$$dX(t) = \int_{-r}^0 X(t+s)a(ds)dt + dW(t), \quad t \geq 0,$$

$$X(u) = \eta(u), u \in [-r, 0],$$

$a(\cdot)$ ... finite signed measure.

Autoregressive Schema with continuous time

Examples: 
$$dX(t) = \sum_{k=0}^N a_k X(t-r_k)dt + dW(t),$$

$$dX(t) = \int_{-r}^0 X(t+s)\alpha(s)dsdt + dW(t).$$

Example (Ornstein-Uhlenbeck-case:  $r = 0$  :)

$$dX(t) = aX(t)dt + dW(t),$$

$$(a(ds) = a\mathbf{1}_{\{0\}}(ds))$$

$$X(t) = \eta e^{at} + \int_0^t e^{a(t-s)} dW(s).$$

# The solution of the affine SDDE

$$\begin{aligned}dX(t) &= \int_{-r}^0 X(t+s)a(ds)dt + dW(t), \quad t \geq 0, \\X(t) &= \eta(t), \quad t \in [-r, 0].\end{aligned}$$

admits the representation

$$X(t) = \eta(0)x_0(t) + \int_0^t x_0(t-s)dW(s) + \int_{-r}^0 \int_u^0 \eta(s)x_0(t+u-s)ds a(du),$$

where  $x_0(\cdot)$  denotes the **fundamental solution**:

$$\begin{aligned}\dot{x}_0(t) &= \int_{-r}^0 x_0(t+s)a(ds), \\x_0(s) &= \mathbf{1}_{\{0\}}(s), \quad s \in [-r, 0].\end{aligned}$$

## Example (Ornstein-Uhlenbeck-case:)

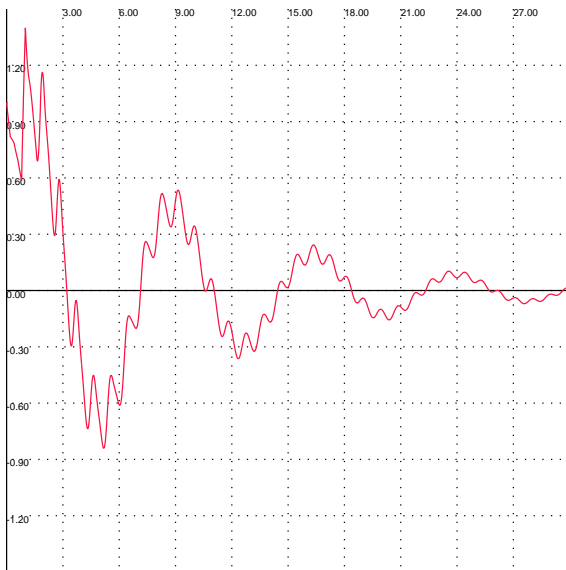
$$\begin{aligned}a(ds) &= a\delta_{\{0\}}(ds) \quad , \quad \dot{x}_0(t) = ax_0(t), \\x_0(t) &= \exp[at].\end{aligned}$$

In general, the fundamental solution  $x_0(\cdot)$  of

$$\dot{x}_0(t) = \int_{-r}^0 x_0(t+s) a(ds), \quad (4a)$$

$$x_0(s) = \mathbf{1}_{\{0\}}(s), \quad s \in [-r, 0], \quad (4b)$$

- has no explicit expression,
- may be oscillating instead of being monotone.



$$a(du) = (-\delta_0 + 0.7\delta_{-0.2} - 0.3\delta_{-0.4} - 0.2\delta_{-0.6} + 5.5\delta_{-0.8} - 5.4\delta_{-1})(du)$$

# Laplace transform of $x_0(t)$

$$\hat{x}_0(\lambda) = \int_0^{\infty} e^{-\lambda s} x_0(s) ds, \quad \operatorname{Re} \lambda > \|a\|,$$

$$\hat{x}_0(\lambda) = \left[ \lambda - \int_{-r}^0 e^{\lambda s} a(ds) \right]^{-1}, \quad \operatorname{Re} \lambda > \|a\|.$$

The denominator of the Laplace transform  $\hat{x}_0(\lambda)$

$$h(\lambda) = \lambda - \int_{-r}^0 e^{\lambda s} a(ds), \quad \lambda \in \mathbb{C},$$

is called the **characteristic function** of the deterministic differential equation (4).





# Properties:

- The characteristic function  $h(\lambda) = \lambda - \int_{-r}^0 e^{\lambda s} a(ds)$  is holomorphic.

Define  $\Lambda := \{\lambda \mid h(\lambda) = 0\}$ , the set of zeros of  $h(\cdot)$ .

- $\Lambda$  is countable infinite, beside of  $a(ds) = a \cdot \delta_{\{0\}}(ds)$ ,
- $\Lambda$  has no finite accumulation point,
- the multiplicity  $m_\lambda$  of every  $\lambda \in \Lambda$  is finite,
- $\#\{\lambda \in \Lambda \mid \operatorname{Re} \lambda \geq c\}$  is finite for every  $c \in \mathbb{R}^1$ .

Define the top coefficient

$$v_0 := v_0(a) = \max\{\operatorname{Re} \lambda \mid \lambda \in \Lambda\} < \infty$$

and further

$$v_{i+1} := \max\{\operatorname{Re} \lambda \mid \lambda, \operatorname{Re} \lambda < v_i\}, i \geq 0.$$

## Series expansion of $x_0(\cdot)$ :

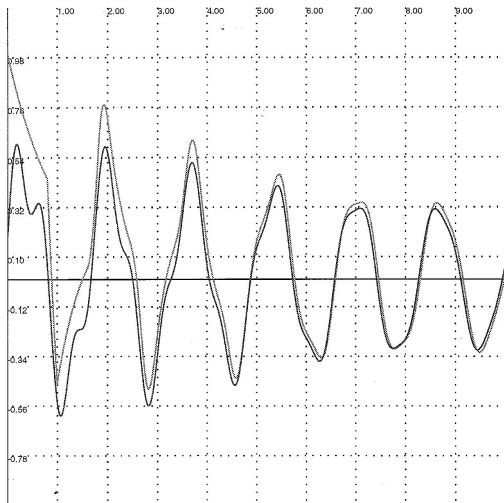
$$\begin{aligned}
 x_0(t) = & \sum_{i: v_i \geq c} \left( \sum_{\substack{\lambda \in \Lambda \\ \lambda = v_i}} p_\lambda(t) e^{v_i t} \right. \\
 & \left. + \sum_{\substack{\lambda \in \Lambda \\ \operatorname{Re} \lambda = v_i \\ \operatorname{Im} \lambda > 0}} \{q_\lambda(t) \cos(t \cdot \operatorname{Im} \lambda) + r_\lambda(t) \sin(t \cdot \operatorname{Im} \lambda)\} e^{v_i t} \right) + o(e^{ct})
 \end{aligned}$$

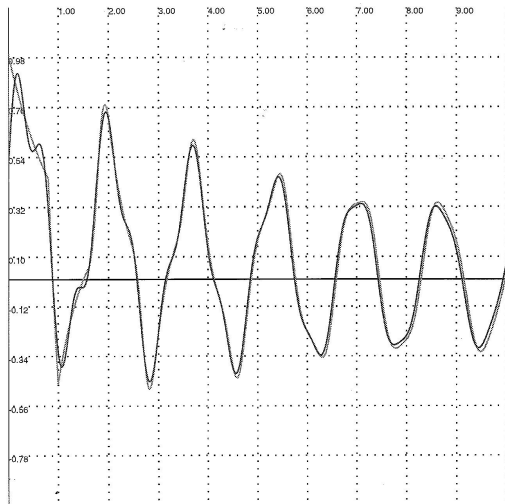
where

- $c < v_0$ ,  $p_\lambda(t)$  are real polynomials in  $t$  with degree  $m_\lambda - 1$ ,
- $q_\lambda(t), r_\lambda(t)$  are real polynomials in  $t$  with degree  $\leq m_\lambda - 1$  (and at least one of them  $= m_\lambda - 1$ ).

Example ( $a(\cdot) = a\delta_0(\cdot)$ , O-U-case)

$$\begin{aligned}
 h(\lambda) &= \lambda - a, \quad \Lambda = \{a\}, \\
 x_0(t) &= e^{at}.
 \end{aligned}$$





# Stationary Solution

## Proposition

*The affine SDDE*

$$dX(t) = \int_{-r}^0 X(t+s)a(ds)dt + dW(t)$$

*admits a stationary solution  $X$  if and only if*

$$v_0 = v_0(a) < 0.$$

*This is equivalent to*

$$\int_0^\infty x_0^2(t)dt < \infty.$$

*Then,*

$$X(t) = \int_{-\infty}^t x_0(t-s)dW(s).$$

In this case,  $X$  is Gaussian, with zero mean and covariance function  $K$  given by

$$K(t) = K(-t) = \int_0^{\infty} x_0(s)x_0(s+t)ds, \quad t \geq 0.$$

It has spectral density  $f$  with

$$f(\lambda) = |h(i\lambda)|^{-2} = \left| i\lambda - \int_{-r}^0 e^{i\lambda s} a(ds) \right|^{-2}, \quad \lambda \in \mathbb{R}^1.$$

The covariance function  $K$  satisfies the analogue of the Yule–Walker equation

$$\dot{K}(t) = \int_{-r}^0 K(t+u)a(du), \quad t > 0, \quad \text{and it holds}$$

$$\dot{K}(0+) = -\frac{1}{2}.$$

The covariance function decreases exponentially to zero as  $\exp[v_0 h]$  for  $h \rightarrow \infty$ .

“Short-range dependence”

If  $X = (X(t), t \geq 0)$  is the stationary solution of

$$dX(t) = \int_{-r}^0 X(t+s)a(ds)dt + dW(t),$$

then  $X$  is absolutely regular ( $\beta$ -mixing), i.e.,

$$\beta(\tau) := \mathbb{E} \left[ \sup_{A \in \sigma(X(s), s \geq t+\tau)} |\mathbb{P}(A | \sigma(X(s), s \leq t)) - \mathbb{P}(A)| \right] \leq C e^{-\tau \cdot v},$$

where  $v$  is any real number from  $(0, -v_0)$  and  $C = C(v) > 0$  is a constant, depending only of  $v$ .

In particular,  $X$  is strong mixing ( $\alpha$ -mixing) and ergodic.  
(M. Reiß (2002))

# Statistical Questions

$$dX(t) = \int_{-r}^0 X(t+s)a(ds)dt + dW(t), \quad t \geq 0$$

$$X(u) = \eta(u), \quad u \in [-r, 0].$$

Log-Likelihood process

$$\begin{aligned} \ell_t = \ln L_t &= \int_{-r}^0 \underbrace{\left( \int_0^t X(s+u) dX(s) \right)}_{=V_t^0(u)} a(du) \\ &\quad - \frac{1}{2} \int_{-r}^0 \underbrace{\left( \int_{-r}^0 \int_0^t X(s+u) X(s+v) ds a(du) \right)}_{=I_t^0(u,v)} a(dv) \\ &= \langle V_t^0, a \rangle - \frac{1}{2} \langle I_t^0 a, a \rangle \rightarrow \max! \end{aligned}$$

$I_t^0$  ... Fisher information operator





# The maximum likelihood equation

$$I_t^0 \hat{a}_t(\cdot) = V_t^0(\cdot),$$

i.e.,

$$\int_{-r}^0 \int_0^t X(s+u)X(s+v)ds \hat{a}_t(du) = \int_0^t X(s+u)dX(s).$$

$\hat{a}_t$  is a nonparametric maximum likelihood estimator for the unknown signed measure  $a$ ,

$I_t^0$  is a compact linear operator, thus

the maximum-likelihood-problem is an **ill posed problem**

# Nonparametric cases, ill-posed-problem

(Reiss (2002) PhD-thesis)

Assume  $a(dv)$  has a density  $g(v)$ ,  $v \in [-r, 0]$  belonging to the Sobolev space  $H^s([-r, 0])$  for some  $s > 0$ .

Introduce for  $S > 0$  and  $\delta > 0$

$M(s, S, \delta) :=$

$\{g \in H^s([-r, 0]) \mid \|g\|_s \leq S, v_0(g) \leq -\delta\}$

**Theorem:** For  $s > 0, S > 0, \delta > 0$  such that  $M(s, S, \delta)$  has nonempty interior in  $H^s([-r, 0])$ , the following lower bound holds for  $T \rightarrow \infty$

$$\inf_{G_T} \sup_{g \in M(s, S, \delta)} E_g \left[ \|G_T - g\|_{L^2}^2 \right]^{\frac{1}{2}} \gtrsim T^{-\frac{s}{2s+3}}$$

where the infimum is taken over all  $\mathcal{F}_T^X$ -measurable estimators  $G_T$ .

An optimal estimator  $\hat{g}_T$  is constructed by Galerkins projection method.

Note: This rate is different from those for i.i.d. case and signal detection problem:  $T^{-\frac{s}{2s+1}}$ .

# Discrete measure $a(\cdot)$

$$dX(t) = \sum_{i=0}^m \vartheta_i X(t - r_i) dt + dW(t), \quad t \geq 0,$$

$$X(s) = \eta(s), \quad s \in [-r, 0],$$

$$0 = r_0 < r_1 < \dots < r_m =: r.$$

$$\ell_t(\vartheta) = \vartheta^* V_t^0 - \frac{1}{2} \vartheta^* I_t^0 \vartheta \quad \text{with}$$

$$V_t^0 = \left( \int_0^t X(s - r_i) dX(s), i = 0, \dots, m \right)^*,$$

$$I_t^0 = \left( \int_0^t X(s - r_i) X(s - r_j) ds, i, j = 0, \dots, m \right).$$

## Maximum-Likelihood-estimator

$$\hat{\vartheta}_T = (I_T^0)^{-1} V_T^0 = \vartheta + (I_T^0)^{-1} V_T^W \quad \text{with}$$

$$V_T^W = \left( \int_0^t X(s - r_i) dW(s), i = 0, \dots, m \right)^*.$$

## Study case $N = 1$ :

Typical properties of the estimator  $\hat{\vartheta}_t$  for  $T \rightarrow \infty$  can be studied at  $N = 1$ :

$$\hat{\vartheta}_T = (I_T^0)^{-1} V_T^0 = \begin{pmatrix} \int_0^T X^2(t) dt & \int_0^T X(t)X(t-1) dt \\ \bullet & \int_0^T X^2(t-1) dt \end{pmatrix}^{-1} \begin{pmatrix} \int_0^T X(t) dX(t) \\ \int_0^T X(t-1) dX(t) \end{pmatrix},$$

$$\hat{\vartheta}_T - \vartheta = (I_T^0)^{-1} V_T^W = \begin{pmatrix} \int_0^T X^2(t) dt & \int_0^T X(t)X(t-1) dt \\ \bullet & \int_0^T X^2(t-1) dt \end{pmatrix}^{-1} \begin{pmatrix} \int_0^T X(t) dW(t) \\ \int_0^T X(t-1) dW(t) \end{pmatrix}.$$

Asymptotics for  $T \rightarrow \infty$  are determined by  $X(t)$ ,  $x_0(t)$ ,  $\Lambda$ .



- fundamental solution

$$\dot{x}_0(t) = ax_0(t) + bx_0(t-1), \quad x_0(s) = \mathbf{1}_{\{0\}}(s), \quad s \in [-1, 0].$$

- Laplace transform

$$\begin{aligned} \lambda \hat{x}_0(\lambda) &= a\hat{x}_0(\lambda) + b e^{-\lambda} \hat{x}_0(\lambda), \\ \hat{x}_0(\lambda) &= \frac{1}{\lambda - a - b e^{-\lambda}}. \end{aligned}$$

- Characteristic function

$$h(\lambda) = \lambda - a - b e^{-\lambda}, \quad \lambda \in K.$$

- Set of zeros of the characteristic function

$$\Lambda = \{\lambda \in K | h(\lambda) = 0\}.$$

$$x_0(t) = \psi_0(t)e^{v_0 t} + o(e^{\gamma t}), \quad t \rightarrow \infty,$$

where  $\gamma$  is any real number with  $v_1 < \gamma < v_0$ , and

$$\psi_0(t) = \begin{cases} \frac{1}{v_0 - a + 1} & \text{if } v_0 \in \Lambda, m(v_0) = 1, \\ 2t + \frac{2}{3} & \text{if } v_0 \in \Lambda, m(v_0) = 2, \\ A_0 \cos(\xi_0 t) + B_0 \sin(\xi_0 t) & \text{if } v_0 \notin \Lambda \quad (\lambda_0 = v_0 + i\xi_0). \end{cases}$$

In the first case ( $v_0 \in \Lambda, m(v_0) = 1$ ) we get for every  $\gamma < v_1$

$$x_0(t) = \frac{1}{v_0 - a + 1} e^{v_0 t} + \psi_1(t)e^{v_1 t} + O(e^{\gamma t})$$

with

$$\psi_1(t) = \begin{cases} \frac{1}{v_1 - a + 1} & \text{if } v_1 \in \Lambda, \\ A_1 \cos(\xi_1 t) + B_1 \sin(\xi_1 t) & \text{if } v_1 \notin \Lambda. \end{cases}$$

# What can we expect?

Start with  $b = 0$ ,  $a = \vartheta$ .

## Example (Ornstein-Uhlenbeck-case)

$$\begin{aligned} dX(t) &= \vartheta X(t)dt + dW(t), \\ X(0) &= \eta, \quad \text{independent of } W(\cdot). \end{aligned}$$

$$X(t) = \eta e^{\vartheta t} + \int_0^t e^{\vartheta(t-s)} dW(s), \quad t \geq 0.$$

The solution is constructed from  $\eta(\cdot)$ ,  $x_0(t) = e^{\vartheta t}$ ,  $W(t)$

$$\frac{d\mathbb{P}_a^T}{d\mathbb{P}_0^T} = \exp \left[ \eta \int_0^T X(s) dX(s) - \frac{\eta^2}{2} \int_0^T X^2(s) ds \right].$$

In general, for  $T \rightarrow \infty$ , all integrals tend to infinity or behave irregular.

One method to study the asymptotic behaviour consists in localization:  
Fix a  $\vartheta \in \mathbb{R}^1$ , choose a function  $\varphi_T(\vartheta)$  and introduce a new (local)  
parametrization by

$$\vartheta(u) = \vartheta + \varphi_T(\vartheta)u, \quad u \in \mathbb{R}^1.$$

Consider

$$\begin{aligned} \frac{d\mathbb{P}_{\vartheta+\varphi_T(\vartheta)u}^T}{d\mathbb{P}_{\vartheta}^T} &= \frac{d\mathbb{P}_{\vartheta+\varphi_T(\vartheta)u}^T}{d\mathbb{P}_0^T} \bigg/ \frac{d\mathbb{P}_{\vartheta}^T}{d\mathbb{P}_0^T} \\ &= \exp \left[ (\vartheta + \varphi_T(\vartheta)u) V_T^0 - \frac{(\vartheta + \varphi_T(\vartheta)u)^2}{2} I_T^0 \right] \\ &= \exp \left[ \underbrace{\left( \varphi_T(\vartheta) \int_0^T X(s) dW(s) \right)}_{=V_T} u - \underbrace{\left( \varphi_T^2(\vartheta) \int_0^T X^2(s) ds \right)}_{=I_T} \frac{u^2}{2} \right], \end{aligned}$$

and hope the pair  $(V_T, I_T)$  tends to a limit for  $T \rightarrow \infty$ .

From this the limit behaviour of

$$\varphi_T^{-1}(\vartheta)(\hat{\vartheta}_T - \vartheta) = I_T^{-1} V_T \quad \text{for } T \rightarrow \infty$$

immediately follows. (Le Cam; Ibragimov, Khasminski)



$$\log \frac{d\mathbb{P}_\vartheta^T + \varphi_T(\vartheta)u}{d\mathbb{P}_\vartheta^T} = \underbrace{\varphi_T(\vartheta) \int_0^T X(s) dW(s) \cdot u}_{=V_T^W} - \underbrace{\varphi_T^2(\vartheta) \int_0^T X^2(s) ds}_{I_T} \cdot \frac{u^2}{2}$$

1.  $\vartheta < 0$  : Stationary case, LAN

$$\varphi_T = (2|\vartheta|T)^{-\frac{1}{2}}, \quad (V_T^W, I_T) \xrightarrow{d} (Z, 1) \text{ with } Z \sim N(0, 1).$$

2.  $\vartheta = 0$  : LAQ, one cluster point

$$\varphi_T = T^{-1}, \quad (V_T^W, I_T) \xrightarrow{d} \left( \int_0^1 \widetilde{W}(s) d\widetilde{W}(s), \int_0^1 \widetilde{W}^2(s) ds \right).$$

3.  $\vartheta > 0$ : Exploding case, LAMN

$$\varphi_T = (2\vartheta)^{-\frac{1}{2}} \exp(-\vartheta T), \quad (V_T^W, I_T) \xrightarrow{d} (Z \cdot l_\infty^{\frac{1}{2}}, l_\infty),$$

where  $l_\infty \sim \chi^2(1)$ ,  $Z \sim N(0, 1)$ ,  
 $l_\infty, Z$  independent random variables.

## Back to the case $N = 1$ :

$$(V_T^W)^* = \left( \int_0^T X(t) dW(t), \int_0^T X(t-1) dW(t) \right) \varphi_T,$$

$\varphi_T = \varphi_T(\vartheta) \dots$  appropriate  $2 \times 2$ -matrix.

$$I_T = \varphi_T^* \begin{pmatrix} \int_0^T X^2(t) dt & \int_0^T X(t)X(t-1) dt \\ \int_0^T X(t)X(t-1) dt & \int_0^T X^2(t-1) dt \end{pmatrix} \varphi_T.$$

If we show that  $I_T$  for  $T \rightarrow \infty$  tends in probability to some  $2 \times 2$ -matrix  $I_\infty$ , then

the convergence of  $(V_T^W, I_T)$  to  $(V_\infty, I_\infty)$  for some random vector  $V_\infty$  follows from the stable limit theorem for martingales.

## Theorem (Gushchin, Kü (1999, 2001))

For every  $\vartheta = (a, b) \in \mathbb{R}^2$  one can find a matrix function  $\varphi_T(\vartheta)$  such that  $(V_T^W, I_T)$  with

$$V_T^W = \varphi_T^*(\vartheta) \left( \int_0^T X(s) dW(s), \int_0^T X(s-1) dW(s) \right)^* \text{ and}$$

$$I_T = \varphi_T^* \begin{pmatrix} \int_0^T X^2(s) ds & \int_0^T X(s) X(s-1) ds \\ \bullet & \int_0^T X^2(s-1) ds \end{pmatrix} \varphi_T$$

tend for  $T \rightarrow \infty$  to a limit  $(V_\infty, I_\infty)$  at least in distribution or behaves asymptotically periodic.

There are eleven different cases depending on the position of  $v_0(\vartheta)$  and  $v_1(\vartheta)$ .

The limit distribution or cluster points respectively can be explicitly calculated for every  $\vartheta \in \mathbb{R}^2$ .



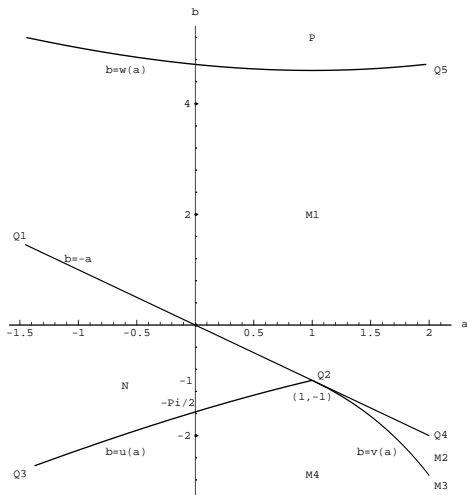


Fig: The eleven cases in the  $(a, b)$ -plane

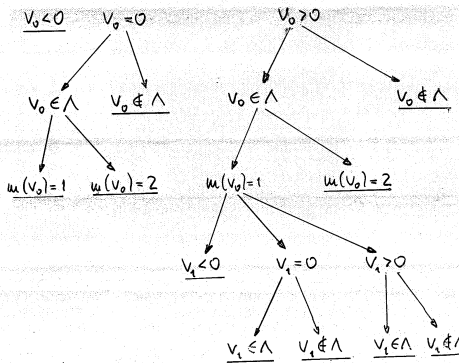
And 2. Prigida

$$\Lambda := \{ \lambda \in \mathbb{C} \mid \lambda - a - be^{-\lambda} = 0 \}$$

$$V_0 := \max \{ \operatorname{Re} \lambda \mid \lambda \in \Lambda \}$$

$$V_1 := \max \{ \operatorname{Re} \lambda \mid \lambda \in \Lambda, \operatorname{Re} \lambda < V_0 \}$$

THE ELEVEN DIFFERENT CASES

OF THE ASYMPT. BEHAVIOUR OF  $G(T)$ 

(A. Gushchin, U.K. 1999)

7 22.



$v_0 < 0$				$a < 1, \ u(a) < b < -a$		N
$v_0 = 0$	$v_0 \in \Lambda$	$m(v_0) = 1$		$a < 1, \ b = -a$		Q1
		$m(v_0) = 2$		$a = 1, \ b = -a$		Q2
	$v_0 \notin \Lambda$			$a < 1, \ b = u(a)$		Q3
$v_0 > 0$	$v_0 \in \Lambda$	$m(v_0) = 1$	$v_1 < 0$		$-a < b < w(a)$	M1
			$v_1 = 0$	$v_1 \in \Lambda$	$a > 1, \ b = -a$	Q4
				$v_1 \notin \Lambda$	$b = w(a)$	Q5
				$v_1 > 0$	$v_1 \in \Lambda$	$a > 1, \ v(a) < b < -a$
			$v_1 \notin \Lambda$		$b > w(a)$	P
		$m(v_0) = 2$		$a > 1, \ b = v(a)$		M3
		$v_0 \notin \Lambda$			$a < 1, \ b < u(a)$ or $a \geq 1, \ b < v(a)$	

Table: The eleven cases in terms of  $(v_0, v_1)$  and  $(a, b)$ .

## Case N: $v_0(\vartheta_0) < 0$

### Proposition

The family  $(\mathbb{P}_\vartheta)$  is locally asymptotically normal at  $\vartheta_0$  (LAN):

$$(V_T^W, I_T) \xrightarrow{d} (V_\infty, I_\infty)$$

with  $\varphi_T(\vartheta_0) = T^{-\frac{1}{2}} \cdot \mathcal{I}_2$ ,

$$V_\infty \sim N(0, I_\infty) \quad \text{and}$$

$$I_\infty = \begin{pmatrix} \int_0^\infty x_0^2(s) ds & \int_0^\infty x_0(s) x_0(s+1) ds \\ \bullet & \int_0^\infty x_0^2(s) ds \end{pmatrix}.$$

Consequently,

$$\lim_{T \rightarrow \infty} \hat{\vartheta}_T = \vartheta_0 \quad \text{in probability } \mathbb{P}_{\vartheta_0},$$

$$T^{\frac{1}{2}}(\hat{\vartheta}_T - \vartheta_0) \xrightarrow{d} N(0, I_\infty^{-1}).$$

Case M1:  $\vartheta_0 = (a, b)^* \in \mathbb{R}^2$  with  $-a < b < w(a)$ .

This means

$$v_0(\vartheta_0) > 0, v_0 \in \Lambda, m(v_0) = 1, v_1(\vartheta_0) < 0, v_1(\vartheta_0) \in \Lambda$$

## Proposition

$(\mathbb{P}_{\vartheta}, \vartheta \in \mathbb{R}_2)$  is LAMN at  $\vartheta_0$ :

$$(V_T^W, I_T) \xrightarrow{d} (V_{\infty}, I_{\infty}), \quad \text{where} \quad (V_{\infty}, I_{\infty}) \stackrel{d}{=} (I_{\infty}^{\frac{1}{2}} Z, I_{\infty})$$

$Z \sim N(0, \mathcal{I}_2)$ , independent of  $I_{\infty}$ ,

$$I_{\infty} = \begin{pmatrix} \frac{U_0^2}{2v_0(v_0 - a + 1)^2} & 0 \\ 0 & \int_0^{\infty} (x_0(t) - e^{v_0} x_0(t-1))^2 dt \end{pmatrix} \quad \text{with}$$

$$U_0 = \eta(0) + b \int_{-1}^0 e^{-v_0(s+1)} \eta(s) ds + \int_0^{\infty} e^{-v_0 s} dW(s)$$



## Case Q1: $\vartheta_0 = (a, b)^*$ with $b = -a$ , $a < 1$

Then,  $v_0 = 0$ ,  $v_0 \in \Lambda$ ,  $m(v_0) = 1$ ,

$$V_\infty = \left( \frac{1}{1-a} \int_0^1 \tilde{W}(t) d\tilde{W}(t), N \right)$$

and

$$I_\infty = \begin{pmatrix} \frac{1}{(1-a)^2} \int_0^1 \tilde{W}^2(t) dt & 0 \\ 0 & \sigma^2 \end{pmatrix}.$$

Here,  $N$  denotes a  $N(0, \sigma^2)$ -distributed r.v. independent of the standard Wiener process  $(\tilde{W}(t))$  and  $\sigma^2 = \int_0^\infty (x_0(t) - x_0(t-1))^2 dt$ .

### Proposition

*The family  $(\mathbb{P}_\vartheta, \vartheta \in \mathbb{R}^2)$ , is locally asymptotically quadratic at  $\vartheta_0 = (a, b)$ :*

$$(V_T^W, I_T) \xrightarrow{d} (V_\infty, I_\infty).$$

# Case P1: $\vartheta_0 = (a, b)^* \in \mathbb{R}^2$ with $b > w(a)$

i.e.,

$$v_0, v_1 > 0, v_0 \in \Lambda, v_1 \notin \Lambda.$$

$$\varphi_T = \varphi_T^{(1)} \varphi_T^{(2)}, \varphi_T^{(1)} = \begin{pmatrix} 1 & 1 \\ 0 & -e^{v_0} \end{pmatrix}, \varphi_T^{(2)} = \begin{pmatrix} e^{-v_0 T} & 0 \\ 0 & e^{-v_1 T} \end{pmatrix}.$$

For all  $u \in [0, \Delta]$  with  $\Delta = \frac{2\pi}{\xi_1}$ , there exists  $I_\infty(u)$  random regular  $2 \times 2$ -matrix:

$$I_\infty(u) = \begin{pmatrix} \frac{U_0^2}{2v_0(v_0 - a + 1)^2} & \frac{U_0}{v_0 - a + 1} \int_0^\infty e^{-(v_0 + v_1)t} U(u - t) dt \\ \frac{U_0}{v_0 - a + 1} \int_0^\infty e^{-(v_0 + v_1)t} U(u - t) dt & \int_0^\infty e^{-2v_1 t} U^2(u - t) dt \end{pmatrix},$$

where

- $U_0 = \int_0^\infty e^{-v_0 s} dW(s)$ , random variable,
- $U(t) = \int_0^\infty \Phi(t - s) e^{-v_1 s} dW(s)$ , random process,
- $\Phi(t) = A \cos(\xi_1 t) + B \sin(\xi_1 t)$ , periodic function.

## Proposition

*The family  $\mathbb{P}^{\vartheta}$ ,  $\vartheta \in \mathbb{R}^2$ , is periodically local asymptotically mixed normal at  $\vartheta_0$ :*

$$(V_{T_n}^W, I_{T_n}) \xrightarrow{d} (V_{\infty}(u), I_{\infty}(u)),$$

*where  $T_n = u + n\Delta$  and  $u \in [0, \Delta]$ .*

# A general parametric model

$$dX(t) = \int_{-r}^0 X(t+s) a_{\vartheta}(ds) dt + dW(t), \quad \vartheta \in \Theta \subseteq \mathbb{R}^k, \quad (5a)$$

$$X(s) = \eta(s), \quad s \in [-r, 0]. \quad (5b)$$

- $M = \{a : a \text{ a finite variation signed measure on } [-r, 0]\}$ ,
- $M_s = \{a \in M : (5) \text{ admits a stationary solution}\}$ .

Assume

$$\mathcal{A} := \{a_{\vartheta}(ds) : \vartheta \in \Theta \subseteq \mathbb{R}^k\} \subseteq M_s, \quad M^k = \underbrace{M \times \cdots \times M}_{k\text{-times}}$$

$$M_{\#}^k = \{(a_1, \dots, a_k) \in M^k : a_1, \dots, a_k \text{ are linearly independent}\}.$$



To study the asymptotic properties of  $\hat{\vartheta}_T$  for  $T \rightarrow \infty$  we turn once again to the framework of asymptotic statistics of LeCam and Ibragimov, Khasminski.

Consider a family  $(a_{\vartheta}, \vartheta \in \Theta)$  with an open  $\Theta \subseteq \mathbb{R}^k$  of bounded signed measures on  $[-r, 0]$  and let  $\mathbb{P}_{\vartheta}^T$  be the measure on  $\mathcal{C}([-r, T])$  generated by the solution  $X^{\vartheta}$  of

$$dX(t) = \int_{-r}^0 X(t+s) a_{\vartheta}(ds) ds dt + dW(t) \text{ with}$$

$$X(s) = \eta(s), \quad s \in [-r, 0].$$

Then one introduces the localization around a fixed  $\vartheta_0 \in \Theta$ :

$$\vartheta = \vartheta_0 + \varphi_T(\vartheta_0)u, \quad u \in \mathbb{R}^k,$$

where  $\varphi_T(\vartheta_0)$  is a  $k \times k$ -matrix, regular, with

$$\varphi_T(\vartheta_0) \rightarrow 0 \quad \text{for } T \rightarrow \infty.$$

(normalizing matrix)



# The likelihood process

$$dX(t) = \int_{-r}^0 X(t+s) a_{\vartheta}(ds) dt + dW(t), \quad t \geq 0, \quad (6a)$$

$$X(t) = \eta(t), \quad t \in [-r, 0], \quad \vartheta \in \Theta \subseteq \mathbb{R}^k. \quad (6b)$$

In the examples above the expression for the log-likelihood function often (but not always) is a quadratic function of the parameters under consideration.

Here we have

$$\begin{aligned} Z_{\vartheta, T}(u) &= \frac{d\mathbb{P}_{\vartheta+\varphi_T u}^T}{d\mathbb{P}_{\vartheta}^T} = \exp \left[ \int_0^T \int_{-r}^0 X(s+v) \left( a_{\vartheta+\varphi_T u}(dv) - a_{\vartheta}(dv) \right) dX(s) - \right. \\ &\quad \left. \frac{1}{2} \int_0^T \left( \int_{-r}^0 \int_{-r}^0 X(s+v) X(s+w) \left[ a_{\vartheta+\varphi_T u}(dv) a_{\vartheta+\varphi_T u}(dw) - a_{\vartheta}(dv) a_{\vartheta}(dw) \right] \right) ds \right]. \end{aligned} \quad (7)$$

The further treatment very depends on the structure of the function  $\vartheta \rightarrow a_{\vartheta}(\cdot)$ .

**Problem:** Under which conditions the family  $(\mathbb{P}_{\vartheta}^T, \vartheta \in \Theta)$  is locally asymptotically normal (LAN)?

$$dX(t) = \int_{-r}^0 X(t+s) a_{\vartheta}(ds) dt + dW(t), \quad t \geq 0,$$

$$X(s) = \eta(s), \quad s \in [-r, 0].$$

Assumptions (A):

- 1)  $\mathcal{A} = (a_{\vartheta}, \vartheta \in \Theta)$ ,  $\Theta$  open, bounded subset of  $\mathbb{R}^k$ ,
- 2)  $\exists C < \infty : \|a_{\vartheta} - a_{\eta}\|_v \leq C \|\vartheta - \eta\|$ ,
- 3)  $a_{\vartheta} \in M_S$ ,  $\vartheta \in \bar{\Theta}$ ,
- 4)  $\vartheta \mapsto \int_{[-r,0]} g(u) a_{\vartheta}(du)$  continuously differentiable in  $\Theta$  with the gradient

$$\int_{[-r,0]} g(u) \dot{a}_{\vartheta}(du),$$

where  $g \in C[-r, 0]$ ,  $\dot{a}_{\vartheta} = (\dot{a}_{\vartheta}^{(1)}, \dot{a}_{\vartheta}^{(2)}, \dots, \dot{a}_{\vartheta}^{(k)})^* \in M_{\#}^k$ ,  $\vartheta \in \Theta$ ,

- 5)  $a_{\vartheta} \neq a_{\eta}$ ,  $\vartheta \in \Theta$ ,  $\eta \in \bar{\Theta}$ ,  $\vartheta \neq \eta$ .

$$\begin{aligned}
X^\vartheta(t) &= x_0(t)\eta(0) + \int_{-r}^0 \int_u^0 \eta(s)x_0(t+u-s)ds a_\vartheta(du) \\
&\quad + \int_0^t x_0(t-s)dW(s), \quad t \geq 0, \\
K(t) &= \int_0^\infty x_0(t+s)x_0(s)ds, \quad t \geq 0.
\end{aligned}$$



## Example

$$dX(t) = \sum_{k=0}^N \vartheta_k X(t - r_k) dt + dW(t),$$

$$a_{\vartheta}(\cdot) = \sum_{i=0}^N \vartheta_i \cdot \delta_{r_i},$$

$$\int g(u) a_{\vartheta}(du) = \sum_{i=0}^N \vartheta_i g(-r_i),$$

$$\dot{a}_{\vartheta}(\cdot) = (\delta_{-r_0}(\cdot), \dots, \delta_{-r_N}(\cdot))^T,$$

satisfies 1) - 5).

## Example

$$\begin{aligned}dX(t) &= b \cdot X(t - \vartheta)dt + dW(t), \\ a_{\vartheta}(du) &= b\delta_{\{-\vartheta\}}(du),\end{aligned}$$

does not satisfy the assumptions, because

$$\vartheta \rightarrow \int_{[-r,0]} g(u)a_{\vartheta}(du) = bg(-\vartheta)$$

is not differentiable for all  $g \in C[-r, 0]$ .

## Theorem (Gushchin, Kü, 2001)

*Under the assumptions (A) for every compact set  $K \subseteq \Theta$  it holds uniformly in  $\vartheta \in K$ :*

$$\sqrt{T}(\vartheta_T - \vartheta) \xrightarrow{d} N(0, \Sigma^{-1}(\vartheta)), \quad T \rightarrow \infty,$$

*where*

$$\begin{aligned} \Sigma(\vartheta) &= (\Sigma_{ij}(\vartheta))_{i,j=1,\dots,k}, \\ \Sigma_{ij}(\vartheta) &= \int \int_{\mathcal{I} \times \mathcal{I}} K_{\vartheta}(u-v) \dot{a}_{\vartheta,i}(du) \dot{a}_{\vartheta,j}(dv). \end{aligned}$$

*All the moments of  $\sqrt{T}(\hat{\vartheta}_T - \vartheta)$  under  $\mathbb{P}_T^{\vartheta}$  tend as  $T \rightarrow \infty$  to the corresponding moments of the normal distribution with parameters  $(0, \Sigma^{-1}(\vartheta))$ .*

*The maximum likelihood estimator  $\hat{\vartheta}_T$  is asymptotically efficient in  $K$ .*

# A counterexample

$$dX(t) = bX(t - \vartheta)dt + dW(t),$$

$$b < 0, \text{ fixed, } \vartheta \in (0, \frac{1}{e|b|}) = \Theta.$$

(ensures  $x_0(\cdot)$  is square integrable and does not oscillate)

$$Z_{T,\vartheta}(u) := \frac{d\mathbb{P}^{\vartheta+\varphi_T u}}{d\mathbb{P}^{\vartheta}} = \exp \left( b \int_0^T (X(t - \vartheta - \varphi_T u) - X(t - \vartheta)) dX(t) - \frac{b}{2} \int_0^T (X(t - \vartheta - \varphi_T u) - X(-\vartheta))^2 dt \right).$$

Here, the log-likelihood function is not quadratic w.r.t. to the parameter. Moreover,  $Z_T(u)$  depends on  $\vartheta$  in a non-differentiable way.



## Proposition (Kü, Kutoyants (2000))

For  $\phi_T = T^{-1}$  the marginal distributions of  $Z_{T,\phi}(\cdot)$  converge to the marginal distribution of

$$Z(u) = \exp \left\{ b\widetilde{W}(u) - \frac{1}{2}|u|b^2 \right\}, \quad u \in \mathbb{R}^1,$$

uniformly over every compact set  $K \subseteq \mathbb{R}^1$ .

Here,  $\widetilde{W}(\cdot)$  denotes a twosided standard Wiener process.

No LAQ

Remember:

$$Z_T(u) = \frac{d\mathbb{P}_{\vartheta+\varphi_T(\vartheta)u}^T}{d\mathbb{P}_{\vartheta}^T} \longrightarrow Z(u) = \exp \left[ b\tilde{W}(u) - \frac{1}{2}|u|b^2 \right],$$

in case  $a_{\vartheta}(dv) = b\mathbf{1}_{\{-\vartheta\}}(dv)$ .

$$Z_T(u) = \frac{d\mathbb{P}_{\vartheta+\varphi_T(\vartheta)u}^T}{d\mathbb{P}_{\vartheta}^T} \longrightarrow Z(u) = \exp \left[ uW - \frac{c^2}{2}u^2 \right]$$

in case  $a_{\vartheta}(dv) = \vartheta\mathbf{1}_{\{-1\}}(dv)$ .

# A bridge between these two cases

Consider two finite signed measures  $a(dv)$  and  $b(dv)$  on some interval  $[-r, 0]$ . Assume  $a(dv) \in M_s$  and denote by  $b_{\vartheta}(dv)$  the translated  $b(dv)$ :

$$b_{\vartheta}(B) = b(B - \vartheta).$$

Define

$$a_{\vartheta} = a + b_{\vartheta} - b \tag{8}$$

and assume  $a_{\vartheta} \in M_s$ ,  $\vartheta \in (\vartheta_0, \vartheta_1)$  with  $\vartheta_0 < 0 < \vartheta_1$ .

## Proposition (Gushchin, Kü (2010))

*The Normalized Likelihood Ratio*

$$Z_{\vartheta, T}(u) = \frac{d\mathbb{P}_{\vartheta + \tilde{\delta}_T u}^T}{d\mathbb{P}_{\vartheta}^T}$$

*converges for  $T \rightarrow \infty$  and for some normalizing function  $\tilde{\delta}_T$*

$$Z_{\vartheta, T}(u) \longrightarrow Z_{\vartheta}(u), \quad u \in \mathbb{R}^1$$

*( $Z_{\vartheta}(\cdot) \not\equiv 1$ , continuous in probability at zero) if and only if the function*

$$\psi_b(x) = \int_{-x}^x |\varphi_b(\lambda)|^2 d\lambda, \quad x \geq 0$$

*is regularly varying at infinity. In this case*

$$\tilde{\delta}_T \sim c\delta_T, \quad T \rightarrow \infty,$$

*for some  $c > 0$  and*

$$\delta_T^{-1} = \inf\{x \geq 1 \mid Tx^{-2}\psi_b(x) < 1\}.$$



Define

$$H = \sup \left\{ \gamma \leq 1 : \int_{-\infty}^{\infty} (1 + \lambda^2)^{-1} |\lambda|^{2\gamma} |\varphi_b(\lambda)|^2 d\lambda < \infty \right\}.$$

We have  $\frac{1}{2} \leq H \leq 1$  and  $\psi_b(\cdot)$  is regularly varying with index  $2 - 2H$ ,  $\delta_T$  is regularly varying with index  $-\frac{1}{2H}$ :

$$\delta_T \sim \ell(T) T^{-\frac{1}{2H}}.$$

$$Z_T(u) = \frac{d\mathbb{P}_{\vartheta + \varphi_T(\vartheta)u}^T}{d\mathbb{P}_{\vartheta}^T} \longrightarrow Z(u) = \exp \left[ B^H(u) - \frac{\mathbb{E}(B^H(u))^2}{2} \right], \quad (9)$$

where  $B^H$  is a **fractional BM**, i.e. a centered Gaussian process with covariance function given by

$$K(u, v) = C(|u|^{2H} + |v|^{2H} - |u - v|^{2H}).$$

### Proposition (Gushchin, Kü (2010))

For every  $H \in [\frac{1}{2}, 1]$  one can find examples  $(a_{\vartheta}(dv))$  with property (9).

The extrem cases:

$H = \frac{1}{2}$ :  $\delta_T = T^{-1}$ , and  $B^H(u)$  is a twosided standard Wiener process  $W(u)$ :  
(Kutoyants-Kü-case)

$H = 1$ :  $\delta_T = T^{-\frac{1}{2}}$ , and  $B^H(u)$  equals  $uW$  with a centered Gaussian r.v.  $W$ :  
LAN-case.

# Fractional affine DDE

$$D_0^\alpha y(t) = \int_{-r}^0 y(t+s) a(ds) + f(t), \quad (10a)$$

$$y(s) = \xi(s), \quad s \in [-r, 0], \quad \xi(\cdot) \in C([-r, 0]). \quad (10b)$$

Solution of (10):

$$y(t) = \xi(0)x_0(t) + D^{1-\alpha} \int_{-r}^0 \left( \int_u^0 x_0(t+u-v) \xi(v) dv \right) a(du) + \int_0^t x_0(t-s) f(s) ds.$$

Here  $x_0(\cdot)$  denotes the **fundamental solution of (10)**, i.e.,

$$\begin{aligned} D_0^\alpha x_0(t) &= \int_{-r}^0 x_0(t+s) a(ds), \\ x_0(s) &= \mathbf{1}_{\{0\}}(s), \quad s \in [-r, 0]. \end{aligned}$$

## Fundamental solution

$$D_0^\alpha x_0(t) = \int_{-r}^0 x_0(t+s) a(ds),$$

$$x_0(s) = \mathbf{1}_{\{0\}}(s), \quad s \in [-r, 0].$$

Laplace-transform:

$$\hat{x}_0(\lambda) = \frac{\lambda^{\alpha-1}}{\lambda^\alpha - \int_{-r}^0 e^{\lambda s} a(ds)}, \quad \operatorname{Re} \lambda > \|a\|^{\frac{1}{\alpha}}.$$

Characteristic function:

$$h_\alpha(\lambda) = \left[ \lambda^\alpha - \int_{-r}^0 e^{\lambda s} a(ds) \right] \cdot \lambda^{1-\alpha} = \lambda - \lambda^{1-\alpha} \int_{-r}^0 e^{\lambda s} a(ds).$$

## Fundamental solution

$$D_0^\alpha x_0(t) = \int_{-r}^0 x_0(t+s) a(ds),$$

$$x_0(s) = \mathbf{1}_{\{0\}}(s), \quad s \in [-r, 0].$$

There is a qualitative jump from  $\alpha = 1$  to  $\alpha < 1$  :  
 The characteristic function

$$h_\alpha(\lambda) = \lambda - \lambda^{1-\alpha} \int_{-r}^0 e^{\lambda s} a(ds)$$

is

- holomorphic only on  $\mathbb{C} \setminus \mathbb{R}_-$ ,
- discontinuous on  $\mathbb{R}_-$ ,

## Fundamental solution

$$D_0^\alpha x_0(t) = \int_{-r}^0 x_0(t+s) a(ds),$$

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## Theorem (Krol (2008))

For  $v_0 < 0$  we have  $x_0(t) = p(t)e^{v_0 t} + g(t)$ ,  $t \geq 0$ ,

with  $p(t)$  polynomially bounded function and

$$g(t) = \begin{cases} O(t^{-\alpha}), & \text{if } a([-r, 0]) \neq 0, \\ O(t^{-\mu}), & \text{for all } \mu \in (0, \alpha), \text{ if } a([-r, 0]) = 0. \end{cases}$$

Thus the asymptotic of the fundamental solution  $x_0(t)$  for  $t \rightarrow \infty$  is **not exponentially** but **polynomially**.

## Stochastic case

$$\begin{aligned}
 X(t) &= \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \int_{-r}^0 X(s+u) a(du) ds + B(t), \\
 X(s) &= \eta(s), \quad s \in [-r, 0].
 \end{aligned}$$

## Theorem (Krol (2008))

*There exists a stationary solution iff  $v_0 < 0$  and  $\alpha > \frac{1}{2}$ .*

## Stochastic case

$$\begin{aligned} X(t) &= \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \int_{-r}^0 X(s+u) a(du) ds + B(t), \\ X(s) &= \eta(s), \quad s \in [-r, 0]. \end{aligned}$$

## Corollary

*The covariance function  $K(t)$  of the stationary solution is given by*

$$K(t) = \int_0^t x_0(s) x_0(s+t) ds.$$

*$K(t)$  tends polynomially to zero for  $t \rightarrow \infty$ .*

Thus,  $(X(t), t \geq 0)$  has

”long-range dependence”



Thank you for your attention!

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