

Remarks on unstable equilibria of conservative systems

Victor Palamodov

Tel Aviv University

20-24 January 2020

Introduction

- A conservative mechanical system

$$\frac{d}{dt} \frac{\partial}{\partial x'_i} K(x, x') - \frac{\partial}{\partial x_i} K(x, x') + \frac{\partial}{\partial x_i} U(x) = 0, \quad i = 1, \dots, n$$

is considered in a neighborhood $\Omega \subset R^n$ of its equilibrium position with potential function U on Ω and kinetic energy function $K(x, x')$ is a positively defined quadratic form of velocity x' depending on x .

Introduction

- A conservative mechanical system

$$\frac{d}{dt} \frac{\partial}{\partial x'_i} K(x, x') - \frac{\partial}{\partial x_i} K(x, x') + \frac{\partial}{\partial x_i} U(x) = 0, \quad i = 1, \dots, n$$

is considered in a neighborhood $\Omega \subset R^n$ of its equilibrium position with potential function U on Ω and kinetic energy function $K(x, x')$ is a positively defined quadratic form of velocity x' depending on x .

- J.-L. Lagrange 1788 used positivity of second derivatives of U to conclude that a equilibrium point is stable.

Introduction

- A conservative mechanical system

$$\frac{d}{dt} \frac{\partial}{\partial x'_i} K(x, x') - \frac{\partial}{\partial x_i} K(x, x') + \frac{\partial}{\partial x_i} U(x) = 0, \quad i = 1, \dots, n$$

is considered in a neighborhood $\Omega \subset R^n$ of its equilibrium position with potential function U on Ω and kinetic energy function $K(x, x')$ is a positively defined quadratic form of velocity x' depending on x .

- J.-L. Lagrange 1788 used positivity of second derivatives of U to conclude that a equilibrium point is stable.
- The final form this result was given by G. Lejeune-Dirichlet 1846:
equilibrium point x_0 is stable if this point is strict local minimum of potential function U . (due conservation of the energy).

- The problem of inversion of Lagrange-Dirichlet theorem was the subject of many studies since A. M. Liapounov 1897.

- The problem of inversion of Lagrange-Dirichlet theorem was the subject of many studies since A. M. Liapounov 1897.
- The positive answer to this problem seems obvious: "*if at an equilibrium position potential energy is not a minimum, then the equilibrium is unstable*" (several references).

- The problem of inversion of Lagrange-Dirichlet theorem was the subject of many studies since A. M. Liapounov 1897.
- The positive answer to this problem seems obvious: *"if at an equilibrium position potential energy is not a minimum, then the equilibrium is unstable"* (several references).
- P.Painlevé 1904 gave an example of a C^∞ potential function U whose stable equilibrium point **is not a minimum**, see also A. Wintner 1941.

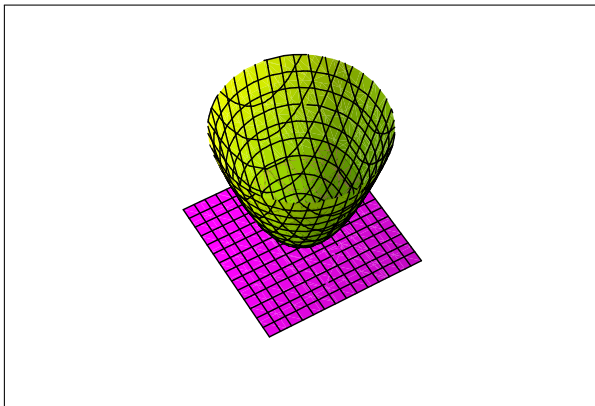
- The problem of inversion of Lagrange-Dirichlet theorem was studied by A.Liapounov 1892, 1897, A.Kneser 1895, P.Painlevé 1897, 1903, G.Hamel 1903, P.Bohl 1904, L.Silla 1908, E.Cotton 1911, N.Chetaev 1934,1938,1952,1955,1960, La Salle-Lefschetz 1961, B.Lanczos 1962, V.Maturosov 1962, M.Laloy 1962, W.Koiter 1965, N.Rouche 1968, L.Salvadori 1969,

- The problem of inversion of Lagrange-Dirichlet theorem was studied by A.Liapounov 1892, 1897, A.Kneser 1895, P.Painlevé 1897, 1903, G.Hamel 1903, P.Bohl 1904, L.Silla 1908, E.Cotton 1911, N.Chetaev 1934,1938,1952,1955,1960, La Salle-Lefschetz 1961, B.Lanczos 1962, V.Maturosov 1962, M.Laloy 1962, W.Koiter 1965, N.Rouche 1968, L.Salvadori 1969,
- P. Hagedorn 1971, V.Palamodov 1977, S.Taliaferro 1980, E.Liubushin 1980, M.Laloy-K.Peiffer 1982, V.Kozlov-V.Palamodov 1982, M.Sofer 1983, V.Kozlov 1981,1986,1987,1989, V.Moauero - P.Negrini 1991, M.Paternain 2019 and other.

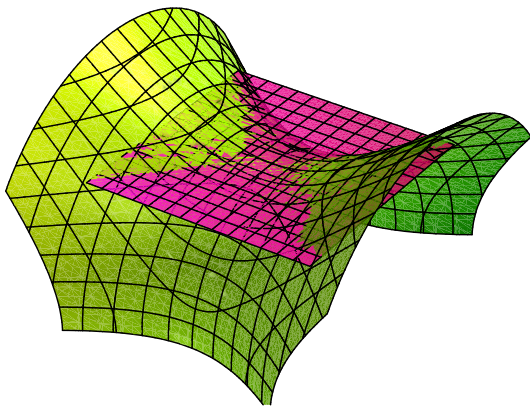
- The problem of inversion of Lagrange-Dirichlet theorem was studied by A.Liapounov 1892, 1897, A.Kneser 1895, P.Painlevé 1897, 1903, G.Hamel 1903, P.Bohl 1904, L.Silla 1908, E.Cotton 1911, N.Chetaev 1934,1938,1952,1955,1960, La Salle-Lefschetz 1961, B.Lanczos 1962, V.Maturov 1962, M.Laloy 1962, W.Koiter 1965, N.Rouche 1968, L.Salvadori 1969,
- P. Hagedorn 1971, V.Palamodov 1977, S.Taliaferro 1980, E.Liubushin 1980, M.Laloy-K.Peiffer 1982, V.Kozlov-V.Palamodov 1982, M.Sofer 1983, V.Kozlov 1981,1986,1987,1989, V.Moauero - P.Negrini 1991, M.Paternain 2019 and other.
- This problem was discussed by J.Hadamard 1897, E.Routh 1898, A.Wintner 1941, P.Appel 1955, V.Arnold 1976.

Stability and instability

- **Example 1.** Cup equilibrium point is stable

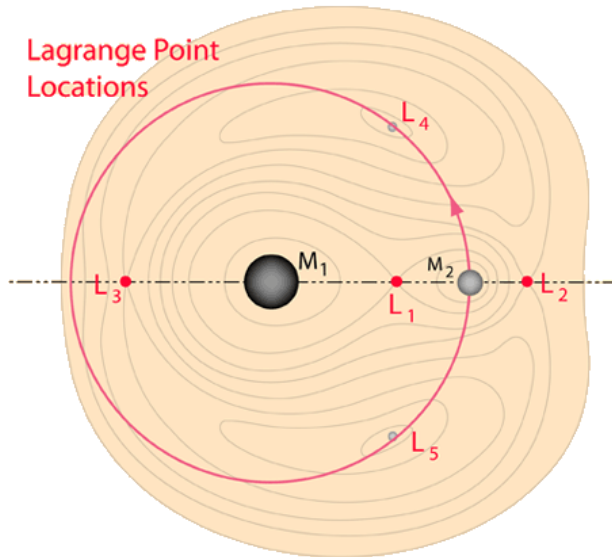


- **Example 2.** Saddle point make is unstable equilibrium



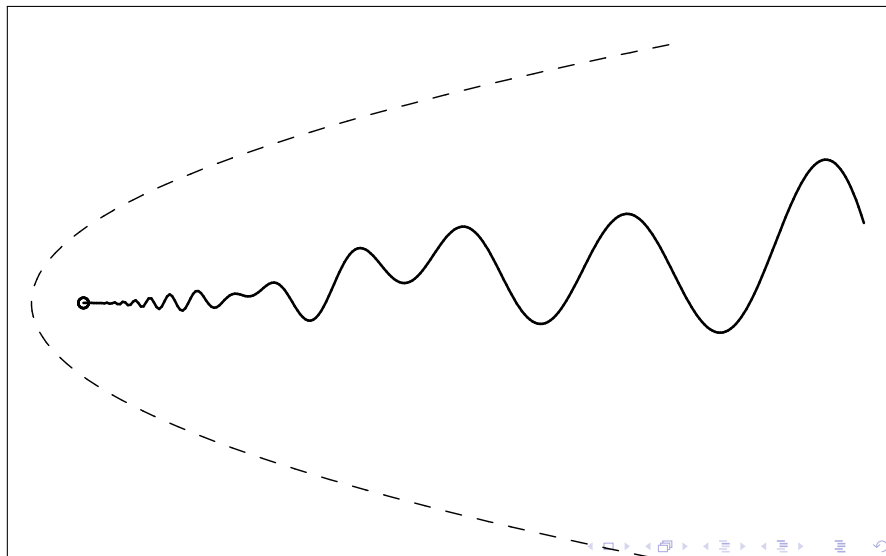
Saddle equilibrium point

- **Example 3.** Lagrange points



Asymptotic solutions

- Method of asymptotic solutions was first applied by Liapounov



Fatal instability

- **Definition.** We call equilibrium point x_0 of a function U on $\Omega \subset \mathbb{R}^n$ *fatally* unstable if any trajectory in Ω with subcritical energy $E \leq U(x_0)$ started from a non-equilibrium point reaches boundary $\partial\Omega$ in finite time.

Fatal instability

- **Definition.** We call equilibrium point x_0 of a function U on $\Omega \subset \mathbb{R}^n$ *fatally* unstable if any trajectory in Ω with subcritical energy $E \leq U(x_0)$ started from a non-equilibrium point reaches boundary $\partial\Omega$ in finite time.
- Definition has a sense only if point x_0 belongs to the boundary of set

$$X := \{x \in \Omega; U(x) < U(x_0)\}.$$

In this case fatal instability implies Liapounov's instability (not vice versa). If x_0 is a minimum (may be not strict) point of U in a neighborhood of x_0 , then there is no motion started from a non-equilibrium position, hence this equilibrium is fatally unstable in this sense.

Fatal instability

- **Definition.** We call equilibrium point x_0 of a function U on $\Omega \subset \mathbb{R}^n$ *fatally* unstable if any trajectory in Ω with subcritical energy $E \leq U(x_0)$ started from a non-equilibrium point reaches boundary $\partial\Omega$ in finite time.
- Definition has a sense only if point x_0 belongs to the boundary of set

$$X := \{x \in \Omega; U(x) < U(x_0)\}.$$

In this case fatal instability implies Liapounov's instability (not vice versa). If x_0 is a minimum (may be not strict) point of U in a neighborhood of x_0 , then there is no motion started from a non-equilibrium position, hence this equilibrium is fatally unstable in this sense.

- **Conjecture** *Any equilibrium point of an analytic potential function is fatally unstable.*

Fatal instability

- **Definition.** We call equilibrium point x_0 of a function U on $\Omega \subset R^n$ *fatally* unstable if any trajectory in Ω with subcritical energy $E \leq U(x_0)$ started from a non-equilibrium point reaches boundary $\partial\Omega$ in finite time.
- Definition has a sense only if point x_0 belongs to the boundary of set

$$X := \{x \in \Omega; U(x) < U(x_0)\}.$$

In this case fatal instability implies Liapounov's instability (not vice versa). If x_0 is a minimum (may be not strict) point of U in a neighborhood of x_0 , then there is no motion started from a non-equilibrium position, hence this equilibrium is fatally unstable in this sense.

- **Conjecture** *Any equilibrium point of an analytic potential function is fatally unstable.*
- Proved for $n = 2$ by P. 1977.

Basic Lemma

- The proof is based on

Basic Lemma

- The proof is based on
- **Lemma** *Let $x_0 \in \Omega$ and A a continuous tangent field A defined on $X = \{x \in \Omega, U(x) \leq U(x_0)\}$ satisfying conditions*

Basic Lemma

- The proof is based on
- **Lemma** *Let $x_0 \in \Omega$ and A a continuous tangent field A defined on $X = \{x \in \Omega, U(x) \leq U(x_0)\}$ satisfying conditions*
- *(I) $A(U) = P(U - U(x_0))$, where P is a positive continuous function on X and*

Basic Lemma

- The proof is based on
- **Lemma** *Let $x_0 \in \Omega$ and A a continuous tangent field A defined on $X = \{x \in \Omega, U(x) \leq U(x_0)\}$ satisfying conditions*
- *(I) $A(U) = P(U - U(x_0))$, where P is a positive continuous function on X and*
- *(II)*

$$\left(\xi \frac{\partial}{\partial x} A(x_0), \xi dx \right) |_{x=x_0} \geq 0.$$

Basic Lemma

- The proof is based on
- **Lemma** *Let $x_0 \in \Omega$ and A a continuous tangent field A defined on $X = \{x \in \Omega, U(x) \leq U(x_0)\}$ satisfying conditions*
- *(I) $A(U) = P(U - U(x_0))$, where P is a positive continuous function on X and*
- *(II)*

$$\left(\zeta \frac{\partial}{\partial x} A(x_0), \zeta dx \right) |_{x=x_0} \geq 0.$$

- *Then any solution of the Lagrange system started in X reaches ∂X in finite time.*

- Let w_1, \dots, w_n be positive rational numbers and

$$e_w = \sum w_k x_k \frac{\partial}{\partial x_k}$$

(weighted Euler field).

- Let w_1, \dots, w_n be positive rational numbers and

$$e_w = \sum w_k x_k \frac{\partial}{\partial x_k}$$

(weighted Euler field).

- Function U is called w -quasihomogeneous if $e_w(U) = \deg_w U \cdot U$ for some number $\deg_w U$.

- Let w_1, \dots, w_n be positive rational numbers and

$$e_w = \sum w_k x_k \frac{\partial}{\partial x_k}$$

(weighted Euler field).

- Function U is called w -quasihomogeneous if $e_w(U) = \deg_w U \cdot U$ for some number $\deg_w U$.
- **Proposition** Any quasihomogeneous potential function U , $\deg U > 0$ fulfils conditions (I) and (II) for $x_0 = 0$.

- Let w_1, \dots, w_n be positive rational numbers and

$$e_w = \sum w_k x_k \frac{\partial}{\partial x_k}$$

(weighted Euler field).

- Function U is called w -quasihomogeneous if $e_w(U) = \deg_w U \cdot U$ for some number $\deg_w U$.
- **Proposition** Any quasihomogeneous potential function U , $\deg U > 0$ fulfils conditions (I) and (II) for $x_0 = 0$.
- *Proof.* Condition I is obvious and inequality

$$\left\langle \xi \frac{\partial}{\partial x} e_w, \xi dx \right\rangle = \sum w_k \xi_k^2 \geq 0$$

implies II.

- **Example 3.** (M. Paternain 2019) Function

$$U_1(x, y, z) = \pm \left((y - x^2)^5 + (y - 2x^2)^5 + z^2 \right)^2$$

admits no geodesic curve through the origin

- **Example 3.** (M. Paternain 2019) Function

$$U_1(x, y, z) = \pm \left((y - x^2)^5 + (y - 2x^2)^5 + z^2 \right)^2$$

admits no geodesic curve through the origin

- It is quasihomogeneous with weights $w_x = 1/20$, $w_y = 1/10$, $w_z = 1/4$.

- **Example 3.** (M. Paternain 2019) Function

$$U_1(x, y, z) = \pm \left((y - x^2)^5 + (y - 2x^2)^5 + z^2 \right)^2$$

admits no geodesic curve through the origin

- It is quasihomogeneous with weights $w_x = 1/20$, $w_y = 1/10$, $w_z = 1/4$.
- **Example 4.** (M. Paternain 2019) Function

$$U_2 = \pm \left((y - x^2)^5 (y - 2x^2)^5 + (z - x^3)^2 \right)^2$$

has no geodesic curve through the origin.

- This function is not quasihomogeneous but field

$$A = \frac{1}{20}x \frac{\partial}{\partial x} + \frac{1}{10}y \frac{\partial}{\partial y} + \frac{1}{2} \left(z - \frac{7}{10}x^3 \right) \frac{\partial}{\partial z}$$

- This function is not quasihomogeneous but field

$$A = \frac{1}{20}x \frac{\partial}{\partial x} + \frac{1}{10}y \frac{\partial}{\partial y} + \frac{1}{2} \left(z - \frac{7}{10}x^3 \right) \frac{\partial}{\partial z}$$

- fulfils $A(u) = u$ where

$$u = (y - x^2)^5 (y - 2x^2)^5 + (z - x^3)^2.$$

- This function is not quasihomogeneous but field

$$A = \frac{1}{20}x \frac{\partial}{\partial x} + \frac{1}{10}y \frac{\partial}{\partial y} + \frac{1}{2} \left(z - \frac{7}{10}x^3 \right) \frac{\partial}{\partial z}$$

- fulfils $A(u) = u$ where
 $u = (y - x^2)^5 (y - 2x^2)^5 + (z - x^3)^2.$
- This yields $A(U_2) = A(u^2) = 2uA(u) = 2U_2$ which implies condition I of basic lemma.

- This function is not quasihomogeneous but field

$$A = \frac{1}{20}x \frac{\partial}{\partial x} + \frac{1}{10}y \frac{\partial}{\partial y} + \frac{1}{2} \left(z - \frac{7}{10}x^3 \right) \frac{\partial}{\partial z}$$

- fulfils $A(u) = u$ where
 $u = (y - x^2)^5 (y - 2x^2)^5 + (z - x^3)^2$.
- This yields $A(U_2) = A(u^2) = 2uA(u) = 2U_2$ which implies condition I of basic lemma.
- Quadratic form

$$\left(\xi \frac{\partial}{\partial x} A, d\xi \right) = \frac{1}{20}\xi_1^2 + \frac{1}{10}\xi_2^2 + \frac{1}{2}\xi_3^2 - \frac{21}{10}x^2 \xi_1 \xi_3$$

depending on x is positive defined if $|x| < \sqrt{2}/21$.

Results of eighties

- **Theorem** (V.Kozlov - V.Palamodov, 1982) *Let $m \geq 2$ and*

$$U(x) = u_m + \sum_{k>m} u_k(x)$$

where u_k is for any k , a homogeneous polynomial of degree k and series converges in a neighborhood of the origin.

Results of eighties

- **Theorem** (V.Kozlov - V.Palamodov, 1982) *Let $m \geq 2$ and*

$$U(x) = u_m + \sum_{k>m} u_k(x)$$

where u_k is for any k , a homogeneous polynomial of degree k and series converges in a neighborhood of the origin.

- *If u_m has no local minimum at $x = 0$,*

Results of eighties

- **Theorem** (V.Kozlov - V.Palamodov, 1982) *Let $m \geq 2$ and*

$$U(x) = u_m + \sum_{k>m} u_k(x)$$

where u_k is for any k , a homogeneous polynomial of degree k and series converges in a neighborhood of the origin.

- *If u_m has no local minimum at $x = 0$,*
- *then there exists an asymptotic solution to this point.*

Results of eighties

- **Theorem** (V.Kozlov - V.Palamodov, 1982) *Let $m \geq 2$ and*

$$U(x) = u_m + \sum_{k>m} u_k(x)$$

where u_k is for any k , a homogeneous polynomial of degree k and series converges in a neighborhood of the origin.

- *If u_m has no local minimum at $x = 0$,*
- *then there exists an asymptotic solution to this point.*
- **Theorem** (V.Kozlov, 1986) *The same conclusion holds for*

$$U(x) = u_2 + u_m + \sum_{k>m} u_k,$$

if $u_2 + u_m$ has no local minimum at equilibrium point $x = 0$.

- **Theorem** (P. 2019) *Let $m \geq 2$ and U is as Theorem K.-P. 1982, where u_k is for any k , homogeneous C^2 -function on a neighborhood Ω of the origin.*

- **Theorem** (P. 2019) *Let $m \geq 2$ and U is as Theorem K.-P. 1982, where u_k is for any k , homogeneous C^2 -function on a neighborhood Ω of the origin.*
- *If u_m has no critical point $\Omega \setminus 0$, then this point is fatally unstable .*

- **Theorem** (P. 2019) *Let $m \geq 2$ and U is as Theorem K.-P. 1982, where u_k is for any k , homogeneous C^2 -function on a neighborhood Ω of the origin.*
- *If u_m has no critical point $\Omega \setminus 0$, then this point is fatally unstable .*
- **Remarks.** The potential U need not to be analytic.

- **Theorem** (P. 2019) *Let $m \geq 2$ and U is as Theorem K.-P. 1982, where u_k is for any k , homogeneous C^2 -function on a neighborhood Ω of the origin.*
- *If u_m has no critical point $\Omega \setminus 0$, then this point is fatally unstable .*
- **Remarks.** The potential U need not to be analytic.
- The last condition and the conclusion are more strong than that of 1982.

- **Theorem** (P. 2019) *Let $m \geq 2$ and U is as Theorem K.-P. 1982, where u_k is for any k , homogeneous C^2 -function on a neighborhood Ω of the origin.*
- *If u_m has no critical point $\Omega \setminus 0$, then this point is fatally unstable .*
- **Remarks.** The potential U need not to be analytic.
- The last condition and the conclusion are more strong than that of 1982.
- The result of K.1986 can also be extended for series of quasihomogeneous functions.

- **Theorem** (P. 2019) *Let $m \geq 2$ and U is as Theorem K.-P. 1982, where u_k is for any k , homogeneous C^2 -function on a neighborhood Ω of the origin.*
- *If u_m has no critical point $\Omega \setminus 0$, then this point is fatally unstable .*
- **Remarks.** The potential U need not to be analytic.
- The last condition and the conclusion are more strong than that of 1982.
- The result of K.1986 can also be extended for series of quasihomogeneous functions.
- **Perspective:** *to prove the Conjecture!*

Thank you for listening and reading!

Wishing to Valeriy Vasilievich Kozlov
further achievements

in science and beyond

for many years to come!

