

The Ergodic Theorem in the Kozlov–Treschev Form

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SOME CLASSICS:

(X, \mathcal{A}, μ) a probability space

$g_t: X \rightarrow X$ measure preserving, $t \geq 0$,

$g_t g_s = g_{t+s}$, $g_0 = Id$, $g_t(x)$ measurable in (t, x)

THEN for any μ -integrable f a.e. and in $L^1(\mu)$

$$\lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t f(g_s(x)) ds = \bar{f}(x)$$

where \bar{f} conditional expectation of f w.r.t.
 σ -algebra \mathcal{I} generated by all g_t -invariant functions

Kozlov V.V., Treschev D.V.: On new forms of the ergodic theorem. J. Dynam. Control Syst. 2003. V. 9, N 3.

$\nu = \varrho(s) ds$ absolutely continuous probability measure on $[0, +\infty)$

BOUNDED f :

$$\lim_{t \rightarrow \infty} \int_0^{+\infty} f(g_{ts}(x)) \nu(ds) = \bar{f}(x), \quad (KT)$$

\bar{f} conditional expectation of f w.r.t. σ -algebra \mathcal{I} generated by all g_t -invariant functions

Classics: $\nu = \text{Lebesgue on } [0, 1]$, $\varrho(s) = I_{[0,1]}(s)$

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Generalizations of Kozlov–Treschev:

UNBOUNDED f

DYNAMICS OF MEASURES $\nu_{t,x}$ = image of ν
under $S_{t,x}: [0, +\infty) \rightarrow X$:

$$S_{t,x}(s) = g_{ts}(x),$$

$$\nu_{t,x}(A) = \nu(S_{t,x}^{-1}(A))$$

STOCHASTIC SYSTEMS:

$$d\xi_t^x = A(\xi_t^x) dW_t + b(\xi_t^x) dt, \quad \xi_0^x = x$$

$$F_t(x, w) = \int_0^\infty f(\xi_{ts}^x(w)) \nu(ds)$$

EXAMPLE. $X = S^1$, μ Lebesgue, g_t rotations,

$$f(z) = |\sin \theta|^{-1} (\ln |\sin \theta| - 1)^{-2},$$

$$z = \exp(i\theta), \theta \in [0, 2\pi)$$

One can find integrable ϱ on $[0, +\infty)$ and f on X such that

$$\limsup_n \int_0^{+\infty} f(g_{ns}(x)) \varrho(s) ds = +\infty$$

The effect due to $|\theta - n/k| \leq k^{-2}$ for infinitely many pairs n, k .

Theorem 1. $f \in L^p(\mu)$, $p \in [1, +\infty)$,
 $\varrho \in L^q[0, +\infty)$, $1/p + 1/q = 1$.

If ϱ has bounded support, then (KT) holds for
a.e. x .

More generally, this is true if

$$\varrho(s) \leq \beta(s), \quad s \geq s_0,$$

$\beta \in L^q[0, +\infty)$ monotone decreasing

??? IS BOUNDED SUPPORT IMPORTANT???

Dynamics of $\nu_{t,x}$:

Theorem 2. X Souslin space, μ Borel probability measure on X , $\{g_t\}$ ergodic. Then

$\nu_{t,x}$ converges weakly to μ as $t \rightarrow +\infty$

for μ -a.e. x .

Theorem 3. Under the same assumptions, for each $\varepsilon > 0$ there is a compact set $K \subset X$ with

$$\mu(K) > 1 - \varepsilon$$

such that the family of measures

$$\{\nu_{t,x} : t \geq \varepsilon, x \in K\}$$

is uniformly tight, i.e.

for each $\delta > 0$ there is a compact set Q_δ with $\nu_{t,x}(Q_\delta) > 1 - \delta$ for all these measures.

$\varepsilon > 0$ is important:

$$\nu_{0,x} = \delta_x \quad \text{Dirac's mass at } x$$

Stochastic case: $Lf = \text{trace}(AD^2f)/2 + \langle b, \nabla f \rangle$

Diffusion matrix A locally Lipschitz, nondegenerate,
drift b Borel, locally bounded,

there is a Lyapunov function V : as $|x| \rightarrow \infty$ we
have $V(x) \rightarrow +\infty$ and $LV(x) \rightarrow -\infty$.

Then there is an invariant probability measure μ for
this diffusion.

P be Wiener measure on the path space
 $W = C([0, +\infty), \mathbb{R}^d)$.

Theorem 4. f bounded Borel measurable. Then
for each x

$$\lim_{t \rightarrow +\infty} \int_0^{+\infty} f(\xi_{ts}^x(w)) \varrho(s) ds = \int_{\mathbb{R}^d} f(y) \mu(dy)$$

for P -a.e. $w \in W$.

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Measure Theory

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