HITCHIN SYSTEMS ON HYPERELLIPTIC CURVES: Separation of Variables

Oleg Sheinman

Steklov Mathematical Institute Moscow

Russian-Chinese Conference «Integrable Systems and Geometry» December 20–22, 2021



Hitchin systems - conventional set-up

G – classical simple Lie group $/\mathbb{C}$, Σ – cpt Riemann surface $/\mathbb{C}$

 ${\cal N}-\text{moduli}$ space of holomorphic s/st vector $\emph{G}\text{-bundles}$ with the standard representation as a fibre

For $E \in \mathcal{N}$ let $\operatorname{End}(E)$ be a bundle with the fiber \mathfrak{g} associated to E by means of the adjoint representation (Ad G)

Higgs field: a $\Phi \in H^0(\operatorname{End}(E) \otimes \mathcal{K})$, \mathcal{K} – canonical bundle

 χ – a degree d invariant polynomial χ on \mathfrak{g} , then

$$\chi(\Phi) \in H^0(\Sigma, \mathcal{K}^d).$$

Pick up a base $\{\Omega_j^d\}$ in $H^0(\Sigma, \mathcal{K}^d)$ and expand $\chi(\Phi)$ as:

$$\chi(\Phi) = \sum H_j(E, \Phi)\Omega_j^d.$$

THEOREM (HITCHIN, '87): $\{H_j\}$ give an integrable system on $T^*(\mathcal{N})$ (i.e. $\{H_i, H_j\} = 0$, and $\operatorname{card}\{H_j\} = \dim T^*(\mathcal{N})/2$)

Historical remarks

- 1987 Hitchin, Duke Math. J.
- 1994 Previato, van Geemen geometry of *SL*(2) case
- 1994 Simpson Hitchin systems in higher dimension
- 1996 2000 Hurtubise some observations on SoV and inverse spectral method
- 1998 Gawedzki *SL*(2), *θ*-functional formula
- 2001 Gorski–Nekrasov–Roubtsov: SoV in more effective terms (G = GL(n))
- **2001** Krichever Lax representation, Hamiltonian theory, inverse spectral method (G = GL(n))
- 2018 Sh. results of the present talk simple classical structure groups, hyperelliptic surfaces, SoV in explicit terms



Spectral curve

Partial trivialization: $\Phi \mapsto \Phi/\xi$, $\xi \in \Omega^1_{hol}(\Sigma)$

Spectral curve:

$$\det\left(\lambda - \frac{\Phi}{\xi}\right) = 0$$

Let $D = (\xi), d_1, \dots, d_n$ be the degrees of basis invariants of $\frac{\Phi}{\xi}$.

PROPOSITION: Basis degree d_j invariants of Φ/ξ run over $\mathcal{O}(-d_jD)$.

<u>**Hamiltonians**</u>: For $\forall j$, $H^0(\Sigma, \mathcal{K}^{d_j}) \simeq \mathcal{O}(-d_j D) \xi^{\otimes d_j}$. We pick up a base in $\mathcal{O}(-d_j D)$ rather than in $H^0(\Sigma, \mathcal{K}^{d_j})$.

Spectral curves of hyperelliptic A_n , B_n , C_n Hitchin systems (Sh'2018)

Let
$$\Sigma : y^2 = P_{2g+1}(x), \ \xi = \frac{dx}{y} \ \text{ (then } D = 2(g-1) \cdot \infty \text{)}.$$

PROPOSITION: A base in $\mathcal{O}(-d_jD)$ is formed by the functions $1, x, \dots, x^{d_j(g-1)}$, and $y, yx, \dots, yx^{(d_j-1)(g-1)-2}$.

PROPOSITION: (The affine part of) the spectral curve for a Hitchin system from the above list is a full intersection of the two surfaces in \mathbb{C}^3 : $y^2 = P_{2g+1}(x)$ and $R(\lambda, x, y, H) = 0$ where

$$R = \lambda^{d} + \sum_{j=1}^{n} \left(\sum_{k=0}^{d_{j}(g-1)} H_{jk}^{(0)} x^{k} + \sum_{s=0}^{(d_{j}-1)(g-1)-2} H_{js}^{(1)} x^{s} y \right) \lambda^{d-d_{j}}$$

where $H_{jk}^{(0)}$, $H_{js}^{(1)}$ are parameters (<u>Hamiltonians</u>).



Separating coordinates and Hamiltonians

Let \mathfrak{g} be a complex Lie algebra of one of the types A_n , B_n , C_n .

We give the spectral curve by means of a tuple of points it passes through. Since coefficients of the spectral curve depend on $h = \dim \mathfrak{g}(g-1)$ parameters (Hamiltonians), every tuple consists of h points denoted by $(\gamma_1, \ldots, \gamma_h)$, $\gamma_i = (x_i, y_i, \lambda_i)$, $\forall i$. In these coordinates the system looks as follows.

Phase space: tuples
$$\{(\lambda_1, x_1, y_1), \dots, (\lambda_h, x_h, y_h)\},\ h = (\dim \mathfrak{g})(g-1), \lambda_i, x_i, y_i \in \mathbb{C}, y_i^2 = P_{2g+1}(x_i) \ (i = 1, \dots, h)$$

<u>Poisson bracket</u> is given by $\{\lambda_i, x_j\} = \delta_{ij}y_i$ (to be proven below)

<u>Hamiltonians</u> $H_{jk}^{(0)}$, $H_{js}^{(1)}$ are defined from the system of linear equations (i = 1, ..., h):

$$\lambda_{i}^{d} + \sum_{j=1}^{n} \left(\sum_{k=0}^{d_{j}(g-1)} H_{jk}^{(0)} x_{i}^{k} + \sum_{s=0}^{(d_{j}-1)(g-1)-2} H_{js}^{(1)} x_{i}^{s} y_{i} \right) \lambda_{i}^{d-d_{j}} = 0$$

Symplectic form

Action–angle variables (I, α) are defined by

$$\lambda dz = \sum_{a=1}^{h} I^{a} \Omega_{a}, \quad \alpha_{a} = \sum_{i=1}^{h} \int^{\gamma_{i}} \Omega_{a}, \quad dz = \frac{dx}{y}$$

where Ω_a are normalized Prym differentials, $h = \dim \mathfrak{g}(g-1)$ (follows from Gorski-Nekrasov-Rubtsov 2001, Hurtubise 1996).

For the **symplectic form** it follows (by def. and variation of the \int in γ_i)

$$\omega = \sum_{a=1}^{n} \delta I^{a} \wedge \delta \alpha_{a} = \sum_{a=1}^{n} \delta I^{a} \wedge \sum_{i=1}^{n} \Omega_{a}(\gamma_{i})$$

Also, $\lambda dz = \sum_{a=1}^{h} I^{a} \Omega_{a} \Longrightarrow \lambda_{i} \delta z_{i} = \sum_{a=1}^{h} I^{a} \Omega_{a} (\gamma_{i}) \Longrightarrow$

 $\Longrightarrow \delta \lambda_i \wedge \delta z_i = \sum_{a=1}^h \delta I^a \wedge \Omega_a(\gamma_i), \, \forall i.$ Summing up in *i* gives

$$\omega = \sum_{i=1}^{h} \delta \lambda_{i} \wedge \delta z_{i} = \sum_{i=1}^{h} \delta \lambda_{i} \wedge \frac{\delta x_{i}}{y_{i}}$$



Example: $\mathfrak{g} = \mathfrak{sl}(2) \ (\sim A_1)$, genus 2 Hitchin system

(previous results E.Previato, 1994; Kz. Gawędzki, 1998)

Phase space:

 $\overline{\text{triples }}(\lambda_1, x_1, y_1), (\lambda_2, x_2, y_2), (\lambda_3, x_3, y_3)$ s.t.

$$\lambda_i^2 = H_0 + H_1 x_i + H_2 x_i^2, \ \ y_i^2 = P_5(x_i) \ (i = 1, 2, 3)$$

In these coordinates

$$H_i = \frac{\Delta_i}{\Delta}, \ \Delta = \begin{vmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \end{vmatrix}, \ \Delta_1 = \begin{vmatrix} \lambda_1^2 & x_1 & x_1^2 \\ \lambda_2^2 & x_2 & x_2^2 \\ \lambda_3^2 & x_3 & x_3^2 \end{vmatrix}, \ \text{etc.}$$

Symplectic form:

$$\sigma = d\lambda_1 \wedge \frac{dx_1}{y_1} + d\lambda_2 \wedge \frac{dx_2}{y_2} + d\lambda_3 \wedge \frac{dx_3}{y_3}$$



$\mathfrak{g} = \mathfrak{sl}(2)$: Hitchin equations in an explicit form

$$H_2 = \frac{\Delta_2}{\Delta}, \quad \Delta_2 = \begin{vmatrix} 1 & x_1 & \lambda_1^2 \\ 1 & x_2 & \lambda_2^2 \\ 1 & x_3 & \lambda_3^2 \end{vmatrix}, \ \Delta = \begin{vmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \end{vmatrix}$$

$$\begin{aligned} \{x_1, H_2\} &= \frac{2\lambda_1 y_1}{\Delta} (x_3 - x_2), \\ \{\lambda_1, H_2\} &= \frac{y_1}{(x_1 - x_2)^2 (x_1 - x_3)^2} \left(\Delta_2 \frac{2x_1 - x_2 - x_3}{x_2 - x_3} - 1 \right) \end{aligned}$$

and cyclic permutations of indices for (x_2, λ_2) , (x_3, λ_3)

Method of generating functions

Aim: to find out coordinates ϕ s.t. $\omega = \sum_{i} dH_{i} \wedge d\phi_{i}$.

Motivation: the flows are linearized in the coordinates (H, ϕ) : $H_i = const$, $\phi_i = \delta_{ii}t_i + \phi_{0,i}$.

PROPOSITION (HAMILTON, JACOBI, ARNOLD, SKLYANIN):

$$\phi_j = \partial S / \partial H_j$$

where $S = \sum_{i=1}^{h} S_i$, S_i to be found from $R\left(\frac{\partial S_i}{\partial z_i}, z_i, H\right) = 0$.

(here, $S_i = S_i(\gamma_i)$, z_i is a pull back of z_i on Σ).

$$\frac{\partial R}{\partial \lambda} \frac{\partial}{\partial H_j} \frac{\partial S_i}{\partial z_i} + \frac{\partial R}{\partial H_j} = 0 \implies \frac{\partial S_i}{\partial H_j} = -\sum_{i=1}^h \int^{\gamma_i} \frac{\partial R/\partial H_j}{\partial R/\partial \lambda} dz$$



Darboux coordinates – cases A_n , B_n , C_n

<u>Darboux coordinates:</u> $(H_{jk}^{(0)}, \phi_{jk}^{(0)})$, and $(H_{js}^{(1)}, \phi_{js}^{(1)})$

:

$$\phi_{jk}^{(0)} = \sum_{i=1}^{(\dim \mathfrak{g})(g-1)} \int_{-\infty}^{(x_i, y_i, \lambda_i)} \frac{x^k \lambda^{d-d_j} dx}{R'_{\lambda}(x, y, \lambda) y}, \ 0 \le k \le d_j(g-1);$$

$$\phi_{js}^{(1)} = \sum_{i=1}^{(\dim \mathfrak{g})(g-1)} \int_{-\infty}^{(x_i, y_i, \lambda_i)} \frac{x^s \lambda^{d-d_j} dx}{R'_{\lambda}(x, y, \lambda)}, \ 0 \le s \le (d_j - 1)(g-1) - 2$$

THEOREM: Integrands form a base of holomorphic differentials on the spectral curve for A_n (n > 1), and a base of holomorphic Pryme differentials for the systems A_1 , B_n , C_n (w.r.t involution $\lambda \to -\lambda$).

Remarks on basis differentials

Peculiarities of the case D_n :

- Separation relations $R(\lambda_i, x_i, y_i, H) = 0$ are quadratic in H (because the last coefficient of R is det $L = (Pf L)^2$);
- Basis differentials are the same for j < n, and are multiplied by 2(Pf L) for j = n;
- They form a base of holomorphic Prym differentials on the normalization of the spectral curve.

Consecutive numbering:

$$\omega_j = \frac{\partial R/\partial H_j}{\partial R/\partial \lambda} \frac{dx}{v}, \quad j = 1, \dots, h$$

in all cases (A_n, B_n, C_n, D_n) .



Action–angle variables via (H, ϕ)

Let
$$A_j^a = \oint_a \omega_j$$
, $A = (A_j^a)$, then $\omega_j = \sum_{a=1}^h A_j^a \Omega_a$, hence for angle variables: $\alpha_a = \sum (A^{-1})_a^j \phi_j$

Problem of finding the matrix A descends to the problem of finding the branch points of the spectral curve, i.e. to the system of algebraic equations $R(\lambda, x, y) = 0$, $R'_{\lambda}(\lambda, x, y) = 0$. The last is solvable in radicals only for $\mathfrak{g} = \mathfrak{sl}(2), \mathfrak{so}(4)$.

Defining relation for <u>action variables</u> is: $\lambda \frac{dx}{y} = \sum_{a=1}^{h} I^{a} \Omega_{a}$. Plug $\Omega_{a} = \sum (A^{-1})_{a}^{j} \omega_{j}$, $\omega_{j} = \frac{\partial R/\partial H_{j}}{R_{\lambda}^{\prime}} \frac{dx}{y}$, and $\lambda = \lambda_{i}$, $x = x_{i}$, $y = y_{i}$. Then I^{a} are to be found out of the linear system of equations

$$\lambda_i R'_{\lambda}(x_i, y_i, H) = \sum_{a=1}^h I^a \sum_{j=1}^h (A^{-1})^j_a \frac{\partial R(x_i, y_i, H)}{\partial H_j}, \quad i = 1, \dots, h$$

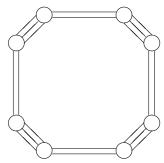
$\mathfrak{so}(4),\,g=2$ case (P.Borisova, Sh'19)

Spectral curve:
$$R(\lambda, x, y, H) = \lambda^4 + \lambda^2 p + q^2 = 0$$

where
$$p = H_0 + xH_1 + x^2H_2$$
, $q = H_3 + xH_4 + x^2H_5$.

<u>THEOREM</u> (P.BORISOVA): Separation equations and equations for branching points are solvable in radicals.

Normalized spectral curve has 16 branching points. By Riemann–Hurwitz $\hat{g}=13$. Involution $\sigma:\lambda\to-\lambda$ is a rotation by π around the center of the picture. No fixed points. 8 preimages of 4 singular points are located in the middles of horizontal lines (2 at each one). Normalization map glues



the points at the opposite horizontal lines.

$\mathfrak{sl}(2)$, $\mathfrak{sp}(4)$, $\mathfrak{so}(5)$, g=2 cases

Case $\mathfrak{sl}(2)$ Spectral curve: $\lambda^2 p + H_0 + xH_1 + x^2H_2 = 0$

$$\lambda p + n_0 + xn_1 + x n_2 =$$

has 4 branching points.

By Riemann–Hurwitz
$$\hat{g} = 5$$
.
Involution $\sigma : \lambda \to -\lambda$ is a

rotation by π around the vertical axis of the picture.

Case sp(4) Spectral curve:

$$\lambda^4 + \lambda^2 p + q = 0,$$

 $p = H_0 + xH_1 + x^2H_2, q = 0$

 $H_3 + xH_4 + \dots x^4H_7 + yH_8 + xyH_9$, has 24 branching points.

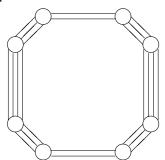
By Riemann–Hurwitz $\hat{q} = 17$.

Involution $\sigma: \lambda \to -\lambda$ is a

reflection in the vertical axis.



Fixed points=branching points with $\lambda = 0$



Case $\mathfrak{so}(5)$ Spectral curve is the same as for $\mathfrak{sp}(4)$



Thank you!