# On the method of solving the Cauchy problem for stochastic and deterministic generalized Burgers equations

Zotova Ekaterina Igorevna

Under the Guidance of Prof. Nasyrov Farit Sagitovich

### Cauchy problem for the generalized Burgers equation

$$u_t + (f(u))_x = u_{xx}, \quad u(x,0) = \varphi(x),$$
  
 $u = u(x,t), \quad (x,t) \in \mathbb{R} \times \mathbb{R}^+.$ 

### Cauchy problem for the Burgers equation [1]

$$u_t + uu_x = u_{xx}, \quad u(x,0) = \varphi(x),$$
  
 $u = u(x,t), \quad (x,t) \in \mathbb{R} \times \mathbb{R}^+.$ 

- **Hydrodynamics and shock wave theory.** Used as a simplified model of viscous fluid flow. Describes the formation and attenuation of shock waves in gases and liquids.
- Acoustics. Models the propagation of large-amplitude sound waves.
- In turbulence theory the Burgers equation is used as a test model for studying the interaction of nonlinear and dissipative effects.

[1] Burgers J. M., The Nonlinear Diffusion Equation: Asymptotic Solutions and Statistical Problems. Dordrecht: D. Reidel, 1974.

# Method for solving the Cauchy problem for the Burgers equation

The Cole-Hopf transform (see [2],[3])

$$u = -2\frac{\partial \ln \phi}{\partial x}$$

reduces the Burgers equation to the heat equation

$$\phi_t = \phi_{xx}, \quad \phi = \phi(x, t), \quad (x, t) \in \mathbb{R} \times \mathbb{R}^+.$$

The solution of the Cauchy problem for the Burgers equation in this case is determined from the relations

$$u(x,t) = \frac{\int_{-\infty}^{\infty} \frac{x-\eta}{t} \exp\left\{\frac{-G(\eta, x, t)}{2}\right\} d\eta}{\int_{-\infty}^{\infty} \exp\left\{\frac{-G(\eta, x, t)}{2}\right\} d\eta},$$
$$G(\eta, x, t) = \frac{(x-\eta)^2}{2t} + \int_{0}^{x} \varphi(\mu) d\mu.$$

- [2] Cole J. D., On a quasi-linear parabolic equation occurring in aerodynamics // Quart. Appl. Math., V. 9, N. 3, P. 225–236, 1951.
- [3] Hopf E., The partial differential equation  $u_t + uu_x = u_{xx}$  // Comm. Pure and Appl. Math., V. 3, P. 201–230, 1950.

# Stochastic Burgers equation with additive white noise in space and time [4]

$$u_t + uu_x = u_{xx} + \varepsilon \eta_t(x),$$

where  $\varepsilon$  is a constant,  $\eta_t(x)$  is white noise in space and time, i.e.

$$\mathbf{E}(\eta_t(x)\eta_{t'}(x')) = \delta(x - x')\delta(t - t').$$

### Cauchy problem for stochastic Burgers equation [5]

$$u_t + uu_x = u_{xx} + F(u) + W'(t),$$

where W(t) is a Wiener process and W'(t) is its formal derivative.

- [4] Bertini L., Cancrini N., Jona-Lasinio G. The stochastic Burgers Equation // Commun. Math. Phys. V. 165, P. 211–232, 1994.
- [5] Nasyrov F.S., Paramoshina I.G., Numerical analytical method of resolve of some classes of stochastic partial differential equations // Bulletin of the Ufa State Aviation Technical University. 2008. V. 11, № 1 (28), P. 175–180. (in Russian)

The goal of research is to construct a new method for solving the Cauchy problem for the generalized Burgers equation both with noise and without noise.

# Formal notation of the Cauchy problem for the generalized Burgers equation with noise in the nonlinear part

$$u_t + (f(u))_x V'(t) = u_{xx}, \quad u(x,0) = \varphi(x),$$
  
 $u = u(x,t), \quad (x,t) \in \mathbb{R} \times \mathbb{R}^+,$ 

where V'(t) is the formal derivative of a continuous deterministic function V(t) or a random process V(t) with continuous realizations that may not exist (for example, V(t) = W(t) is a Wiener process).

Let a random process V(t), V(0) = 0,  $t \in [0, T]$ , with continuous realizations with probability 1 be defined on the probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .

## Cauchy problem for stochastic generalized Burgers equation in integral form

$$u(x,t) - u(x,0) + \int_0^t (f(u(x,s)))_x * dV(s) = \int_0^t u_{xx}(x,s)ds,$$

$$u(x,0) = \varphi(x).$$
(1)

where the integral on the left side of the equality is a symmetric integral with respect to the process V(t).

A symmetric integral with respect to a continuous function is a generalization of the Stratonovich stochastic integral and coincides with it in the case of a Wiener process [6].

[6] F.S. Nasyrov. Local Times, Symmetric Integrals, and Stochastic Analysis. Fizmatlit, Moscow, 2011 (in Russian).

#### Theorem.

Let the function g(x, v) be determined from the relation

$$g(x,v) = \varphi(x - vf'(g(x,v))), \quad (x,v) \in \mathbf{R} \times \mathbf{R}.$$
 (2)

Then the function

$$u(x,t) = \frac{1}{2\sqrt{\pi t}} \int_{-\infty}^{\infty} g(\xi, V(t)) \exp\left\{\frac{-(x-\xi)^2}{4t}\right\} d\xi,$$

is a solution to the Cauchy problem for the stochastic generalized Burgers equation (1).

**Remark 1.** The implicit relation (2) is obtained by solving the Cauchy problem for the generalized Hopf equation

$$g_v + f'(g)g_x = 0$$
,  $g(x,0) = \varphi(x)$ ,  $(x,v) \in \mathbf{R} \times \mathbf{R}$ .

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**Remark 2.** Setting  $f(u) = \frac{u^2}{2}$  in problem (1). We obtain the Cauchy problem for the stochastic Burgers equation. The solution of this problem is determined from the relations

$$u(x,t,V(t)) = \frac{1}{2\sqrt{\pi t}} \int_{-\infty}^{\infty} g(\xi,V(t)) \exp\left[\frac{-(x-\xi)^2}{4t}\right] d\xi,$$
  

$$g(x,V(t)) = \varphi(x-V(t)g(x,V(t))).$$
(3)

**Remark 3.** Let in problem (1)  $f(u) = \frac{u^2}{2}$  and V(t) = t, we obtain the Cauchy problem for the deterministic Burgers equation

$$u_t + uu_x = u_{xx}, \quad u(x,0) = \varphi(x).$$

The solution to this problem is determined from the relations

$$u(x,t) = \frac{1}{2\sqrt{\pi t}} \int_{-\infty}^{\infty} g(\xi,t) \exp\left[\frac{-(x-\xi)^2}{4t}\right] d\xi,$$
$$g(x,t) = \varphi(x-tg(x,t)).$$

#### Example 1.

$$\varphi(x) = \exp\left\{\frac{-x^2}{2}\right\} \tag{4}$$

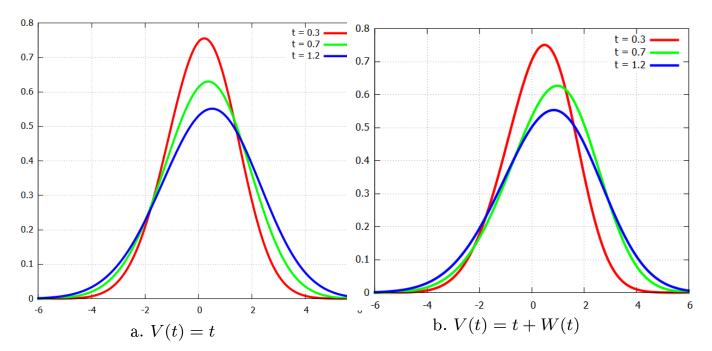


Fig. 1: Results of modeling solution of Cauchy problem for stochastic Burgers equation with initial condition (4) for linear and random functions V(t) at different times (W(t) is a Wiener process).

Example 2.

$$\varphi(x) = \exp\left\{\frac{-(x-1)^2}{2}\right\} - \exp\left\{\frac{-(x+1)^2}{2}\right\}$$
 (5)

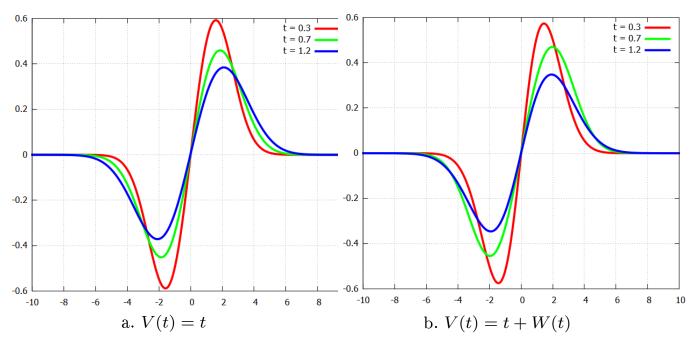


Fig. 2: Results of modeling solution of Cauchy problem for stochastic Burgers equation with initial condition (5) for linear and random functions V(t) at different times (W(t) is a Wiener process).

#### Example 3.

$$\varphi(x) = \sin(2\pi x) \tag{6}$$

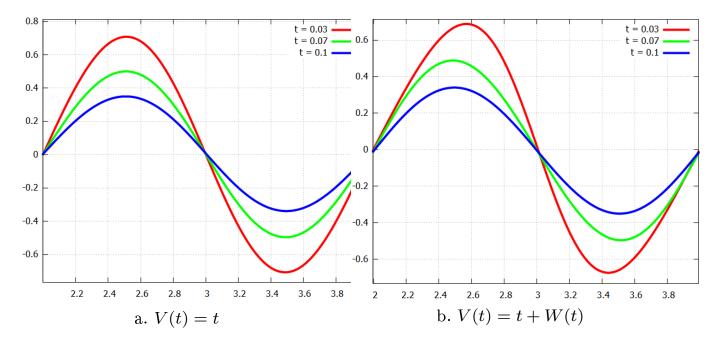


Fig. 3: Results of modeling solution of Cauchy problem for stochastic Burgers equation with initial condition (6) for linear and random functions V(t) at different times (W(t) is a Wiener process).

- 1 Burgers J. M., The Nonlinear Diffusion Equation: Asymptotic Solutions and Statistical Problems. Dordrecht: D. Reidel, 1974.
- Cole J. D., On a quasi-linear parabolic equation occurring in |2|aerodynamics // Quart. Appl. Math., V. 9, N. 3, P. 225–236, 1951.
- [3] Hopf E., The partial differential equation  $u_t + uu_x = u_{xx}$  // Comm. Pure and Appl. Math., V. 3, P. 201–230, 1950.
- |4|Bertini L., Cancrini N., Jona-Lasinio G. The stochastic Burgers Equation // Commun. Math. Phys. V. 165, P. 211–232, 1994.
- Nasyrov F.S., Paramoshina I.G., Numerical analytical method of |5|resolve of some classes of stochastic partial differential equations // Bulletin of the Ufa State Aviation Technical University. 2008. V. 11, No. 1 (28), P. 175–180. (in Russian)
- F.S. Nasyrov. Local Times, Symmetric Integrals, and Stochastic |6| Analysis. Fizmatlit, Moscow, 2011 (in Russian).

# Thank you for your attention!

**Definition 1.** Let V(t),  $t \in [0, +\infty)$ , be an arbitrary continuous function, then the symmetric integral is called

$$\int_{0}^{t} f(s, V(s)) * dV(s) = \lim_{n \to \infty} \sum_{k} \frac{1}{\Delta t_{k}^{(n)}} \int_{[\Delta t_{k}^{(n)}]} f(s, V^{(n)}(s)) ds \, \Delta V_{k}^{(n)} = \lim_{n \to \infty} \int_{0}^{t} f(s, V^{(n)}(s)) (V^{(n)})'(s) ds,$$

where  $V^{(n)}(s)$  is a broken line constructed by the function V(t) and the partition  $\{t^{(n)}\}$  of the interval [0,t] such that  $\max_n(t_k^{(n)}-t_{k-1}^{(n)})\to 0$  for  $n\to\infty$ .

**Definition 2.** For a pair of functions (V(s), f(s, u)), condition (S) is said to be satisfied if the following assumptions are satisfied:

- (a) V(s),  $s \in [0, t]$ , is a continuous function;
- (b) For almost all u, the function f(s, u),  $s \in [0, t]$ , is right-continuous and has bounded variation;
- (c) The total variation |f|(t,u) with respect to s of the function f(s,u) on [0,t] is locally summable with respect to the variable u;
- (d) For almost all u  $\int_0^t \mathbf{1}(s:V(s)=u)|f|(ds,u)=0$ , where  $\mathbf{1}(A)$  is the indicator of the set A, i.e. a function equal to 1 on A and 0 outside A.

Some properties of the symmetric integral:

1. Let a pair of functions (V(s), f(s, v)) satisfy condition (S), then

$$\int_0^t f(s, V(s)) * dV(s) = \int_{V(0)}^{V(t)} f(t, v) dv - \int_{\mathbb{R}} \int_0^t \kappa(v, V(0), V(s)) f(ds, v) dv, \quad (3.1)$$

where  $\kappa(v, a, b) = sgn(b-a)\mathbf{1}(a \land b < v < a \lor b)$ . This means that the symmetric integral is a function of three variables.

2. Let the function F(t, u) have continuous partial derivatives  $F'_t(t, u)$  and  $F'_u(t, u)$ , then there exists a symmetric integral  $\int_0^t F'_u(s, V(s)) * dV(s)$ , and the formula

$$F(t, V(t)) - F(0, V(0)) = \int_0^t F_s'(s, V(s))ds + \int_0^t F_u'(s, V(s)) * dV(s) is valid.$$
 (3.2)

If V(s) is a Wiener process, then formula (3.2) coincides with the formula for the Stratonovich stochastic differential.

**Lemma 1.** (On the equality of two integrals) Let V(s),  $s \in [0, T]$ , be a continuous nowhere differentiable function. Suppose that the continuous functions  $f_1(s, v)$  and  $f_2(s, v)$ ,  $(s, v) \in [0, T] \times \mathbb{R}$  satisfy the following conditions:

- (a) The function  $f_2(s, V(s)), s \in [0, T]$ , is summable;
- (b) The function  $f_1(s,v)$  for each s is summable over the variable  $v \in R$  and has a continuous derivative  $(f_1(s,v))'_s$  satisfying the condition  $\int_{\mathbb{R}} \int_0^T |(f_1(s,v))'_s| ds dv < \infty.$

Then the condition

$$\int_0^t f_1(s, V(s)) * dV(s) = \int_0^t f_2(s, V(s)) ds, \quad t \in [0, T],$$

is equivalent to the condition

$$f_1(s, V(s)) = f_2(s, V(s)) = 0, s \in [0, T].$$