# On $G_2$ Holonomy Riemannian Metrics on Deformations of Cones over $S^3 \times S^3$

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Let  $(M^n, g)$  be Riemannian manifold. Metric g generates Levi-Chivita connection  $\nabla$  and parallel transportation operation

$$P_{\gamma}: T_{\gamma}(0)M \rightarrow T_{\gamma}(1)M$$

along arbitrary curve  $\gamma:[0,1]\to M$ .

Fix  $p \in M$ . Then any loop  $\gamma : [0,1] \to M$ ,  $\gamma(0) = \gamma(1) = p$  gives isometric transformation

$$P_{\gamma} \in O(n) = Iso(T_pM).$$

The set of all such transformation generates Holonomy Group  $Hol_p = Hol$  of Riemannain manifold M which is a subgroup of O(n):

$$\mathsf{Hol}_p = \{P_\gamma | \gamma : [0,1] \to \mathsf{M}, \gamma(0) = \gamma(1) = \mathsf{p}\} \subset \mathsf{O}(\mathsf{n}).$$

It is easy to see that conjugation class of  $Hol_p$  in O(n) does not depend of p.

Question: what are the subgroups of O(n) which can be holonomy groups of some Riemannian manifold  $M^n$ ?

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If M is simply connected then  $Hol \subset SO(n)$  and we have:

# Borel-Lichnerowicz, 1952

Holonomy group of simply connected n-dimensional Riemannian manifold is compact Lie subgroup of SO(n)

If M is not simply connected then the analogous result is not true (Wilking, 1999).

The action of  $P_{\gamma}$  on  $T_pM$  is called holonomy representation. The following theorem shows that holonomy group characterizes global structure of complete Riemannian manifold.

## de Rham, 1952

Let holonomy representation of holonomy group G of complete Riemannian manifold M can be reduced to product of two representation of groups  $G_1$  and  $G_2$  (in particular G is isomorphic to product  $G_1 \times G_2$ ). Then M is isometric to Cartesian product of two compete Riemannian manifolds  $M_1$  and  $M_2$  with holonomy groups  $G_1$  and  $G_2$  (and with corresponding holonomy representations).

The first important examples of special holonomy groups were shown by Cartan:

## E. Cartan, 1923-1926

Let M be symmetric space and G be the group generated by all reflections of M which turn geodesics and M = G/H. Then holonomy group of M is isomorphic to H.

Cartan obtained list of all symmetric spaces with corresponding holonomy groups.

## Berger, 1955

Let M be simply connected irreducible (in the since of de Rham theorem) Riemannian n-dimensional manifold which is not a symmetric. Then one of the following case holds:

- 1) Hol(M) = SO(n) general case,
- 2) n = 2m, where  $m \ge 2$ ,  $Hol(M) = U(m) \subset SO(2m)$  Kähler manifolds,
- 3) n=2m, where  $m \geq 2$ ,  $Hol(M)=SU(m) \subset SO(2m)$  special Kähler manifolds,
- 4) n=4m, where  $m\geq 2$ ,  $Hol(M)=Sp(m)\subset SO(4m)$  hyper-Kähler manifolds,
- 5) n=4m, where  $m\geq 2$ ,  $Hol(M)=Sp(m)Sp(1)\subset SO(4m)$  -quaternionic Kähler manifolds,
- 6) n = 7,  $Hol(M) = G_2 \subset SO(7)$ ,
- 7) n = 8,  $Hol(M) = Spin(7) \subset SO(8)$ .



Riemannian manifold M is Einstein manifold with cosmological constant  $\Lambda$  if it satisfies Einstein equation:

$$R_{ij} = \Lambda g_{ij}$$
.

The following facts give method of finding solutions of Einstein equation.

- Riemannian metrics with  $Hol(M) = SU(m), Sp(m), G_2, Spin(7)$  satisfy Einstein equation for  $\Lambda = 0$  (Ricci-flat case:  $R_{ij} = 0$ ). For  $G_2$ , Spin(7) it was proved by Bonan, 1966.
- Riemannian metrics with Hol(M) = Sp(m)Sp(1) satisfy Einstein equation for some  $\Lambda \neq 0$ .

Ricci-flat manifolds are the most difficult for constructing.

#### **Fact**

All known compact simply connected Ricci-flat Einstein manifolds have special holonomy group SU(m), Sp(m),  $G_2$  or Spin(7).

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Existing of Riemannian manifolds with special holonomy growps:

- holonomy U(m), Sp(m)Sp(1) classical spaces;
- holonomy Sp(m), SU(m) Calabi, 1978;
- holonomy  $G_2$ , Spin(7) Bryant, Salamon, 1987 (first examples), 1989 (first complete examples); Joyce, 1996 (first compact examples).

Further development in  $G_2$  holonomy: Kovalev, 2003 (compact examle), noncompact examples by mathematical physicists.

- Construction of Joyce: to consider flat orbifold T<sup>7</sup>/Γ, discrete group Γ
  act by isometries with disjoint copies of T<sup>3</sup> as fixed points set; then
  make blowup of each copy.
- Construction of Kovalev: to glue two copies of product of  $S^1$  and special SU(3) holonomy noncompact space.

In each construction we need to make some «surgery» of noncompact Riemannian manifolds with holonomy group  $H \subset G_2$  and then to disturb resulting Riemannian metric to produce special holonomy.

Lie group  $G_2$  can be defined as group of all automorphisms of octonions  $\mathbb{C}a$  (the Cayley numbers). Another representation of  $G_2$  can be considered if we produce skew symmetric three-form apply standard scalar product in  $\mathbb{C}a$  to multiplication operation of octonions.

Let  $\{e^i\}$ ,  $i=0,1,2,\ldots,7$  be orthonormal coframe in  $\mathbb{R}^7$ . Putting  $e^{ijk}=e^i\wedge e^j\wedge e^k$  consider three-form  $\Phi_0$  and Hodge star dual four-form  $\star\Phi_0$  on  $\mathbb{R}^7$ :

$$\begin{split} &\Phi_0 = e^{123} + e^{147} + e^{165} + e^{246} + e^{257} + e^{354} + e^{367}, \\ &\star \Phi_0 = e^{4567} + e^{2356} + e^{2374} + e^{1357} + e^{1346} + e^{1276} + e^{1245}, \end{split}$$

Then 
$$G_2 = \{A \in GL(7) | A^*\Phi_0 = \Phi_0, A^*(\star\Phi_0) = (\star\Phi_0) \}.$$



## G<sub>2</sub> structure

Differential three-form  $\Phi$  on oriented 7-dimensional manifold M defines  $G_2$  structure if in a neighborhood of every point  $p \in M$  there exits orientation preserving isometry  $\phi_p : T_pM \to \mathbb{R}^7$  such that  $\phi_p^*\Phi_0 = \Phi_p$ .

Moreover it possible to show that form  $\Phi$  defines unique Riemanian metric  $g=g_{\Phi}$  such that  $g_{\Phi}(v,w)=\langle \phi_p v,\phi_p w\rangle$  for  $v,w\in T_pM$ . If differential form  $\Phi$  is parallel with respect to Levi-Chivita connection (that is  $\nabla\Phi=0$ ) then holonomy group of Riemannian manifold (M,g) is a subgroup of the group  $G_2$ . Parallelism condition is very restrictive and bring to over-defined differential equations.

Gray proved that form  $\Phi$  is parallel if and only if it is closed and coclosed:

$$d\Phi = 0, d \star \Phi = 0.$$

The last two equations are correct in some geometrical cases.



# $G_2$ structure on the cone over $S^3 \times S^3$

 $S^3 = SU(2) = \{ \begin{pmatrix} a & b \\ -\bar{b} & \bar{a} \end{pmatrix}, |a|^2 + |b|^2 = 1 \}$  with standard biinvariant metric.

$$\langle X, Y \rangle = -\text{tr } (XY),$$

where  $X, Y \in \mathbf{su}(2)$ . On the  $S^3$  consider three Killing vector fields:

$$\xi^1 = \left(\begin{array}{cc} i & 0 \\ 0 & -i \end{array}\right), \ \xi^2 = \left(\begin{array}{cc} 0 & 1 \\ -1 & 0 \end{array}\right), \ \xi^3 = \left(\begin{array}{cc} 0 & i \\ i & 0 \end{array}\right),$$

$$[\xi^{i}, \xi^{i+1}] = 2\xi^{i+2},$$

where indexes i=1,2,3 are reduced mod3. Let  $\eta_1,\eta_2,\eta_3$  be dual co-frame,  $\eta_i(\xi^j)=\delta^j_i$ . Then

$$d\eta_i = -2\eta_{i+1} \wedge \eta_{i+2}$$
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# $G_2$ structure on the cone over $S^3 \times S^3$

Let  $M = S^3 \times S^3$  then there exist six Killing vector fields  $\xi^i$ ,  $\tilde{\xi}^i$ , i = 1, 2, 3 on M tangent to first and second factor, respectively, and there exist six dual one-forms  $\eta_i$ ,  $\tilde{\eta}_i$ . Consider cone  $\overline{M} = \mathbb{R}_+ \times M$  with a metric

$$d\bar{s}^2 = dt^2 + \sum_{i=1}^3 A_i(t)^2 (\eta_i + \tilde{\eta}_i)^2 + \sum_{i=1}^3 B_i(t)^2 (\eta_i - \tilde{\eta}_i)^2,$$

where  $A_i(t)$  and  $B_i(t)$  are some positive functions which define deformation of standard cone metric. If we consider orthonormal co-frame

$$\begin{split} e^1 &= A_1 \left( \eta_1 + \tilde{\eta}_1 \right), & e^4 &= B_1 \left( \eta_1 - \tilde{\eta}_1 \right), \\ e^2 &= A_2 \left( \eta_2 + \tilde{\eta}_2 \right), & e^5 &= B_2 \left( \eta_2 - \tilde{\eta}_2 \right), \\ e^3 &= A_3 \left( \eta_3 + \tilde{\eta}_3 \right), & e^6 &= B_3 \left( \eta_3 - \tilde{\eta}_3 \right), \\ e^7 &= dt, \end{split}$$

then we can define the following three-form:

# $G_2$ structure on the cone over $S^3 \times S^3$

$$\Phi = e^{564} + e^{527} + e^{513} + e^{621} + e^{637} + e^{432} + e^{417},$$

where  $e^{ijk} = e^i \wedge e^j \wedge e^k$ . Form  $\Phi$  defines  $G_2$  structure on  $\overline{M}$  and we have first oder equations which guarantee parallelism of this form:

$$d\Phi = 0, d \star \Phi = 0. \tag{1}$$

We consider particular case  $A_2 = A_3$ ,  $B_2 = B_3$ .



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Equations (1) can be write down explicitly:

$$\frac{dA_{1}}{dt} = \frac{1}{2} \left( \frac{A_{1}^{2}}{A_{2}^{2}} - \frac{A_{1}^{2}}{B_{2}^{2}} \right) 
\frac{dA_{2}}{dt} = \frac{1}{2} \left( \frac{B_{2}^{2} - A_{2}^{2} + B_{1}^{2}}{B_{1}B_{2}} - \frac{A_{1}}{A_{2}} \right) 
\frac{dB_{1}}{dt} = \frac{A_{2}^{2} + B_{2}^{2} - B_{1}^{2}}{A_{2}B_{2}} 
\frac{dB_{2}}{dt} = \frac{1}{2} \left( \frac{A_{2}^{2} - B_{2}^{2} + B_{1}^{2}}{A_{2}B_{1}} + \frac{A_{1}}{B_{2}} \right)$$
(2)

Now if we want to obtain smooth Riemannian manifold with regular metric we have to resolve cone singularity. We have two ways to produce this.

• Type 1:

$$A_1(0) = A_2(0) = 0,$$
  
 $B_1(0) = B_2(0) \neq 0,$   
 $|A'_1(0)| = |A'_2(0)| = \frac{1}{2},$   
 $B'_1(0) = B'_2(0) = 0.$ 

In this case  $\overline{M}$  is diffeomorphic to  $S^3 \times \mathbb{R}^4$ .

• Type 2:

$$B_1(0) = 0, |B'_1(0)| = 2,$$
  
 $A_2(0) = B_2(0) \neq 0, A'_2(0) = -B'_2(0),$   
 $A_1(0) \neq 0, A'_1(0) = 0.$ 

In this case we obtain manifold  $\overline{M}$  which is diffeomorphic to  $S^3 \times H^4$ , where  $H^4$  is the forth tensor power of canonical complex line bundle H over two-sphere  $S^2$ .

I will discuss in my talk only Type 2 of resolving singularity.

### **ALC** metrics

Riemannian metric  $d\bar{s}^2$  is called asymptotically locally conical off there exist affine over t functions  $\tilde{A}_i(t)$ ,  $\tilde{B}_i(t)$  such that

$$\left|1-rac{A_i}{ ilde{A}_i}
ight| o 0,\; \left|1-rac{B_i}{ ilde{B}_i}
ight| o 0,\;$$
 при  $t o \infty$ 

The metric which is defined by such functions  $\tilde{A}_i(t)$ ,  $\tilde{B}_i(t)$  is called locally conical.

Let  $R(t) = (A_1(t), A_2(t), B_1(t), B_2(t)) \in \mathbb{R}^4$  and  $V : \mathbb{R}^4 \to \mathbb{R}^4$  is the right side of system (2). Then our system of differential equations has form

$$\frac{dR}{dt} = V(R).$$

We see that V is invariant with respect to homotheties of  $\mathbb{R}^4$  so we can put R(t) = f(t)S(t), where

$$|S(t)| = 1, f(t) = |R(t)|,$$
  
 $S(t) = (\alpha_1(t), \alpha_2(t), \alpha_3(t), \alpha_4(t)).$ 

In such way our system (2) splits into «radial» and «tangential» parts:

$$\frac{dS}{du} = V(S) - \langle V(S), S \rangle S = W(S), 
\frac{1}{f} \frac{df}{du} = \langle V(S), S \rangle, 
dt = fdu.$$
(3)

Consequently we need firstly to solve autonomous system (3) on three-sphere  $S^3 = \{(\alpha_1, \alpha_2, \alpha_3, \alpha_4) | \sum_{i=1}^4 \alpha_i^2 = 1 \}$  and then solutions of (2) can be found by integrating last two equations.

## Лемма

Stationary solutions of (3) on  $S^3$  correspond to zeros of vector field W in  $S^3 \subset \mathbb{R}^4$  with respect to symmetries of our system:

$$\left(\frac{1}{2\sqrt{2}},\frac{1}{2\sqrt{2}},\frac{\sqrt{3}}{2\sqrt{2}},\frac{\sqrt{3}}{2\sqrt{2}}\right),\ \left(0,\frac{\sqrt{3}}{\sqrt{10}},\frac{\sqrt{2}}{\sqrt{5}},\frac{\sqrt{3}}{\sqrt{10}}\right).$$

## Lemma

Stationary solutions of (3) correspond to locally conical metrics on  $\overline{M}$  and trajectories of (3) which converges to stationary solutions correspond to asymptotically locally conical metrics on  $\overline{M}$ .

Solutions of system (2) with initial data of Type 2 correspond to solutions of autonomous system (3) with initial point  $S_0 = (\mu, \lambda, 0, \lambda)$ , where  $2\lambda^2 + \mu^2 = 1$  (with respect to symmetries of our system). Remark that right hand of system (2) has singularity at point  $S_0$ , so classical Cauchy problem does not work here.

#### Lemma

For any above considered point  $S_0 = (\mu, \lambda, 0, \lambda)$  there exists unique smooth trajectory of system (3) escaping point  $S_0$ .

#### Lemma

The trajectory of system (3) defined by initial point  $S_0 = (\mu, \lambda, 0, \lambda)$ ,  $\lambda, \mu > 0$ ,  $2\lambda^2 + \mu^2 = 1$ , converges to stationary point  $S_{\infty} = \left(0, \frac{\sqrt{3}}{\sqrt{10}}, \frac{\sqrt{2}}{\sqrt{5}}, \frac{\sqrt{3}}{\sqrt{10}}\right)$  when  $u \to \infty$ .

So we obtain the following:

# Theorem (B.-Bogoyavlenskaya)

There exist one-parameter family of pairwise nonhomothetic complete Riemannian metrics of form  $d\bar{s}^2$  with holonomy group  $G_2$  over  $H^4\times S^3$ . More over these metrics can be parametrize by initial data set  $(A_1(0), A_2(0), B_1(0), B_2(0)) = (\mu, \lambda, 0, \lambda)$ , where  $\lambda, \mu > 0$  and  $\mu^2 + \lambda^2 = 1$ . When  $t \to \infty$  the metrics of this family are asymptotically isometric to Cartesian product  $S^1 \times C(S^2 \times S^3)$ , where  $C(S^2 \times S^3)$  is cone over spheres product.



THANK YOU FOR YOUR ATTENTION!