

Gradient methods for convex problems with stochastic inexact oracle

Pavel Dvurechensky¹, Alexander Gasnikov²

¹ MIPT/PreMoLab, IITP RAS; ² MIPT/PreMoLab

27.06.14

Traditional Mathematical School „Control, Information and Optimization“
Moscow

Outline

- 1 Introduction to convex optimization

Outline

- 1 Introduction to convex optimization
- 2 Concept of (δ, L) -oracle

Outline

- 1 Introduction to convex optimization
- 2 Concept of (δ, L) -oracle
- 3 Stochastic inexact oracle

Outline

- 1 Introduction to convex optimization
- 2 Concept of (δ, L) -oracle
- 3 Stochastic inexact oracle
- 4 Stochastic Intermediate Gradient Method

Outline

- 1 Introduction to convex optimization
- 2 Concept of (δ, L) -oracle
- 3 Stochastic inexact oracle
- 4 Stochastic Intermediate Gradient Method

Optimization areas (due to Nemirovski, Yudin, Nesterov), n is the space dimension.

- ① **Small-size problems**, n^4 operations per iteration is ok, ellipsoid methods: $N(\varepsilon) \approx O\left(n^5 \ln\left(\frac{1}{\varepsilon}\right)\right)$.

Optimization areas (due to Nemirovski, Yudin, Nesterov), n is the space dimension.

- 1 **Small-size problems**, n^4 operations per iteration is ok, ellipsoid methods: $N(\varepsilon) \approx O\left(n^5 \ln\left(\frac{1}{\varepsilon}\right)\right)$.
- 2 **Medium-size problems**, n^3 operations per iteration is ok, interior point methods (based on Newton method): $N(\varepsilon) \approx O\left(n^{7/2} \ln\left(\frac{n}{\varepsilon}\right)\right)$.

Optimization areas (due to Nemirovski, Yudin, Nesterov), n is the space dimension.

- ① **Small-size problems**, n^4 operations per iteration is ok, ellipsoid methods: $N(\varepsilon) \approx O\left(n^5 \ln\left(\frac{1}{\varepsilon}\right)\right)$.
- ② **Medium-size problems**, n^3 operations per iteration is ok, interior point methods (based on Newton method): $N(\varepsilon) \approx O\left(n^{7/2} \ln\left(\frac{n}{\varepsilon}\right)\right)$.
- ③ **Large-scale problems**, n^2 operations per iteration is ok, first order methods (gradient type): $N(\varepsilon) \approx O\left(\frac{n^2}{\varepsilon}\right)$.

Optimization areas (due to Nemirovski, Yudin, Nesterov), n is the space dimension.

- 1 **Small-size problems**, n^4 operations per iteration is ok, ellipsoid methods: $N(\varepsilon) \approx O\left(n^5 \ln\left(\frac{1}{\varepsilon}\right)\right)$.
- 2 **Medium-size problems**, n^3 operations per iteration is ok, interior point methods (based on Newton method): $N(\varepsilon) \approx O\left(n^{7/2} \ln\left(\frac{n}{\varepsilon}\right)\right)$.
- 3 **Large-scale problems**, n^2 operations per iteration is ok, first order methods (gradient type): $N(\varepsilon) \approx O\left(\frac{n^2}{\varepsilon}\right)$.
- 4 **Huge-scale problems**, n or $\ln n$ operations per iteration is ok, coordinate descent schemes, sparsity, randomization. $N(\varepsilon) \approx O\left(\frac{n}{\varepsilon^2}\right)$.

Notation

- ① E – finite-dimensional real vector space, E^* – its dual.

Notation

- 1 E – finite-dimensional real vector space, E^* – its dual.
- 2 The value of linear function $g \in E^*$ at $x \in E$ is $\langle g, x \rangle$.

Notation

- ① E – finite-dimensional real vector space, E^* – its dual.
- ② The value of linear function $g \in E^*$ at $x \in E$ is $\langle g, x \rangle$.
- ③ $\|\cdot\|$ – some norm on E , $\|\cdot\|_*$ is its dual.

Notation

- ① E – finite-dimensional real vector space, E^* – its dual.
- ② The value of linear function $g \in E^*$ at $x \in E$ is $\langle g, x \rangle$.
- ③ $\|\cdot\|$ – some norm on E , $\|\cdot\|_*$ is its dual.
- ④ $d(x)$ – [prox-function](#), differentiable and strongly convex with the parameter 1 on Q with respect to $\|\cdot\|$: $d(x) \geq \frac{1}{2}\|x - x_0\|^2, \forall x \in Q$.

Notation

- ① E – finite-dimensional real vector space, E^* – its dual.
- ② The value of linear function $g \in E^*$ at $x \in E$ is $\langle g, x \rangle$.
- ③ $\|\cdot\|$ – some norm on E , $\|\cdot\|_*$ is its dual.
- ④ $d(x)$ – [prox-function](#), differentiable and strongly convex with the parameter 1 on Q with respect to $\|\cdot\|$: $d(x) \geq \frac{1}{2}\|x - x_0\|^2$, $\forall x \in Q$.
Examples:

- ① Euclidean distance: $Q = \mathbb{R}^n$, $\|\cdot\| = \|\cdot\|_2$, $d(x) = \frac{1}{2}\|x\|_2^2$, $x_0 = 0$.

Notation

- ① E – finite-dimensional real vector space, E^* – its dual.
- ② The value of linear function $g \in E^*$ at $x \in E$ is $\langle g, x \rangle$.
- ③ $\|\cdot\|$ – some norm on E , $\|\cdot\|_*$ is its dual.
- ④ $d(x)$ – **prox-function**, differentiable and strongly convex with the parameter 1 on Q with respect to $\|\cdot\|$: $d(x) \geq \frac{1}{2}\|x - x_0\|^2$, $\forall x \in Q$.
Examples:

- ① Euclidean distance: $Q = \mathbb{R}^n$, $\|\cdot\| = \|\cdot\|_2$, $d(x) = \frac{1}{2}\|x\|_2^2$, $x_0 = 0$.
- ② Entropy $Q = \{x \in \mathbb{R}^n : x_i \geq 0, \sum_{i=1}^n x_i = 1\}$, $\|\cdot\| = \|\cdot\|_1$,
 $d(x) = \ln n + \sum_{i=1}^n x_i \ln x_i$, $x_0 = (\frac{1}{n}, \dots, \frac{1}{n})^T$.

Notation

- ① E – finite-dimensional real vector space, E^* – its dual.
- ② The value of linear function $g \in E^*$ at $x \in E$ is $\langle g, x \rangle$.
- ③ $\|\cdot\|$ – some norm on E , $\|\cdot\|_*$ is its dual.
- ④ $d(x)$ – **prox-function**, differentiable and strongly convex with the parameter 1 on Q with respect to $\|\cdot\|$: $d(x) \geq \frac{1}{2}\|x - x_0\|^2$, $\forall x \in Q$.

Examples:

- ① Euclidean distance: $Q = \mathbb{R}^n$, $\|\cdot\| = \|\cdot\|_2$, $d(x) = \frac{1}{2}\|x\|_2^2$, $x_0 = 0$.
- ② Entropy $Q = \{x \in \mathbb{R}^n : x_i \geq 0, \sum_{i=1}^n x_i = 1\}$, $\|\cdot\| = \|\cdot\|_1$,
$$d(x) = \ln n + \sum_{i=1}^n x_i \ln x_i, \quad x_0 = \left(\frac{1}{n}, \dots, \frac{1}{n}\right)^T.$$
- ⑤ **Bregman distance**: $V(x, z) = d(x) - d(z) - \langle \nabla d(z), x - z \rangle$.

Notation

- ① E – finite-dimensional real vector space, E^* – its dual.
- ② The value of linear function $g \in E^*$ at $x \in E$ is $\langle g, x \rangle$.
- ③ $\|\cdot\|$ – some norm on E , $\|\cdot\|_*$ is its dual.
- ④ $d(x)$ – **prox-function**, differentiable and strongly convex with the parameter 1 on Q with respect to $\|\cdot\|$: $d(x) \geq \frac{1}{2}\|x - x_0\|^2$, $\forall x \in Q$.
Examples:

- ① Euclidean distance: $Q = \mathbb{R}^n$, $\|\cdot\| = \|\cdot\|_2$, $d(x) = \frac{1}{2}\|x\|_2^2$, $x_0 = 0$.
- ② Entropy $Q = \{x \in \mathbb{R}^n : x_i \geq 0, \sum_{i=1}^n x_i = 1\}$, $\|\cdot\| = \|\cdot\|_1$,
 $d(x) = \ln n + \sum_{i=1}^n x_i \ln x_i$, $x_0 = (\frac{1}{n}, \dots, \frac{1}{n})^T$.
- ⑤ **Bregman distance**: $V(x, z) = d(x) - d(z) - \langle \nabla d(z), x - z \rangle$.
 - ① Euclidean distance: $V(x, z) = \frac{1}{2}\|x - z\|_2^2$.

Notation

- ① E – finite-dimensional real vector space, E^* – its dual.
- ② The value of linear function $g \in E^*$ at $x \in E$ is $\langle g, x \rangle$.
- ③ $\|\cdot\|$ – some norm on E , $\|\cdot\|_*$ is its dual.
- ④ $d(x)$ – **prox-function**, differentiable and strongly convex with the parameter 1 on Q with respect to $\|\cdot\|$: $d(x) \geq \frac{1}{2}\|x - x_0\|^2$, $\forall x \in Q$.
Examples:

- ① Euclidean distance: $Q = \mathbb{R}^n$, $\|\cdot\| = \|\cdot\|_2$, $d(x) = \frac{1}{2}\|x\|_2^2$, $x_0 = 0$.
- ② Entropy $Q = \{x \in \mathbb{R}^n : x_i \geq 0, \sum_{i=1}^n x_i = 1\}$, $\|\cdot\| = \|\cdot\|_1$,
 $d(x) = \ln n + \sum_{i=1}^n x_i \ln x_i$, $x_0 = (\frac{1}{n}, \dots, \frac{1}{n})^T$.
- ⑤ **Bregman distance**: $V(x, z) = d(x) - d(z) - \langle \nabla d(z), x - z \rangle$.
 - ① Euclidean distance: $V(x, z) = \frac{1}{2}\|x - z\|_2^2$.
 - ② Kullback–Leibler divergence: $V(x, z) = \sum_{i=1}^n x_i \ln \frac{x_i}{z_i}$.

Classes of convex functions: convexity

1 Convex functions:

$$f(y) \geq f(x) + \langle g(x), y - x \rangle, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

Classes of convex functions: convexity

1 Convex functions:

$$f(y) \geq f(x) + \langle g(x), y - x \rangle, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

2 Strongly convex functions:

$$f(y) \geq f(x) + \langle g(x), y - x \rangle + \frac{\mu}{2} \|x - y\|^2, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

Classes of convex functions: convexity

1 Convex functions:

$$f(y) \geq f(x) + \langle g(x), y - x \rangle, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

2 Strongly convex functions:

$$f(y) \geq f(x) + \langle g(x), y - x \rangle + \frac{\mu}{2} \|x - y\|^2, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

3 Uniformly convex functions:

$$f(y) \geq f(x) + \langle g(x), y - x \rangle + \frac{\kappa}{2} \|x - y\|^\rho, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x),$$

where $\rho \geq 2$.

Classes of convex functions: smoothness

- 1 Bounded subgradient: $\|g(x)\|_* \leq M, \forall x \in Q, \forall g(x) \in \partial f(x)$.
Then $\|g(x) - g(y)\|_* \leq 2M$

Classes of convex functions: smoothness

- 1 Bounded subgradient: $\|g(x)\|_* \leq M, \forall x \in Q, \forall g(x) \in \partial f(x)$.

Then $\|g(x) - g(y)\|_* \leq 2M$ and

$$f(y) \leq f(x) + \langle g(x), y - x \rangle + 2M\|x - y\|, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

Classes of convex functions: smoothness

- ① Bounded subgradient: $\|g(x)\|_* \leq M, \forall x \in Q, \forall g(x) \in \partial f(x)$.

Then $\|g(x) - g(y)\|_* \leq 2M$ and

$$f(y) \leq f(x) + \langle g(x), y - x \rangle + 2M\|x - y\|, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

- ② Lipschitz continuous gradient: $\|\nabla f(x) - \nabla f(y)\|_* \leq L\|x - y\|$.

Classes of convex functions: smoothness

- ① Bounded subgradient: $\|g(x)\|_* \leq M, \forall x \in Q, \forall g(x) \in \partial f(x)$.

Then $\|g(x) - g(y)\|_* \leq 2M$ and

$$f(y) \leq f(x) + \langle g(x), y - x \rangle + 2M\|x - y\|, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

- ② Lipschitz continuous gradient: $\|\nabla f(x) - \nabla f(y)\|_* \leq L\|x - y\|$.

Then

$$f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + \frac{L}{2}\|x - y\|^2, \quad \forall x, y \in Q.$$

Classes of convex functions: smoothness

- ① Bounded subgradient: $\|g(x)\|_* \leq M, \forall x \in Q, \forall g(x) \in \partial f(x)$.

Then $\|g(x) - g(y)\|_* \leq 2M$ and

$$f(y) \leq f(x) + \langle g(x), y - x \rangle + 2M\|x - y\|, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

- ② Lipschitz continuous gradient: $\|\nabla f(x) - \nabla f(y)\|_* \leq L\|x - y\|$.

Then

$$f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + \frac{L}{2}\|x - y\|^2, \quad \forall x, y \in Q.$$

- ③ Intermediate level of smoothness: for some $\nu \in [0, 1]$

$$\|g(x) - g(y)\|_* \leq L_\nu\|x - y\|^\nu, \quad \forall x \in Q, \forall g(x) \in \partial f(x).$$

Classes of convex functions: smoothness

- ① Bounded subgradient: $\|g(x)\|_* \leq M, \forall x \in Q, \forall g(x) \in \partial f(x)$.

Then $\|g(x) - g(y)\|_* \leq 2M$ and

$$f(y) \leq f(x) + \langle g(x), y - x \rangle + 2M\|x - y\|, \quad \forall x, y \in Q, \forall g(x) \in \partial f(x).$$

- ② Lipschitz continuous gradient: $\|\nabla f(x) - \nabla f(y)\|_* \leq L\|x - y\|$.

Then

$$f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + \frac{L}{2}\|x - y\|^2, \quad \forall x, y \in Q.$$

- ③ Intermediate level of smoothness: for some $\nu \in [0, 1]$
 $\|g(x) - g(y)\|_* \leq L_\nu\|x - y\|^\nu, \forall x \in Q, \forall g(x) \in \partial f(x)$.

Then

$$f(y) \leq f(x) + \langle g(x), y - x \rangle + \frac{L_\nu}{1 + \nu}\|x - y\|^{1 + \nu}, \quad \forall x, y \in Q, \forall g(x) \in \partial f$$

Problem formulation: simple case

Consider the problem

$$\min_{x \in Q} f(x),$$

where

Problem formulation: simple case

Consider the problem

$$\min_{x \in Q} f(x),$$

where

- 1 $Q \subset E$ is a closed convex set,

Problem formulation: simple case

Consider the problem

$$\min_{x \in Q} f(x),$$

where

- 1 $Q \subset E$ is a closed convex set,
- 2 $f(x)$ is either convex or strongly convex, either with bounded subgradient or with Lipschitz continuous gradient.

Problem formulation: simple case

Consider the problem

$$\min_{x \in Q} f(x),$$

where

- 1 $Q \subset E$ is a closed convex set,
- 2 $f(x)$ is either convex or strongly convex, either with bounded subgradient or with Lipschitz continuous gradient.
- 3 We know all the constants M, L, μ .

Problem formulation: simple case

Consider the problem

$$\min_{x \in Q} f(x),$$

where

- 1 $Q \subset E$ is a closed convex set,
- 2 $f(x)$ is either convex or strongly convex, either with bounded subgradient or with Lipschitz continuous gradient.
- 3 We know all the constants M, L, μ .

The method usually constructs sequences

- 1 x_k – points where the (sub)gradients are calculated.

Problem formulation: simple case

Consider the problem

$$\min_{x \in Q} f(x),$$

where

- 1 $Q \subset E$ is a closed convex set,
- 2 $f(x)$ is either convex or strongly convex, either with bounded subgradient or with Lipschitz continuous gradient.
- 3 We know all the constants M, L, μ .

The method usually constructs sequences

- 1 x_k – points where the (sub)gradients are calculated.
- 2 y_k – approximate solution.

Problem formulation: simple case

Consider the problem

$$\min_{x \in Q} f(x),$$

where

- 1 $Q \subset E$ is a closed convex set,
- 2 $f(x)$ is either convex or strongly convex, either with bounded subgradient or with Lipschitz continuous gradient.
- 3 We know all the constants M, L, μ .

The method usually constructs sequences

- 1 x_k – points where the (sub)gradients are calculated.
- 2 y_k – approximate solution.
- 3 $\Psi_k(x)$ – model of the function which approximates $f(x)$ in some sense.

Lower complexity bounds

We assume a black-box first order oracle $(f(x), g(x))$. $R^2 \stackrel{\text{def}}{\geq} 2d(x^*)$.

Lower complexity bounds

We assume a black-box first order oracle $(f(x), g(x))$. $R^2 \stackrel{\text{def}}{\geq} 2d(x^*)$.
The best we can expect from a method in this case.

① **Nonsmooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{MR}{\sqrt{k}}\right)$,

$$N(\varepsilon) = \Omega\left(\frac{M^2 R^2}{\varepsilon^2}\right).$$

Lower complexity bounds

We assume a black-box first order oracle $(f(x), g(x))$. $R^2 \stackrel{\text{def}}{\geq} 2d(x^*)$.
The best we can expect from a method in this case.

① **Nonsmooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{MR}{\sqrt{k}}\right)$,

$$N(\varepsilon) = \Omega\left(\frac{M^2 R^2}{\varepsilon^2}\right).$$

② **Nonsmooth Strongly Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{M}{\mu k}\right)$,

$$N(\varepsilon) = \Omega\left(\frac{M}{\mu \varepsilon}\right).$$

Lower complexity bounds

We assume a black-box first order oracle $(f(x), g(x))$. $R^2 \stackrel{\text{def}}{\geq} 2d(x^*)$.
The best we can expect from a method in this case.

① **Nonsmooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{MR}{\sqrt{k}}\right)$,

$$N(\varepsilon) = \Omega\left(\frac{M^2 R^2}{\varepsilon^2}\right).$$

② **Nonsmooth Strongly Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{M}{\mu k}\right)$,

$$N(\varepsilon) = \Omega\left(\frac{M}{\mu \varepsilon}\right).$$

③ **Smooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{LR^2}{k^2}\right)$, $N(\varepsilon) = \Omega\left(\sqrt{\frac{LR^2}{\varepsilon}}\right)$.

Lower complexity bounds

We assume a black-box first order oracle $(f(x), g(x))$. $R^2 \stackrel{\text{def}}{\geq} 2d(x^*)$.
The best we can expect from a method in this case.

① **Nonsmooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{MR}{\sqrt{k}}\right),$

$$N(\varepsilon) = \Omega\left(\frac{M^2 R^2}{\varepsilon^2}\right).$$

② **Nonsmooth Strongly Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{M}{\mu k}\right),$

$$N(\varepsilon) = \Omega\left(\frac{M}{\mu \varepsilon}\right).$$

③ **Smooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{LR^2}{k^2}\right), N(\varepsilon) = \Omega\left(\sqrt{\frac{LR^2}{\varepsilon}}\right).$

④ **Smooth Strongly Convex Problem:**

$$f(y_k) - f^* \leq O\left(\mu R^2 \exp\left(-k\sqrt{\frac{\mu}{L}}\right)\right), N(\varepsilon) = \Omega\left(\sqrt{\frac{L}{\mu}} \ln\left(\frac{\mu R^2}{\varepsilon}\right)\right).$$

Lower complexity bounds

We assume a black-box first order oracle $(f(x), g(x))$. $R^2 \stackrel{\text{def}}{\geq} 2d(x^*)$.
The best we can expect from a method in this case.

① **Nonsmooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{MR}{\sqrt{k}}\right),$

$$N(\varepsilon) = \Omega\left(\frac{M^2 R^2}{\varepsilon^2}\right).$$

② **Nonsmooth Strongly Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{M}{\mu k}\right),$

$$N(\varepsilon) = \Omega\left(\frac{M}{\mu \varepsilon}\right).$$

③ **Smooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{LR^2}{k^2}\right), N(\varepsilon) = \Omega\left(\sqrt{\frac{LR^2}{\varepsilon}}\right).$

④ **Smooth Strongly Convex Problem:**

$$f(y_k) - f^* \leq O\left(\mu R^2 \exp\left(-k\sqrt{\frac{\mu}{L}}\right)\right), N(\varepsilon) = \Omega\left(\sqrt{\frac{L}{\mu}} \ln\left(\frac{\mu R^2}{\varepsilon}\right)\right).$$

Note: In **stochastic optimization** the best we can expect from a method in this case

① **Nonsmooth or Smooth Convex Problem:** $\mathbb{E}f(y_k) - f^* \leq O\left(\frac{1}{\sqrt{k}}\right).$

Lower complexity bounds

We assume a black-box first order oracle $(f(x), g(x))$. $R^2 \stackrel{\text{def}}{\geq} 2d(x^*)$.
The best we can expect from a method in this case.

① **Nonsmooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{MR}{\sqrt{k}}\right),$

$$N(\varepsilon) = \Omega\left(\frac{M^2 R^2}{\varepsilon^2}\right).$$

② **Nonsmooth Strongly Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{M}{\mu k}\right),$

$$N(\varepsilon) = \Omega\left(\frac{M}{\mu \varepsilon}\right).$$

③ **Smooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{LR^2}{k^2}\right), N(\varepsilon) = \Omega\left(\sqrt{\frac{LR^2}{\varepsilon}}\right).$

④ **Smooth Strongly Convex Problem:**

$$f(y_k) - f^* \leq O\left(\mu R^2 \exp\left(-k\sqrt{\frac{\mu}{L}}\right)\right), N(\varepsilon) = \Omega\left(\sqrt{\frac{L}{\mu}} \ln\left(\frac{\mu R^2}{\varepsilon}\right)\right).$$

Note: In **stochastic optimization** the best we can expect from a method in this case

① **Nonsmooth or Smooth Convex Problem:** $\mathbb{E}f(y_k) - f^* \leq O\left(\frac{1}{\sqrt{k}}\right).$

② **Nonsmooth or Smooth Strongly Convex Problem:**

$$\mathbb{E}f(y_k) - f^* \leq O\left(\frac{1}{k}\right).$$

Lower complexity bounds

We assume a black-box first order oracle $(f(x), g(x))$. $R^2 \stackrel{\text{def}}{\geq} 2d(x^*)$.
The best we can expect from a method in this case.

① **Nonsmooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{MR}{\sqrt{k}}\right)$,

$$N(\varepsilon) = \Omega\left(\frac{M^2 R^2}{\varepsilon^2}\right).$$

② **Nonsmooth Strongly Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{M}{\mu k}\right)$,

$$N(\varepsilon) = \Omega\left(\frac{M}{\mu \varepsilon}\right).$$

③ **Smooth Convex Problem:** $f(y_k) - f^* \leq O\left(\frac{LR^2}{k^2}\right)$, $N(\varepsilon) = \Omega\left(\sqrt{\frac{LR^2}{\varepsilon}}\right)$.

④ **Smooth Strongly Convex Problem:**

$$f(y_k) - f^* \leq O\left(\mu R^2 \exp\left(-k\sqrt{\frac{\mu}{L}}\right)\right), \quad N(\varepsilon) = \Omega\left(\sqrt{\frac{L}{\mu}} \ln\left(\frac{\mu R^2}{\varepsilon}\right)\right).$$

Note: In **stochastic optimization** the best we can expect from a method in this case

① **Nonsmooth or Smooth Convex Problem:** $\mathbb{E}f(y_k) - f^* \leq O\left(\frac{1}{\sqrt{k}}\right)$.

② **Nonsmooth or Smooth Strongly Convex Problem:**

$$\mathbb{E}f(y_k) - f^* \leq O\left(\frac{1}{k}\right).$$

Below we consider mostly the smooth case.

Simple Primal Gradient Method

$f(x)$ is smooth.

Simple Primal Gradient Method

$f(x)$ is smooth.

Method:

- 1 Choose $x_0 \in Q$.

Simple Primal Gradient Method

$f(x)$ is smooth.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{f(x_k) + \langle \nabla f(x_k), x - x_k \rangle + \frac{L}{2} \|x - x_k\|_2^2\} = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right).$

Simple Primal Gradient Method

$f(x)$ is smooth.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{f(x_k) + \langle \nabla f(x_k), x - x_k \rangle + \frac{L}{2} \|x - x_k\|_2^2\} = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.

Output:

$$y_k = x_k, \quad y_k = \frac{\sum_{i=1}^k x_i}{k} \text{ (more robust)}, \quad y_k = \arg \min_{i=1, \dots, k} f(x_i) = x_k.$$

Simple Primal Gradient Method

$f(x)$ is smooth.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{f(x_k) + \langle \nabla f(x_k), x - x_k \rangle + \frac{L}{2} \|x - x_k\|_2^2\} = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.

Output:

$y_k = x_k$, $y_k = \frac{\sum_{i=1}^k x_i}{k}$ (more robust), $y_k = \arg \min_{i=1, \dots, k} f(x_i) = x_k$.

Rate of convergence:

- 1 Convex case: $f(y_k) - f^* \leq \frac{L \|x_0 - x^*\|_2^2}{2k}$.

Simple Primal Gradient Method

$f(x)$ is smooth.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{f(x_k) + \langle \nabla f(x_k), x - x_k \rangle + \frac{L}{2} \|x - x_k\|_2^2\} = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.

Output:

$y_k = x_k$, $y_k = \frac{\sum_{i=1}^k x_i}{k}$ (more robust), $y_k = \arg \min_{i=1, \dots, k} f(x_i) = x_k$.

Rate of convergence:

- 1 Convex case: $f(y_k) - f^* \leq \frac{L \|x_0 - x^*\|_2^2}{2k}$.
- 2 Strongly convex case ($y_k = x_k$): $f(y_k) - f^* \leq \frac{L \|x_0 - x^*\|_2^2}{2} \exp \left(-k \frac{\mu}{L} \right)$.

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$
- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2]$

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$
- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2] \leq \beta_k d(x) + f(x) \sum_{i=0}^k \alpha_i$ - model of the objective function.

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$
- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2] \leq \beta_k d(x) + f(x) \sum_{i=0}^k \alpha_i$ - model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value. $A_k = \sum_{i=0}^k \alpha_i$.

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$
- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2] \leq \beta_k d(x) + f(x) \sum_{i=0}^k \alpha_i$ - model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value. $A_k = \sum_{i=0}^k \alpha_i$.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^*, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x), \quad \forall x \in Q.$$

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$
- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2] \leq \beta_k d(x) + f(x) \sum_{i=0}^k \alpha_i$ - model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value. $A_k = \sum_{i=0}^k \alpha_i$.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^*, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x), \quad \forall x \in Q.$$

Then

$$A_k f(y_k) \leq \Psi_k^* \leq$$

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$
- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2] \leq \beta_k d(x) + f(x) \sum_{i=0}^k \alpha_i$ - model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value. $A_k = \sum_{i=0}^k \alpha_i$.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^*, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x), \quad \forall x \in Q.$$

Then

$$A_k f(y_k) \leq \Psi_k^* \leq \Psi_k(x^*) \leq$$

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$
- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2] \leq \beta_k d(x) + f(x) \sum_{i=0}^k \alpha_i$ - model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value. $A_k = \sum_{i=0}^k \alpha_i$.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^*, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x), \quad \forall x \in Q.$$

Then

$$A_k f(y_k) \leq \Psi_k^* \leq \Psi_k(x^*) \leq A_k f^* + \beta_k d(x^*),$$

and

Estimating functions

Assume that $\mu \geq 0$ and we have sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$.

- $d(x) = \frac{1}{2} \|x - x_0\|_2^2$
- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2] \leq \beta_k d(x) + f(x) \sum_{i=0}^k \alpha_i$ - model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value. $A_k = \sum_{i=0}^k \alpha_i$.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^*, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x), \quad \forall x \in Q.$$

Then

$$A_k f(y_k) \leq \Psi_k^* \leq \Psi_k(x^*) \leq A_k f^* + \beta_k d(x^*),$$

and

$$f(y_k) - f^* \leq \frac{\beta_k}{A_k} d(x^*),$$

which can give us the rate of convergence.

Dual Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = \frac{L}{L-\mu}$, $A_k = \sum_{i=0}^k \alpha_i$, $\alpha_{k+1} = \frac{A_k \mu + L}{L - \mu}$,
 $\beta_k = L$.

Dual Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = \frac{L}{L-\mu}$, $A_k = \sum_{i=0}^k \alpha_i$, $\alpha_{k+1} = \frac{A_k \mu + L}{L - \mu}$,
 $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.

Dual Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = \frac{L}{L-\mu}$, $A_k = \sum_{i=0}^k \alpha_i$, $\alpha_{k+1} = \frac{A_k \mu + L}{L - \mu}$,
 $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.

Dual Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = \frac{L}{L-\mu}$, $A_k = \sum_{i=0}^k \alpha_i$, $\alpha_{k+1} = \frac{A_k \mu + L}{L - \mu}$,
 $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i \left[f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2 \right] \right\}$.

Dual Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = \frac{L}{L-\mu}$, $A_k = \sum_{i=0}^k \alpha_i$, $\alpha_{k+1} = \frac{A_k\mu + L}{L-\mu}$, $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i \left[f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2 \right] \right\}$.

Output: $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$.

Dual Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = \frac{L}{L-\mu}$, $A_k = \sum_{i=0}^k \alpha_i$, $\alpha_{k+1} = \frac{A_k\mu+L}{L-\mu}$, $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i \left[f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2 \right] \right\}$.

Output: $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$.

Rate of convergence:

- 1 Convex case: $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2(k+1)}$.

Dual Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = \frac{L}{L-\mu}$, $A_k = \sum_{i=0}^k \alpha_i$, $\alpha_{k+1} = \frac{A_k\mu + L}{L-\mu}$, $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i \left[f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2 \right] \right\}$.

Output: $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$.

Rate of convergence:

- 1 Convex case: $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2(k+1)}$.
- 2 Strongly convex case: $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2} \exp \left(-(k+1)\frac{\mu}{L} \right)$.

Fast Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = 1$, $A_k = \sum_{i=0}^k \alpha_i$, $L + \mu A_k = \frac{L\alpha_{k+1}^2}{A_{k+1}}$,
 $\beta_k = L$.

Fast Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = 1$, $A_k = \sum_{i=0}^k \alpha_i$, $L + \mu A_k = \frac{L\alpha_{k+1}^2}{A_{k+1}}$,
 $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.

Fast Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = 1$, $A_k = \sum_{i=0}^k \alpha_i$, $L + \mu A_k = \frac{L\alpha_{k+1}^2}{A_{k+1}}$,
 $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.

Fast Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = 1$, $A_k = \sum_{i=0}^k \alpha_i$, $L + \mu A_k = \frac{L\alpha_{k+1}^2}{A_{k+1}}$,
 $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i \left[f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2 \right] \right\}$.

Fast Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = 1$, $A_k = \sum_{i=0}^k \alpha_i$, $L + \mu A_k = \frac{L\alpha_{k+1}^2}{A_{k+1}}$,
 $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i \left[f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2 \right] \right\}$.
- 4 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$, $\tau_k = \frac{\alpha_{k+1}}{A_{k+1}}$.

Fast Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = 1$, $A_k = \sum_{i=0}^k \alpha_i$, $L + \mu A_k = \frac{L\alpha_{k+1}^2}{A_{k+1}}$, $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i \left[f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2 \right] \right\}$.
- 4 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$, $\tau_k = \frac{\alpha_{k+1}}{A_{k+1}}$.

Rate of convergence:

- 1 Convex case: $f(y_k) - f^* \leq \frac{4L\|x_0 - x^*\|_2^2}{k^2}$.

Fast Gradient Method (first by Yu. Nesterov)

$f(x)$ is smooth.

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 = 1$, $A_k = \sum_{i=0}^k \alpha_i$, $L + \mu A_k = \frac{L\alpha_{k+1}^2}{A_{k+1}}$, $\beta_k = L$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{L} \nabla f(x_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i \left[f(x_i) + \langle \nabla f(x)(x_i), x - x_i \rangle + \frac{\mu}{2} \|x - x_i\|_2^2 \right] \right\}$.
- 4 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$, $\tau_k = \frac{\alpha_{k+1}}{A_{k+1}}$.

Rate of convergence:

- 1 Convex case: $f(y_k) - f^* \leq \frac{4L\|x_0 - x^*\|_2^2}{k^2}$.
- 2 Strongly convex case: $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2} \exp\left(-\frac{k}{2} \sqrt{\frac{\mu}{L}}\right)$.

Generalizations

- 1 Non-Euclidean setup, e.g. Q – simplex, $d(x)$ – entropy.

Generalizations

- 1 **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

Generalizations

- ① **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

Generalizations

- 1 **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

- 2 **Composite optimization**: $f(x) \rightarrow \varphi(x) := f(x) + h(x)$, where $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable.

Generalizations

- 1 **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

- 2 **Composite optimization**: $f(x) \rightarrow \varphi(x) := f(x) + h(x)$, where $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable.

Example: LASSO $\|x - a\|_2^2 + \lambda \|x\|_1 \rightarrow \min$.

Generalizations

- 1 **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

- 2 **Composite optimization**: $f(x) \rightarrow \varphi(x) := f(x) + h(x)$, where $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable.

Example: LASSO $\|x - a\|_2^2 + \lambda \|x\|_1 \rightarrow \min$.

Non-smooth (but strongly convex) function $\Rightarrow$ lower bound $O(\frac{1}{k})$.

Generalizations

- 1 **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

- 2 **Composite optimization**: $f(x) \rightarrow \varphi(x) := f(x) + h(x)$, where $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable.

Example: LASSO $\|x - a\|_2^2 + \lambda \|x\|_1 \rightarrow \min$.

Non-smooth (but strongly convex) function $\Rightarrow$ lower bound $O(\frac{1}{k})$.

But $\|x - a\|_2^2$ is strongly convex and smooth $\Rightarrow$ we get method with $O(\exp(-k \cdot \text{const}))$.

Generalizations

- ① **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

- ② **Composite optimization**: $f(x) \rightarrow \varphi(x) := f(x) + h(x)$, where $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable.

Example: LASSO $\|x - a\|_2^2 + \lambda \|x\|_1 \rightarrow \min$.

Non-smooth (but strongly convex) function $\Rightarrow$ lower bound $O(\frac{1}{k})$.

But $\|x - a\|_2^2$ is strongly convex and smooth $\Rightarrow$ we get method with $O(\exp(-k \cdot \text{const}))$.

- ③ **Stochastic error**, e.g. $\mathbb{E}_\xi f(x, \xi) \rightarrow \min_{x \in Q}$.

Generalizations

- ① **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

- ② **Composite optimization**: $f(x) \rightarrow \varphi(x) := f(x) + h(x)$, where $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable.

Example: LASSO $\|x - a\|_2^2 + \lambda \|x\|_1 \rightarrow \min$.

Non-smooth (but strongly convex) function $\Rightarrow$ lower bound $O(\frac{1}{k})$.

But $\|x - a\|_2^2$ is strongly convex and smooth $\Rightarrow$ we get method with $O(\exp(-k \cdot \text{const}))$.

- ③ **Stochastic error**, e.g. $\mathbb{E}_\xi f(x, \xi) \rightarrow \min_{x \in Q}$.

On the step k we can get only

$\nabla f(x, \xi_k) : \mathbb{E}_{\xi_k} \nabla f(x, \xi_k) = \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)$ and

$\mathbb{E}_{\xi_k} \|\nabla f(x, \xi_k) - \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)\|_*^2 \leq \sigma^2$.

Generalizations

- ① **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

- ② **Composite optimization**: $f(x) \rightarrow \varphi(x) := f(x) + h(x)$, where $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable.

Example: LASSO $\|x - a\|_2^2 + \lambda \|x\|_1 \rightarrow \min$.

Non-smooth (but strongly convex) function $\Rightarrow$ lower bound $O(\frac{1}{k})$.

But $\|x - a\|_2^2$ is strongly convex and smooth $\Rightarrow$ we get method with $O(\exp(-k \cdot \text{const}))$.

- ③ **Stochastic error**, e.g. $\mathbb{E}_\xi f(x, \xi) \rightarrow \min_{x \in Q}$.

On the step k we can get only

$\nabla f(x, \xi_k) : \mathbb{E}_{\xi_k} \nabla f(x, \xi_k) = \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)$ and

$\mathbb{E}_{\xi_k} \|\nabla f(x, \xi_k) - \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)\|_*^2 \leq \sigma^2$.

- ④ **Deterministic error** (will be explained below).

Generalizations

- 1 **Non-Euclidean setup**, e.g. Q – simplex, $d(x)$ – entropy.

Auxiliary problem $\min_{x \in Q} \{\langle g, x \rangle + d(x)\}$ can be solved explicitly:

$$\hat{x}_i = \frac{\exp(-g_i)}{\sum_{i=1}^n \exp(-g_i)}, \quad i = 1, \dots, n.$$

- 2 **Composite optimization**: $f(x) \rightarrow \varphi(x) := f(x) + h(x)$, where $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable.

Example: LASSO $\|x - a\|_2^2 + \lambda \|x\|_1 \rightarrow \min$.

Non-smooth (but strongly convex) function $\Rightarrow$ lower bound $O(\frac{1}{k})$.

But $\|x - a\|_2^2$ is strongly convex and smooth $\Rightarrow$ we get method with $O(\exp(-k \cdot \text{const}))$.

- 3 **Stochastic error**, e.g. $\mathbb{E}_\xi f(x, \xi) \rightarrow \min_{x \in Q}$.

On the step k we can get only

$\nabla f(x, \xi_k) : \mathbb{E}_{\xi_k} \nabla f(x, \xi_k) = \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)$ and

$\mathbb{E}_{\xi_k} \|\nabla f(x, \xi_k) - \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)\|_*^2 \leq \sigma^2$.

- 4 **Deterministic error** (will be explained below).

- 5 **Unknown L, μ, R** .

Outline

- 1 Introduction to convex optimization
- 2 Concept of (δ, L) -oracle
- 3 Stochastic inexact oracle
- 4 Stochastic Intermediate Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

For every $x \in Q$ there are $f_{\delta,L}(x) \in \mathbb{R}$ and $g_{\delta,L}(x) \in E^*$ such that

$$0 \leq f(y) - f_{\delta,L}(x) - \langle g_{\delta,L}(x), y - x \rangle \leq \frac{L}{2} \|x - y\|^2 + \delta, \quad \forall y \in Q.$$

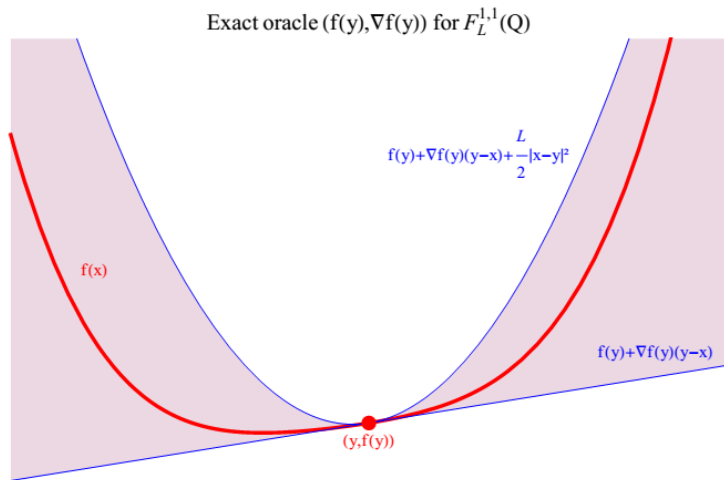
[Devolder, Glineur and Nesterov, 2011-2013]

For every $x \in Q$ there are $f_{\delta,L}(x) \in \mathbb{R}$ and $g_{\delta,L}(x) \in E^*$ such that

$$0 \leq f(y) - f_{\delta,L}(x) - \langle g_{\delta,L}(x), y - x \rangle \leq \frac{L}{2} \|x - y\|^2 + \delta, \quad \forall y \in Q.$$

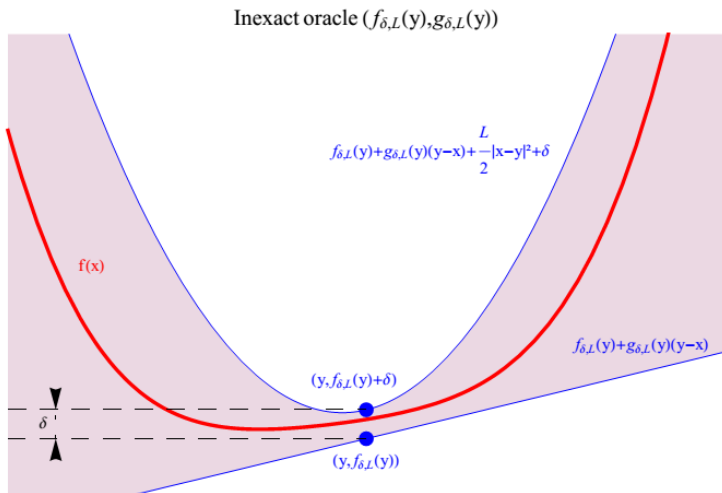
Usual oracle $(f(x), \nabla f(x))$ is replaced by (δ, L) -oracle $(f_{\delta,L}(x), g_{\delta,L}(x))$.

(δ, L) -oracle geometry



Picture from O.Devolder PhD Thesis, 2013

(δ, L) -oracle geometry



Picture from O.Devolder PhD Thesis, 2013

(δ, L) -oracle examples

- 1 $f(x)$ – convex non-smooth function with Hölder continuous subgradient $\|g(x) - g(y)\|_* \leq L_\nu \|x - y\|^\nu$, $\forall x, y \in Q$, for some $\nu \in [0, 1]$

(δ, L) -oracle examples

- ① $f(x)$ – convex non-smooth function with Hölder continuous subgradient $\|g(x) - g(y)\|_* \leq L_\nu \|x - y\|^\nu$, $\forall x, y \in Q$, for some $\nu \in [0, 1]$

Then for any $\delta > 0$ $(f(x), g(x))$ is (δ, L) -oracle, where

$$L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}.$$

(δ, L) -oracle examples

- ① $f(x)$ – convex non-smooth function with Hölder continuous subgradient $\|g(x) - g(y)\|_* \leq L_\nu \|x - y\|^\nu$, $\forall x, y \in Q$, for some $\nu \in [0, 1]$

Then for any $\delta > 0$ $(f(x), g(x))$ is (δ, L) -oracle, where

$$L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}.$$

When $\nu = 0$ we have $L = \frac{L_0^2}{2\delta}$.

(δ, L) -oracle examples

- 1 $f(x)$ – convex non-smooth function with Hölder continuous subgradient $\|g(x) - g(y)\|_* \leq L_\nu \|x - y\|^\nu$, $\forall x, y \in Q$, for some $\nu \in [0, 1]$

Then for any $\delta > 0$ $(f(x), g(x))$ is (δ, L) -oracle, where

$$L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}.$$

When $\nu = 0$ we have $L = \frac{L_0^2}{2\delta}$.

- 2 $f(x)$ – smooth with M -Lipschitz continuous gradient.

(δ, L) -oracle examples

- 1 $f(x)$ – convex non-smooth function with Hölder continuous subgradient $\|g(x) - g(y)\|_* \leq L_\nu \|x - y\|^\nu$, $\forall x, y \in Q$, for some $\nu \in [0, 1]$

Then for any $\delta > 0$ $(f(x), g(x))$ is (δ, L) -oracle, where

$$L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}.$$

When $\nu = 0$ we have $L = \frac{L_0^2}{2\delta}$.

- 2 $f(x)$ – smooth with M -Lipschitz continuous gradient.

At each point $x \in Q$ we can get

$$\tilde{f}_x: |f(x) - \tilde{f}_x| \leq \Delta_1 \text{ and } \tilde{\nabla} f_x: \|\nabla f(x) - \tilde{\nabla} f_x\| \leq \Delta_2.$$

(δ, L) -oracle examples

- ① $f(x)$ – convex non-smooth function with Hölder continuous subgradient $\|g(x) - g(y)\|_* \leq L_\nu \|x - y\|^\nu$, $\forall x, y \in Q$, for some $\nu \in [0, 1]$

Then for any $\delta > 0$ $(f(x), g(x))$ is (δ, L) -oracle, where

$$L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}.$$

When $\nu = 0$ we have $L = \frac{L_0^2}{2\delta}$.

- ② $f(x)$ – smooth with M -Lipschitz continuous gradient.

At each point $x \in Q$ we can get

$$\tilde{f}_x : |f(x) - \tilde{f}_x| \leq \Delta_1 \text{ and } \tilde{\nabla} f_x : \|\nabla f(x) - \tilde{\nabla} f_x\| \leq \Delta_2.$$

If $\text{diam} Q = D < +\infty$ then $(\tilde{f}_x - \Delta_1 - \Delta_2 D, \tilde{\nabla} f_x)$ is a $(2\Delta_1 + 2\Delta_2 D, M)$ -oracle.

Convex case: PGM, DGM and FGM revisited

For $\mu = 0$ the only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L}(x)$,
 $\nabla f(x) \rightarrow g_{\delta,L}(x)$.

Convex case: PGM, DGM and FGM revisited

For $\mu = 0$ the only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L}(x)$, $\nabla f(x) \rightarrow g_{\delta,L}(x)$.

[Devolder, Glineur and Nesterov, 2011-2013]:

❶ PGM, $y_k = \frac{\sum_{i=1}^k x_i}{k}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2k} + \delta$.

Convex case: PGM, DGM and FGM revisited

For $\mu = 0$ the only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L}(x)$, $\nabla f(x) \rightarrow g_{\delta,L}(x)$.

[Devolder, Glineur and Nesterov, 2011-2013]:

- 1 PGM, $y_k = \frac{\sum_{i=1}^k x_i}{k}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2k} + \delta$.
- 2 DGM, $y_k = \frac{\sum_{i=0}^k w_i}{k+1}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2(k+1)} + \delta$.

Convex case: PGM, DGM and FGM revisited

For $\mu = 0$ the only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L}(x)$, $\nabla f(x) \rightarrow g_{\delta,L}(x)$.

[Devolder, Glineur and Nesterov, 2011-2013]:

- 1 PGM, $y_k = \frac{\sum_{i=1}^k x_i}{k}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2k} + \delta$.
- 2 DGM, $y_k = \frac{\sum_{i=0}^k w_i}{k+1}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2(k+1)} + \delta$.
- 3 FGM, $f(y_k) - f^* \leq \frac{2L\|x_0 - x^*\|_2^2}{(k+1)^2} + \frac{1}{3}(k+3)\delta$.

Convex case: PGM, DGM and FGM revisited

For $\mu = 0$ the only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L}(x)$, $\nabla f(x) \rightarrow g_{\delta,L}(x)$.

[Devolder, Glineur and Nesterov, 2011-2013]:

❶ PGM, $y_k = \frac{\sum_{i=1}^k x_i}{k}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2k} + \delta$.

❷ DGM, $y_k = \frac{\sum_{i=0}^k w_i}{k+1}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2(k+1)} + \delta$.

❸ FGM, $f(y_k) - f^* \leq \frac{2L\|x_0 - x^*\|_2^2}{(k+1)^2} + \frac{1}{3}(k+3)\delta$.

These methods can be generalized to strongly convex case.

[Devolder, Glineur and Nesterov, 2011-2013]

For every $x \in Q$ there are $f_{\delta, L, \mu}(x) \in \mathbb{R}$ and $g_{\delta, L, \mu}(x) \in E^*$ such that

$$\frac{\mu}{2} \|x - y\|^2 \leq f(y) - f_{\delta, L, \mu}(x) - \langle g_{\delta, L, \mu}(x), y - x \rangle \leq \frac{L}{2} \|x - y\|^2 + \delta, \forall y \in Q.$$

[Devolder, Glineur and Nesterov, 2011-2013]

For every $x \in Q$ there are $f_{\delta,L,\mu}(x) \in \mathbb{R}$ and $g_{\delta,L,\mu}(x) \in E^*$ such that

$$\frac{\mu}{2} \|x - y\|^2 \leq f(y) - f_{\delta,L,\mu}(x) - \langle g_{\delta,L,\mu}(x), y - x \rangle \leq \frac{L}{2} \|x - y\|^2 + \delta, \forall y \in Q.$$

Usual oracle $(f(x), \nabla f(x))$ is replaced by (δ, L, μ) -oracle $(f_{\delta,L,\mu}(x), g_{\delta,L,\mu}(x))$.

Strongly convex case: PGM, DGM and FGM revisited

The only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L,\mu}(x)$,
 $\nabla f(x) \rightarrow g_{\delta,L,\mu}(x)$.

Strongly convex case: PGM, DGM and FGM revisited

The only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L,\mu}(x)$,
 $\nabla f(x) \rightarrow g_{\delta,L,\mu}(x)$.

[Devolder, Glineur and Nesterov, 2011-2013]:

① PGM, $y_k = \arg \min_{i=1,\dots,k} f(x_i)$,
$$f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2} \exp\left(-k\frac{\mu}{L}\right) + \delta.$$

Strongly convex case: PGM, DGM and FGM revisited

The only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L,\mu}(x)$,
 $\nabla f(x) \rightarrow g_{\delta,L,\mu}(x)$.

[Devolder, Glineur and Nesterov, 2011-2013]:

- 1 PGM, $y_k = \arg \min_{i=1,\dots,k} f(x_i)$,
$$f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2} \exp\left(-k\frac{\mu}{L}\right) + \delta.$$
- 2 DGM, $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2} \exp\left(-(k+1)\frac{\mu}{L}\right) + \delta.$

Strongly convex case: PGM, DGM and FGM revisited

The only change we need to do in the schemes is $f(x) \rightarrow f_{\delta,L,\mu}(x)$,
 $\nabla f(x) \rightarrow g_{\delta,L,\mu}(x)$.

[Devolder, Glineur and Nesterov, 2011-2013]:

- ① **PGM**, $y_k = \arg \min_{i=1,\dots,k} f(x_i)$,
$$f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2} \exp\left(-k\frac{\mu}{L}\right) + \delta.$$
- ② **DGM**, $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$, $f(y_k) - f^* \leq \frac{L\|x_0 - x^*\|_2^2}{2} \exp\left(-(k+1)\frac{\mu}{L}\right) + \delta.$
- ③ **FGM**, $f(y_k) - f^* \leq L\|x_0 - x^*\|_2^2 \exp\left(-\frac{k}{2}\sqrt{\frac{\mu}{L}}\right) + \left(1 + \sqrt{\frac{L}{\mu}}\right)\delta.$

(δ, L) -oracle application 1

As we have seen $f(x)$ – convex non-smooth function with Hölder continuous subgradient can be for any $\delta > 0$ equipped with (δ, L) -oracle

with $L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}$.

(δ, L) -oracle application 1

As we have seen $f(x)$ – convex non-smooth function with Hölder continuous subgradient can be for any $\delta > 0$ equipped with (δ, L) -oracle

with $L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}$.

Then for N iterations of FGM we get

$$f(y_N) - f^* \leq \frac{2R^2}{(N+1)^2} L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}} + \frac{1}{3}(N+1)\delta$$

(δ, L) -oracle application 1

As we have seen $f(x)$ – convex non-smooth function with Hölder continuous subgradient can be for any $\delta > 0$ equipped with (δ, L) -oracle

with $L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}$.

Then for N iterations of FGM we get

$$f(y_N) - f^* \leq \frac{2R^2}{(N+1)^2} L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}} + \frac{1}{3}(N+1)\delta$$

Optimizing in δ we get

$$\delta_N = \frac{1-\nu}{1+\nu} \frac{L_\nu R^{1+\nu}}{(N+1)^{\frac{3}{2}(1+\nu)}} 2^\nu, \quad L = \frac{L_\nu (N+1)^{\frac{3(1-\nu)}{2}}}{2^{1-\nu} R^{1-\nu}},$$

(δ, L) -oracle application 1

As we have seen $f(x)$ – convex non-smooth function with Hölder continuous subgradient can be for any $\delta > 0$ equipped with (δ, L) -oracle

with $L = L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}}$.

Then for N iterations of FGM we get

$$f(y_N) - f^* \leq \frac{2R^2}{(N+1)^2} L_\nu \left[\frac{L_\nu(1-\nu)}{2\delta(1+\nu)} \right]^{\frac{1-\nu}{1+\nu}} + \frac{1}{3}(N+1)\delta$$

Optimizing in δ we get

$$\delta_N = \frac{1-\nu}{1+\nu} \frac{L_\nu R^{1+\nu}}{(N+1)^{\frac{3}{2}(1+\nu)}} 2^\nu, \quad L = \frac{L_\nu (N+1)^{\frac{3(1-\nu)}{2}}}{2^{1-\nu} R^{1-\nu}},$$

and optimal for every $\nu \in [0, 1]$ rate

$$f(y_N) - f^* \leq \frac{2^{1+\nu} L_\nu R^{1+\nu}}{1+\nu} \left(\frac{1}{N+1} \right)^{\frac{1+3\nu}{2}}$$

(δ, L) -oracle application 2

$f(x) = f_1(x) + f_2(x)$, where $f_1(x)$ is convex, smooth with L_1 - Lipschitz continuous gradient, $f_2(x)$ is convex, non-smooth with M_2 bounded variation of subgradient.

(δ, L) -oracle application 2

$f(x) = f_1(x) + f_2(x)$, where $f_1(x)$ is convex, smooth with L_1 - Lipschitz continuous gradient, $f_2(x)$ is convex, non-smooth with M_2 bounded variation of subgradient.

Then $(f_1(x) + f_2(x), \nabla f_1(x) + g_2(x))$, $g_2(x) \in \partial f_2(x)$ is a (δ, L) -oracle for $f(x)$ with $L = L_1 + \frac{M_2^2}{2\delta}$.

(δ, L) -oracle application 2

$f(x) = f_1(x) + f_2(x)$, where $f_1(x)$ is convex, smooth with L_1 - Lipschitz continuous gradient, $f_2(x)$ is convex, non-smooth with M_2 bounded variation of subgradient.

Then $(f_1(x) + f_2(x), \nabla f_1(x) + g_2(x))$, $g_2(x) \in \partial f_2(x)$ is a (δ, L) -oracle for $f(x)$ with $L = L_1 + \frac{M_2^2}{2\delta}$.

Fixing again number of iterations N and optimizing in δ we obtain

$$f(y_N) - f^* \leq \frac{2L_1R^2}{(N+1)^2} + \frac{2M_2R}{\sqrt{N+1}}.$$

Theorem [Devolder, Glineur and Nesterov]

Consider a first-order method for the class of L -smooth functions with convergence rate $O\left(\frac{LR^2}{k^p}\right)$ when exact first-order information is used. Assume that the bounds on the performance of this method applied to a problem equipped with an inexact (δ, L) -oracle are given by inequality

$$f(y_k) - f^* \leq \frac{C_1 LR^2}{k^p} + C_2 k^q \delta,$$

where C_1, C_2 are absolute constants. Then the inequality $q \geq p - 1$ must hold.

Theorem [Devolder, Glineur and Nesterov]

Consider a first-order method for the class of L -smooth functions with convergence rate $O\left(\frac{LR^2}{k^p}\right)$ when exact first-order information is used. Assume that the bounds on the performance of this method applied to a problem equipped with an inexact (δ, L) -oracle are given by inequality

$$f(y_k) - f^* \leq \frac{C_1 LR^2}{k^p} + C_2 k^q \delta,$$

where C_1, C_2 are absolute constants. Then the inequality $q \geq p - 1$ must hold.

Examples:

PGM $p = 1$ and $q = 0$.

Theorem [Devolder, Glineur and Nesterov]

Consider a first-order method for the class of L -smooth functions with convergence rate $O\left(\frac{LR^2}{k^p}\right)$ when exact first-order information is used. Assume that the bounds on the performance of this method applied to a problem equipped with an inexact (δ, L) -oracle are given by inequality

$$f(y_k) - f^* \leq \frac{C_1 LR^2}{k^p} + C_2 k^q \delta,$$

where C_1, C_2 are absolute constants. Then the inequality $q \geq p - 1$ must hold.

Examples:

PGM $p = 1$ and $q = 0$.

FGM $p = 2$ and $q = 1$.

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0, \quad \alpha_k^2 \leq B_k \leq \sum_{i=0}^k \alpha_i, \quad \forall k \geq 1$$

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0, \quad \alpha_k^2 \leq B_k \leq \sum_{i=0}^k \alpha_i, \quad \forall k \geq 1$$

We define also $A_k = \sum_{i=0}^k \alpha_i$ and $\tau_i = \frac{\alpha_{i+1}}{B_{i+1}}$.

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0, \quad \alpha_k^2 \leq B_k \leq \sum_{i=0}^k \alpha_i, \quad \forall k \geq 1$$

We define also $A_k = \sum_{i=0}^k \alpha_i$ and $\tau_i = \frac{\alpha_{i+1}}{B_{i+1}}$.

Method:

- 1 Choose $x_0 \in Q$.

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0, \quad \alpha_k^2 \leq B_k \leq \sum_{i=0}^k \alpha_i, \quad \forall k \geq 1$$

We define also $A_k = \sum_{i=0}^k \alpha_i$ and $\tau_i = \frac{\alpha_{i+1}}{B_{i+1}}$.

Method:

- ① Choose $x_0 \in Q$.
- ② $w_k = \pi_Q \left(x_k - \frac{1}{L} g_{\delta, L}(x_k) \right)$.

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0, \quad \alpha_k^2 \leq B_k \leq \sum_{i=0}^k \alpha_i, \quad \forall k \geq 1$$

We define also $A_k = \sum_{i=0}^k \alpha_i$ and $\tau_i = \frac{\alpha_{i+1}}{B_{i+1}}$.

Method:

- ① Choose $x_0 \in Q$.
- ② $w_k = \pi_Q \left(x_k - \frac{1}{L} g_{\delta, L}(x_k) \right)$.
- ③ $z_k = \arg \min_{x \in Q} \Psi_k(x) =$
 $\arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [f_{\delta, L}(x_i) + \langle g_{\delta, L}(x_i), x - x_i \rangle] \right\}.$

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0, \quad \alpha_k^2 \leq B_k \leq \sum_{i=0}^k \alpha_i, \quad \forall k \geq 1$$

We define also $A_k = \sum_{i=0}^k \alpha_i$ and $\tau_i = \frac{\alpha_{i+1}}{B_{i+1}}$.

Method:

- ① Choose $x_0 \in Q$.
- ② $w_k = \pi_Q \left(x_k - \frac{1}{L} g_{\delta, L}(x_k) \right)$.
- ③ $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [f_{\delta, L}(x_i) + \langle g_{\delta, L}(x_i), x - x_i \rangle] \right\}$.
- ④ $y_k = \frac{A_k - B_k}{A_k} y_{k-1} + \frac{B_k}{A_k} w_k$.

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0, \quad \alpha_k^2 \leq B_k \leq \sum_{i=0}^k \alpha_i, \quad \forall k \geq 1$$

We define also $A_k = \sum_{i=0}^k \alpha_i$ and $\tau_i = \frac{\alpha_{i+1}}{B_{i+1}}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{L} g_{\delta, L}(x_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [f_{\delta, L}(x_i) + \langle g_{\delta, L}(x_i), x - x_i \rangle] \right\}$.
- 4 $y_k = \frac{A_k - B_k}{A_k} y_{k-1} + \frac{B_k}{A_k} w_k$.
- 5 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k, \quad \tau_k = \frac{\alpha_{k+1}}{B_{k+1}}$.

Intermediate gradient method

Devolder, Glineur and Nesterov proposed a method with intermediate rate.

Let $\{\alpha_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be two sequences of coefficients satisfying

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0, \quad \alpha_k^2 \leq B_k \leq \sum_{i=0}^k \alpha_i, \quad \forall k \geq 1$$

We define also $A_k = \sum_{i=0}^k \alpha_i$ and $\tau_i = \frac{\alpha_{i+1}}{B_{i+1}}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{L} g_{\delta, L}(x_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{L}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [f_{\delta, L}(x_i) + \langle g_{\delta, L}(x_i), x - x_i \rangle] \right\}$.
- 4 $y_k = \frac{A_k - B_k}{A_k} y_{k-1} + \frac{B_k}{A_k} w_k$.
- 5 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k, \quad \tau_k = \frac{\alpha_{k+1}}{B_{k+1}}$.

Choose $\alpha_i = \left(\frac{i+p}{p} \right)^{p-1}$, $B_i = \alpha_i^2$. Then rate of convergence for convex case:

$$f(y_k) - f^* \leq \Theta \left(\frac{L \|x_0 - x^*\|_2^2}{2k^p} \right) + \Theta(k^{p-1} \delta)$$

Outline

- 1 Introduction to convex optimization
- 2 Concept of (δ, L) -oracle
- 3 Stochastic inexact oracle
- 4 Stochastic Intermediate Gradient Method

Concept of stochastic inexact oracle

[Devolder, Glineur and Nesterov, 2011-2013]

The function $f(x)$ is equipped with (δ, L) -oracle. For every $x \in Q$ there are $f_{\delta,L}(x) \in \mathbb{R}$ and $g_{\delta,L}(x) \in E^*$ such that

$$0 \leq f(y) - f_{\delta,L}(x) - \langle g_{\delta,L}(x), y - x \rangle \leq \frac{L}{2} \|x - y\|^2 + \delta, \quad \forall y \in Q.$$

Concept of stochastic inexact oracle

[Devolder, Glineur and Nesterov, 2011-2013]

The function $f(x)$ is equipped with (δ, L) -oracle. For every $x \in Q$ there are $f_{\delta,L}(x) \in \mathbb{R}$ and $g_{\delta,L}(x) \in E^*$ such that

$$0 \leq f(y) - f_{\delta,L}(x) - \langle g_{\delta,L}(x), y - x \rangle \leq \frac{L}{2} \|x - y\|^2 + \delta, \quad \forall y \in Q.$$

Instead of $(f_{\delta,L}(x), g_{\delta,L}(x))$ ((δ, L) -oracle) we use their stochastic approximations $(F_{\delta,L}(x, \xi), G_{\delta,L}(x, \xi))$.

Concept of stochastic inexact oracle

[Devolder, Glineur and Nesterov, 2011-2013]

The function $f(x)$ is equipped with (δ, L) -oracle. For every $x \in Q$ there are $f_{\delta,L}(x) \in \mathbb{R}$ and $g_{\delta,L}(x) \in E^*$ such that

$$0 \leq f(y) - f_{\delta,L}(x) - \langle g_{\delta,L}(x), y - x \rangle \leq \frac{L}{2} \|x - y\|^2 + \delta, \quad \forall y \in Q.$$

Instead of $(f_{\delta,L}(x), g_{\delta,L}(x))$ ((δ, L) -oracle) we use their stochastic approximations $(F_{\delta,L}(x, \xi), G_{\delta,L}(x, \xi))$.

We associate with x a random variable ξ whose probability distribution is supported $\Xi \subset \mathbb{R}^d$ and such that

$$\mathbb{E}_{\xi} F_{\delta,L}(x, \xi) = f_{\delta,L}(x)$$

$$\mathbb{E}_{\xi} G_{\delta,L}(x, \xi) = g_{\delta,L}(x)$$

$$\mathbb{E}_{\xi} \|G_{\delta,L}(x, \xi) - g_{\delta,L}(x)\|_*^2 \leq \sigma^2.$$

Stochastic inexact oracle: examples

- 1 Usual **stochastic optimization** $\mathbb{E}_\xi f(x, \xi) \rightarrow \min_{x \in Q}$.

Stochastic inexact oracle: examples

- ① Usual **stochastic optimization** $\mathbb{E}_{\xi} f(x, \xi) \rightarrow \min_{x \in Q}$.

On the step k we can get only

$$\nabla f(x, \xi_k) : \quad \mathbb{E}_{\xi_k} \nabla f(x, \xi_k) = \nabla \mathbb{E}_{\xi_k} f(x, \xi_k) \text{ and}$$

$$\mathbb{E}_{\xi_k} \|\nabla f(x, \xi_k) - \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)\|_*^2 \leq \sigma^2.$$

Here $\delta = 0$.

Stochastic inexact oracle: examples

- ① Usual **stochastic optimization** $\mathbb{E}_{\xi} f(x, \xi) \rightarrow \min_{x \in Q}$.

On the step k we can get only

$$\nabla f(x, \xi_k) : \quad \mathbb{E}_{\xi_k} \nabla f(x, \xi_k) = \nabla \mathbb{E}_{\xi_k} f(x, \xi_k) \text{ and}$$

$$\mathbb{E}_{\xi_k} \|\nabla f(x, \xi_k) - \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)\|_*^2 \leq \sigma^2.$$

Here $\delta = 0$.

- ② **Randomization technique** for LASSO.

$$\frac{1}{2} \|Ax - b\|_2^2 + \lambda \|x\|_1 = f(x) + h(x), \text{ where } A \in \mathbb{R}^{N \times n}, x \in \mathbb{R}^n, \\ b \in \mathbb{R}^N.$$

Stochastic inexact oracle: examples

- ① Usual **stochastic optimization** $\mathbb{E}_{\xi} f(x, \xi) \rightarrow \min_{x \in Q}$.

On the step k we can get only

$$\nabla f(x, \xi_k) : \quad \mathbb{E}_{\xi_k} \nabla f(x, \xi_k) = \nabla \mathbb{E}_{\xi_k} f(x, \xi_k) \text{ and}$$

$$\mathbb{E}_{\xi_k} \|\nabla f(x, \xi_k) - \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)\|_*^2 \leq \sigma^2.$$

Here $\delta = 0$.

- ② **Randomization technique** for LASSO.

$$\frac{1}{2} \|Ax - b\|_2^2 + \lambda \|x\|_1 = f(x) + h(x), \text{ where } A \in \mathbb{R}^{N \times n}, x \in \mathbb{R}^n, b \in \mathbb{R}^N.$$

$\nabla f(x) = A^T Ax - A^T b = \sum_{i=1}^N (x^T a_i - b_i) a_i$ is very difficult to calculate when N is very large.

Stochastic inexact oracle: examples

- ① Usual **stochastic optimization** $\mathbb{E}_{\xi} f(x, \xi) \rightarrow \min_{x \in Q}$.

On the step k we can get only

$$\nabla f(x, \xi_k) : \quad \mathbb{E}_{\xi_k} \nabla f(x, \xi_k) = \nabla \mathbb{E}_{\xi_k} f(x, \xi_k) \text{ and}$$

$$\mathbb{E}_{\xi_k} \|\nabla f(x, \xi_k) - \nabla \mathbb{E}_{\xi_k} f(x, \xi_k)\|_*^2 \leq \sigma^2.$$

Here $\delta = 0$.

- ② **Randomization technique** for LASSO.

$$\frac{1}{2} \|Ax - b\|_2^2 + \lambda \|x\|_1 = f(x) + h(x), \text{ where } A \in \mathbb{R}^{N \times n}, x \in \mathbb{R}^n, b \in \mathbb{R}^N.$$

$\nabla f(x) = A^T Ax - A^T b = \sum_{i=1}^N (x^T a_i - b_i) a_i$ is very difficult to calculate when N is very large.

The idea is to replace $\nabla f(x)$ by $G_{0,L}(x, \xi) = \frac{N}{M} \sum_{j=1}^M (x^T a_{\xi_j} - b_{\xi_j}) a_{\xi_j}$, where $\{\xi_1, \dots, \xi_M\}$ is a subset of rows uniformly chosen from $\{1, \dots, N\}$.

Here $\delta = 0$.

Stochastic Primal Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\beta_k > L$, $\gamma_k = \frac{1}{\beta_k}$.

Stochastic Primal Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\beta_k > L$, $\gamma_k = \frac{1}{\beta_k}$.

Method:

- 1 Choose $x_0 \in Q$.

Stochastic Primal Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\beta_k > L$, $\gamma_k = \frac{1}{\beta_k}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{F_{\delta,L}(x_k, \xi_k) + \langle G_{\delta,L}(x_k, \xi_k), x - x_k \rangle + \frac{\beta_k}{2}\|x - x_k\|_2^2\} = \pi_Q(x_k - \gamma_k G_{\delta,L}(x_k, \xi_k))$.

Stochastic Primal Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\beta_k > L$, $\gamma_k = \frac{1}{\beta_k}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{F_{\delta,L}(x_k, \xi_k) + \langle G_{\delta,L}(x_k, \xi_k), x - x_k \rangle + \frac{\beta_k}{2}\|x - x_k\|_2^2\} = \pi_Q(x_k - \gamma_k G_{\delta,L}(x_k, \xi_k))$.

Output: $y_k = \frac{\sum_{i=0}^{k-1} \gamma_i x_{i+1}}{\sum_{i=0}^{k-1} \gamma_i}$.

Stochastic Primal Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\beta_k > L$, $\gamma_k = \frac{1}{\beta_k}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{F_{\delta,L}(x_k, \xi_k) + \langle G_{\delta,L}(x_k, \xi_k), x - x_k \rangle + \frac{\beta_k}{2}\|x - x_k\|_2^2\} = \pi_Q(x_k - \gamma_k G_{\delta,L}(x_k, \xi_k))$.

Output: $y_k = \frac{\sum_{i=0}^{k-1} \gamma_i x_{i+1}}{\sum_{i=0}^{k-1} \gamma_i}$.

Rate of convergence:

- 1 If N is fixed in advance: choose $\beta_i = L + \frac{\sigma}{R}\sqrt{N}$ and obtain $\mathbb{E}f(y_N) - f^* \leq \frac{LR^2}{2N} + \frac{3\sigma R}{2\sqrt{N}} + \delta$.

Stochastic Primal Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\beta_k > L$, $\gamma_k = \frac{1}{\beta_k}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{ F_{\delta,L}(x_k, \xi_k) + \langle G_{\delta,L}(x_k, \xi_k), x - x_k \rangle + \frac{\beta_k}{2} \|x - x_k\|_2^2 \} = \pi_Q(x_k - \gamma_k G_{\delta,L}(x_k, \xi_k))$.

Output: $y_k = \frac{\sum_{i=0}^{k-1} \gamma_i x_{i+1}}{\sum_{i=0}^{k-1} \gamma_i}$.

Rate of convergence:

- 1 If N is fixed in advance: choose $\beta_i = L + \frac{\sigma}{R} \sqrt{N}$ and obtain

$$\mathbb{E}f(y_N) - f^* \leq \frac{LR^2}{2N} + \frac{3\sigma R}{2\sqrt{N}} + \delta.$$

- 2 Otherwise choose $\beta_i = \frac{(L + \frac{\sigma}{R} \sqrt{i+1})^2}{L + \frac{\sigma}{2R} \sqrt{i+1}}$ and obtain

$$\mathbb{E}f(y_k) - f^* \leq \Theta \left(\frac{LR^2 \ln k}{k} + \frac{\sigma R \ln k}{\sqrt{k}} + \delta \right).$$

Stochastic Primal Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\beta_k > L$, $\gamma_k = \frac{1}{\beta_k}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $x_{k+1} = \arg \min_{x \in Q} \{F_{\delta,L}(x_k, \xi_k) + \langle G_{\delta,L}(x_k, \xi_k), x - x_k \rangle + \frac{\beta_k}{2}\|x - x_k\|_2^2\} = \pi_Q(x_k - \gamma_k G_{\delta,L}(x_k, \xi_k))$.

Output: $y_k = \frac{\sum_{i=0}^{k-1} \gamma_i x_{i+1}}{\sum_{i=0}^{k-1} \gamma_i}$.

Rate of convergence:

- 1 If N is fixed in advance: choose $\beta_i = L + \frac{\sigma}{R}\sqrt{N}$ and obtain

$$\mathbb{E}f(y_N) - f^* \leq \frac{LR^2}{2N} + \frac{3\sigma R}{2\sqrt{N}} + \delta.$$

- 2 Otherwise choose $\beta_i = \frac{(L + \frac{\sigma}{R}\sqrt{i+1})^2}{L + \frac{\sigma}{2R}\sqrt{i+1}}$ and obtain

$$\mathbb{E}f(y_k) - f^* \leq \Theta\left(\frac{LR^2 \ln k}{k} + \frac{\sigma R \ln k}{\sqrt{k}} + \delta\right).$$

Can be generalized to non-Euclidean setup and composite optimization.

Stochastic estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [\textcolor{red}{F}_{\delta,L}(x_i, \xi_i) + \langle \textcolor{red}{G}_{\delta,L}(x_i, \xi_i), x - x_i \rangle] -$
stochastic model of the objective function.

Stochastic estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [\textcolor{red}{F}_{\delta,L}(x_i, \xi_i) + \langle \textcolor{red}{G}_{\delta,L}(x_i, \xi_i), x - x_i \rangle] -$
 stochastic model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.

Stochastic estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle]$ – stochastic model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^* + E_k, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x) + \bar{E}_k(x), \quad \forall x \in Q.$$

Stochastic estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [\textcolor{red}{F}_{\delta,L}(x_i, \xi_i) + \langle \textcolor{red}{G}_{\delta,L}(x_i, \xi_i), x - x_i \rangle] - \text{stochastic model}$ of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^* + \textcolor{red}{E}_k, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x) + \textcolor{red}{E}_k(x), \quad \forall x \in Q.$$

Then

$$A_k f(y_k) \leq \Psi_k^* + E_k \leq$$

Stochastic estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [\textcolor{red}{F}_{\delta,L}(x_i, \xi_i) + \langle \textcolor{red}{G}_{\delta,L}(x_i, \xi_i), x - x_i \rangle] - \text{stochastic model}$ of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^* + \textcolor{red}{E}_k, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x) + \textcolor{red}{E}_k(x), \quad \forall x \in Q.$$

Then

$$A_k f(y_k) \leq \Psi_k^* + E_k \leq \Psi_k(x^*) + E_k \leq$$

Stochastic estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [\textcolor{red}{F}_{\delta,L}(x_i, \xi_i) + \langle \textcolor{red}{G}_{\delta,L}(x_i, \xi_i), x - x_i \rangle] - \text{stochastic model}$ of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^* + \textcolor{red}{E}_k, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x) + \textcolor{red}{\bar{E}}_k(x), \quad \forall x \in Q.$$

Then

$$A_k f(y_k) \leq \Psi_k^* + E_k \leq \Psi_k(x^*) + E_k \leq A_k f^* + \beta_k d(x^*) + \bar{E}_k(x^*) + E_k,$$

and

Stochastic estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle] -$
stochastic model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k f(y_k) \leq \Psi_k^* + E_k, \quad \Psi_k(x) \leq A_k f(x) + \beta_k d(x) + \bar{E}_k(x), \quad \forall x \in Q.$$

Then

$$A_k f(y_k) \leq \Psi_k^* + E_k \leq \Psi_k(x^*) + E_k \leq A_k f^* + \beta_k d(x^*) + \bar{E}_k(x^*) + E_k,$$

and

$$f(y_k) - f^* \leq \frac{\beta_k}{A_k} d(x^*) + \frac{\bar{E}_k(x^*) + E_k}{A_k},$$

which can give us mean rate of convergence and probability of large deviations.

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Method:

- 1 Choose $x_0 \in Q$.

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta,L}(x_k, \xi_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle] \right\}$.

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta,L}(x_k, \xi_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle] \right\}$.

Output: $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$.

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta,L}(x_k, \xi_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle] \right\}$.

Output: $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$.

Choose $\alpha_i = \frac{1}{\sqrt{2}}$, $\beta_i = L + \frac{2^{1/4}\sigma}{R} \sqrt{i+1}$

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta,L}(x_k, \xi_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle] \right\}$.

Output: $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$.

Choose $\alpha_i = \frac{1}{\sqrt{2}}$, $\beta_i = L + \frac{2^{1/4}\sigma}{R} \sqrt{i+1}$

Rate of convergence: $\mathbb{E}f(y_k) - f^* \leq \frac{LR^2}{\sqrt{2}(k+1)} + \frac{2^{3/4}\sigma R}{\sqrt{k+1}} + \delta$.

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta, L}(x_i, \xi_i) + \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle] \right\}$.

Output: $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$.

Choose $\alpha_i = \frac{1}{\sqrt{2}}$, $\beta_i = L + \frac{2^{1/4}\sigma}{R} \sqrt{i+1}$

Rate of convergence: $\mathbb{E}f(y_k) - f^* \leq \frac{LR^2}{\sqrt{2}(k+1)} + \frac{2^{3/4}\sigma R}{\sqrt{k+1}} + \delta$. Large deviations:

$$P \left\{ f(y_k) - f^* > \frac{LR^2}{\sqrt{2}(k+1)} + \left(1 + \frac{\Omega}{2}\right) \frac{2^{3/4}\sigma R}{\sqrt{k+1}} + \frac{\sqrt{3\Omega}\sigma D}{\sqrt{k+1}} + \delta \right\} \leq 2 \exp(-\Omega).$$

Stochastic Dual Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\beta_k \geq \alpha_{k+1}\beta_{k+1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $w_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.
- 3 $x_{k+1} = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta, L}(x_i, \xi_i) + \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle] \right\}$.

Output: $y_k = \frac{\sum_{i=0}^k \alpha_i w_i}{A_k}$.

Choose $\alpha_i = \frac{1}{\sqrt{2}}$, $\beta_i = L + \frac{2^{1/4}\sigma}{R} \sqrt{i+1}$

Rate of convergence: $\mathbb{E}f(y_k) - f^* \leq \frac{LR^2}{\sqrt{2}(k+1)} + \frac{2^{3/4}\sigma R}{\sqrt{k+1}} + \delta$. Large deviations:

$$P \left\{ f(y_k) - f^* > \frac{LR^2}{\sqrt{2}(k+1)} + \left(1 + \frac{\Omega}{2}\right) \frac{2^{3/4}\sigma R}{\sqrt{k+1}} + \frac{\sqrt{3\Omega}\sigma D}{\sqrt{k+1}} + \delta \right\} \leq 2 \exp(-\Omega).$$

Can be generalized to non-Euclidean setup and composite optimization.

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Method:

- 1 Choose $x_0 \in Q$.

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta, L}(x_i, \xi_i) + \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle] \right\}$.

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta, L}(x_i, \xi_i) + \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle] \right\}$.
- 4 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$, $\tau_k = \frac{\alpha_{k+1}}{A_{k+1}}$.

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta, L}(x_i, \xi_i) + \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle] \right\}$.
- 4 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$, $\tau_k = \frac{\alpha_{k+1}}{A_{k+1}}$.

Choose $\alpha_i = \frac{i+1}{2\sqrt{2}}$, $\beta_i = L + \frac{\sigma}{2^{1/4}\sqrt{3}R}(i+2)^{3/2}$

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta, L}(x_i, \xi_i) + \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle] \right\}$.
- 4 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$, $\tau_k = \frac{\alpha_{k+1}}{A_{k+1}}$.

Choose $\alpha_i = \frac{i+1}{2\sqrt{2}}$, $\beta_i = L + \frac{\sigma}{2^{1/4}\sqrt{3}R} (i+2)^{3/2}$

Rate of convergence:

$$\mathbb{E} f(y_k) - f^* \leq \frac{2^{3/2} L R^2}{(k+1)(k+2)} + \frac{2^{9/4} (k+3)^{3/2} \sigma R}{\sqrt{3} (k+1)(k+2)} + \frac{1}{3} (k+3) \delta.$$

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta, L}(x_i, \xi_i) + \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle] \right\}$.
- 4 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$, $\tau_k = \frac{\alpha_{k+1}}{A_{k+1}}$.

Choose $\alpha_i = \frac{i+1}{2\sqrt{2}}$, $\beta_i = L + \frac{\sigma}{2^{1/4}\sqrt{3}R} (i+2)^{3/2}$

Rate of convergence:

$\mathbb{E} f(y_k) - f^* \leq \frac{2^{3/2} L R^2}{(k+1)(k+2)} + \frac{2^{9/4} (k+3)^{3/2} \sigma R}{\sqrt{3} (k+1)(k+2)} + \frac{1}{3} (k+3) \delta$. Large deviations:
the same order.

Stochastic Fast Gradient Method

[Devolder, Glineur and Nesterov, 2011-2013]

Choose $d(x) = \frac{1}{2}\|x - x_0\|_2^2$, $\alpha_0 \in (0, 1]$, $A_k = \sum_{i=0}^k \alpha_i$, $\beta_{k+1} \geq \beta_k > L$,
 $\alpha_k^2 \beta_k \leq A_k \beta_{k-1}$.

Method:

- 1 Choose $x_0 \in Q$.
- 2 $y_k = \pi_Q \left(x_k - \frac{1}{\beta_k} G_{\delta, L}(x_k, \xi_k) \right)$.
- 3 $z_k = \arg \min_{x \in Q} \Psi_k(x) = \arg \min_{x \in Q} \left\{ \frac{\beta_k}{2} \|x - x_0\|_2^2 + \sum_{i=0}^k \alpha_i [F_{\delta, L}(x_i, \xi_i) + \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle] \right\}$.
- 4 $x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$, $\tau_k = \frac{\alpha_{k+1}}{A_{k+1}}$.

Choose $\alpha_i = \frac{i+1}{2\sqrt{2}}$, $\beta_i = L + \frac{\sigma}{2^{1/4}\sqrt{3}R} (i+2)^{3/2}$

Rate of convergence:

$\mathbb{E} f(y_k) - f^* \leq \frac{2^{3/2} L R^2}{(k+1)(k+2)} + \frac{2^{9/4} (k+3)^{3/2} \sigma R}{\sqrt{3} (k+1)(k+2)} + \frac{1}{3} (k+3) \delta$. Large deviations:
the same order.

Can be generalized to non-Euclidean setup and composite optimization.

Outline

- 1 Introduction to convex optimization
- 2 Concept of (δ, L) -oracle
- 3 Stochastic inexact oracle
- 4 Stochastic Intermediate Gradient Method

Problem formulation

The main problem we are going to consider is

$$\min_{x \in Q} \{\varphi(x) := f(x) + h(x)\},$$

where

Problem formulation

The main problem we are going to consider is

$$\min_{x \in Q} \{\varphi(x) := f(x) + h(x)\},$$

where

- 1 $Q \subset E$ is a closed convex set,

Problem formulation

The main problem we are going to consider is

$$\min_{x \in Q} \{\varphi(x) := f(x) + h(x)\},$$

where

- 1 $Q \subset E$ is a closed convex set,
- 2 $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable,

Problem formulation

The main problem we are going to consider is

$$\min_{x \in Q} \{\varphi(x) := f(x) + h(x)\},$$

where

- ① $Q \subset E$ is a closed convex set,
- ② $h(x)$ is a simple convex function: the problem $\min_{x \in Q} \{\langle g, x \rangle + \alpha d(x) + \beta h(x)\}$ is easy solvable,
- ③ $f(x)$ is convex function with stochastic inexact oracle.

Existing results

From the complexity theory: the best convergence rate when $\delta = 0$ is $\text{const} \cdot \frac{1}{\sqrt{k}}$.

Existing results

From the complexity theory: the best convergence rate when $\delta = 0$ is $\text{const} \cdot \frac{1}{\sqrt{k}}$. Some results by Devolder, Glineur and Nesterov, 2011-2013:

Existing results

From the complexity theory: the best convergence rate when $\delta = 0$ is $\text{const} \cdot \frac{1}{\sqrt{k}}$. Some results by Devolder, Glineur and Nesterov, 2011-2013:

- ❶ Stochastic Dual Gradient Method gives the mean rate (and large deviations)

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k} + \frac{\sigma R}{\sqrt{k}} + \delta \right).$$

Existing results

From the complexity theory: the best convergence rate when $\delta = 0$ is $\text{const} \cdot \frac{1}{\sqrt{k}}$. Some results by Devolder, Glineur and Nesterov, 2011-2013:

- 1 Stochastic Dual Gradient Method gives the mean rate (and large deviations)

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k} + \frac{\sigma R}{\sqrt{k}} + \delta \right).$$

- 2 Stochastic Fast Gradient Method gives the mean rate (and large deviations)

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k^2} + \frac{\sigma R}{\sqrt{k}} + k\delta \right).$$

Existing results

From the complexity theory: the best convergence rate when $\delta = 0$ is $\text{const} \cdot \frac{1}{\sqrt{k}}$. Some results by Devolder, Glineur and Nesterov, 2011-2013:

- 1 Stochastic Dual Gradient Method gives the mean rate (and large deviations)

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k} + \frac{\sigma R}{\sqrt{k}} + \delta \right).$$

- 2 Stochastic Fast Gradient Method gives the mean rate (and large deviations)

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k^2} + \frac{\sigma R}{\sqrt{k}} + k\delta \right).$$

- 3 For deterministic case Intermediate Gradient Method gives the rate

$$\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k^p} + k^{p-1}\delta \right),$$

where we can choose $p \in [1, 2]$.

Stochastic Intermediate Gradient Method

Our goal is the method

- ① with mean rate

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta \right),$$

where we can choose $p \in [1, 2]$

Stochastic Intermediate Gradient Method

Our goal is the method

- ① with mean rate

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta \right),$$

where we can choose $p \in [1, 2]$

- ② with **bounded large deviations** from this rate,

Stochastic Intermediate Gradient Method

Our goal is the method

- 1 with mean rate

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right),$$

where we can choose $p \in [1, 2]$

- 2 with **bounded large deviations** from this rate,
- 3 which is possible to use in **non-Euclidean set-up** (free choice of the norm),

Stochastic Intermediate Gradient Method

Our goal is the method

- ① with mean rate

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \Theta \left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta \right),$$

where we can choose $p \in [1, 2]$

- ② with **bounded large deviations** from this rate,
- ③ which is possible to use in **non-Euclidean set-up** (free choice of the norm),
- ④ applicable to **composite optimization** problems.

- Simple gradient mapping

$$y = \arg \min_{x \in Q} \{ \beta_k d(x) + \alpha_k [F_{\delta,L}(x_k, \xi_k) + \langle G_{\delta,L}(x_k, \xi_k), x - x_k \rangle] + h(x) \}.$$

- Simple gradient mapping

$$y = \arg \min_{x \in Q} \{ \beta_k d(x) + \alpha_k [F_{\delta,L}(x_k, \xi_k) + \langle G_{\delta,L}(x_k, \xi_k), x - x_k \rangle] + h(x) \}.$$

- Minimum of smoothed model of the function

$$z = \arg \min_{x \in Q} \{ \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle] + A_k h(x) \}$$

Let $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be three sequences of coefficients satisfying

Let $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be three sequences of coefficients satisfying

$$\alpha_0 \in (0, 1], \quad \beta_{i+1} \geq \beta_i > L, \quad \forall i \geq 0,$$

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0,$$

$$\alpha_k^2 \beta_k \leq B_k \beta_{k-1} \leq \left(\sum_{i=0}^k \alpha_i \right) \beta_{k-1}, \quad \forall k \geq 1.$$

Auxiliary objects

Let $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ be three sequences of coefficients satisfying

$$\alpha_0 \in (0, 1], \quad \beta_{i+1} \geq \beta_i > L, \quad \forall i \geq 0,$$

$$0 \leq \alpha_i \leq B_i, \quad \forall i \geq 0,$$

$$\alpha_k^2 \beta_k \leq B_k \beta_{k-1} \leq \left(\sum_{i=0}^k \alpha_i \right) \beta_{k-1}, \quad \forall k \geq 1.$$

We define also $A_k = \sum_{i=0}^k \alpha_i$ and $\tau_i = \frac{\alpha_{i+1}}{B_{i+1}}$.

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$.

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$. Output: The point y_k .

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$. Output: The point y_k .

1 $x_0 = \arg \min_{x \in Q} \{d(x)\}.$

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$. Output: The point y_k .

1 $x_0 = \arg \min_{x \in Q} \{d(x)\}.$

2
$$y_0 = \arg \min_{x \in Q} \{\beta_0 d(x) + \alpha_0 \langle G_{\delta, L}(x_0, \xi_0), x - x_0 \rangle + h(x)\}$$

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$. Output: The point y_k .

1 $x_0 = \arg \min_{x \in Q} \{d(x)\}.$

2
$$y_0 = \arg \min_{x \in Q} \{\beta_0 d(x) + \alpha_0 \langle G_{\delta, L}(x_0, \xi_0), x - x_0 \rangle + h(x)\}$$

3 for $k = 0, 1, \dots$ repeat

4
$$z_k = \arg \min_{x \in Q} \{\beta_k d(x) + \sum_{i=0}^k \alpha_i \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle + A_k h(x)\}$$

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$. Output: The point y_k .

1 $x_0 = \arg \min_{x \in Q} \{d(x)\}.$

2
$$y_0 = \arg \min_{x \in Q} \{\beta_0 d(x) + \alpha_0 \langle G_{\delta, L}(x_0, \xi_0), x - x_0 \rangle + h(x)\}$$

3 for $k = 0, 1, \dots$ repeat

4
$$z_k = \arg \min_{x \in Q} \{\beta_k d(x) + \sum_{i=0}^k \alpha_i \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle + A_k h(x)\}$$

5
$$x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$$

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$. Output: The point y_k .

1 $x_0 = \arg \min_{x \in Q} \{d(x)\}.$

2
$$y_0 = \arg \min_{x \in Q} \{\beta_0 d(x) + \alpha_0 \langle G_{\delta, L}(x_0, \xi_0), x - x_0 \rangle + h(x)\}$$

3 for $k = 0, 1, \dots$ repeat

4
$$z_k = \arg \min_{x \in Q} \{\beta_k d(x) + \sum_{i=0}^k \alpha_i \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle + A_k h(x)\}$$

5
$$x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$$

6
$$\hat{x}_{k+1} = \arg \min_{x \in Q} \{\beta_k V(x, z_k) + \alpha_{k+1} \langle G_{\delta, L}(x_{k+1}, \xi_{k+1}), x - z_k \rangle + \alpha_{k+1} h(x)\}.$$

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$. Output: The point y_k .

1 $x_0 = \arg \min_{x \in Q} \{d(x)\}.$

2
$$y_0 = \arg \min_{x \in Q} \{\beta_0 d(x) + \alpha_0 \langle G_{\delta, L}(x_0, \xi_0), x - x_0 \rangle + h(x)\}$$

3 for $k = 0, 1, \dots$ repeat

4
$$z_k = \arg \min_{x \in Q} \{\beta_k d(x) + \sum_{i=0}^k \alpha_i \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle + A_k h(x)\}$$

5
$$x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$$

6
$$\hat{x}_{k+1} = \arg \min_{x \in Q} \{\beta_k V(x, z_k) + \alpha_{k+1} \langle G_{\delta, L}(x_{k+1}, \xi_{k+1}), x - z_k \rangle + \alpha_{k+1} h(x)\}.$$

7
$$w_{k+1} = \tau_k \hat{x}_{k+1} + (1 - \tau_k) y_k$$

The method

Input: The sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$, functions $d(x)$, $V(x, z)$. Output: The point y_k .

1 $x_0 = \arg \min_{x \in Q} \{d(x)\}.$

2
$$y_0 = \arg \min_{x \in Q} \{\beta_0 d(x) + \alpha_0 \langle G_{\delta, L}(x_0, \xi_0), x - x_0 \rangle + h(x)\}$$

3 for $k = 0, 1, \dots$ repeat

4
$$z_k = \arg \min_{x \in Q} \{\beta_k d(x) + \sum_{i=0}^k \alpha_i \langle G_{\delta, L}(x_i, \xi_i), x - x_i \rangle + A_k h(x)\}$$

5
$$x_{k+1} = \tau_k z_k + (1 - \tau_k) y_k$$

6
$$\hat{x}_{k+1} = \arg \min_{x \in Q} \{\beta_k V(x, z_k) + \alpha_{k+1} \langle G_{\delta, L}(x_{k+1}, \xi_{k+1}), x - z_k \rangle + \alpha_{k+1} h(x)\}.$$

7
$$w_{k+1} = \tau_k \hat{x}_{k+1} + (1 - \tau_k) y_k$$

8
$$y_{k+1} = \frac{A_{k+1} - B_{k+1}}{A_{k+1}} y_k + \frac{B_{k+1}}{A_{k+1}} w_{k+1}$$

Estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle + h(x)]$
– model of the objective function.

Estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle + h(x)]$
– model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.

Estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle + h(x)]$
– model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k, \quad \Psi_k(x) \leq A_k \varphi(x) + \beta_k d(x) + \bar{E}_k(x), \quad \forall x \in Q.$$

Estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle + h(x)]$
– model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k, \quad \Psi_k(x) \leq A_k \varphi(x) + \beta_k d(x) + \bar{E}_k(x), \quad \forall x \in Q.$$

Then

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k \leq$$

Estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle + h(x)]$
– model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k, \quad \Psi_k(x) \leq A_k \varphi(x) + \beta_k d(x) + \bar{E}_k(x), \quad \forall x \in Q.$$

Then

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k \leq \Psi_k(x^*) + E_k \leq$$

Estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle + h(x)]$
– model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k, \quad \Psi_k(x) \leq A_k \varphi(x) + \beta_k d(x) + \bar{E}_k(x), \quad \forall x \in Q.$$

Then

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k \leq \Psi_k(x^*) + E_k \leq A_k \varphi^* + \beta_k d(x^*) + \bar{E}_k(x^*) + E_k,$$

and

Estimating functions

- $\Psi_k(x) = \beta_k d(x) + \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) + \langle G_{\delta,L}(x_i, \xi_i), x - x_i \rangle + h(x)]$
– model of the objective function.
- $\Psi_k^* = \min_{x \in Q} \Psi_k(x)$ its minimal value.
- If we prove that for all $k \geq 0$ it holds that

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k, \quad \Psi_k(x) \leq A_k \varphi(x) + \beta_k d(x) + \bar{E}_k(x), \quad \forall x \in Q.$$

Then

$$A_k \varphi(y_k) \leq \Psi_k^* + E_k \leq \Psi_k(x^*) + E_k \leq A_k \varphi^* + \beta_k d(x^*) + \bar{E}_k(x^*) + E_k,$$

and

$$\varphi(y_k) - \varphi^* \leq \frac{\beta_k}{A_k} d(x^*) + \frac{\bar{E}_k(x^*) + E_k}{A_k},$$

which can give us mean rate of convergence and probability of large deviations.

We managed to prove that

$$\begin{aligned} E_k &= \sum_{i=0}^k B_i \delta + \sum_{i=0}^k \frac{B_i}{\beta_i - L} (\|G_{\delta,L}(x_i, \xi_i) - g_{\delta,L}(x_i)\|_*)^2 + \\ &+ \sum_{i=0}^k \alpha_i (f_{\delta,L}(x_i) - F_{\delta,L}(x_i, \xi_i)) + \\ &+ \sum_{i=1}^k (B_i - \alpha_i) \frac{\alpha_i}{B_i} \langle g_{\delta,L}(x_i) - G_{\delta,L}(x_i, \xi_i), z_{i-1} - y_{i-1} \rangle, \\ \bar{E}_k(x) &= \sum_{i=0}^k \alpha_i [F_{\delta,L}(x_i, \xi_i) - f_{\delta,L}(x_i) + \\ &\langle G_{\delta,L}(x_i, \xi_i) - g_{\delta,L}(x_i), x - x_i \rangle]. \end{aligned}$$

General rate of convergence

Theorem 1

Assume that the function f is endowed with stochastic inexact oracle with parameters δ , L , σ . Then the sequence y_k generated by the Stochastic Intermediate Gradient Method, when applied to the composite function φ , satisfies

$$\begin{aligned}\varphi(y_k) - \varphi^* &\leq \frac{1}{A_k} \left(\beta_k d(x^*) + \sum_{i=0}^k B_i \delta + \right. \\ &+ \sum_{i=0}^k \frac{B_i}{\beta_i - L} \|G_{\delta,L}(x_i, \xi_i) - g_{\delta,L}(x_i)\|_*^2 + \\ &+ \sum_{i=0}^k \alpha_i \langle G_{\delta,L}(x_i, \xi_i) - g_{\delta,L}(x_i), x^* - x_i \rangle + \\ &\left. + \sum_{i=1}^k (B_i - \alpha_i) \frac{\alpha_i}{B_i} \langle G_{\delta,L}(x_i, \xi_i) - g_{\delta,L}(x_i), y_{i-1} - z_{i-1} \rangle \right).\end{aligned}$$

General mean rate of convergence

Taking expectation we get

Theorem 2

Assume that the function f is endowed with stochastic inexact oracle with parameters δ , L , σ . Then the sequence y_k generated by the Stochastic Intermediate Gradient Method, when applied to the composite function φ , satisfies

$$\mathbb{E}_{\xi_0, \dots, \xi_k} \varphi(y_k) - \varphi^* \leq \frac{\beta_k d(x^*)}{A_k} + \frac{\sum_{i=0}^k B_i \delta}{A_k} + \frac{1}{A_k} \sum_{i=0}^k \frac{B_i}{\beta_i - L} \sigma^2.$$

Additional assumptions

- 1 $\xi_0, \dots, \xi_k$ are i.i.d random variables.

Additional assumptions

- 1 $\xi_0, \dots, \xi_k$ are i.i.d random variables.
- 2 $G_{\delta,L}(x, \xi)$ satisfies the condition
$$\mathbb{E}_{\xi} \left[\exp \left(\frac{\|G_{\delta,L}(x, \xi) - g_{\delta,L}(x)\|_*^2}{\sigma^2} \right) \right] \leq \exp(1).$$

Additional assumptions

- ❶ $\xi_0, \dots, \xi_k$ are i.i.d random variables.
- ❷ $G_{\delta,L}(x, \xi)$ satisfies the condition
$$\mathbb{E}_{\xi} \left[\exp \left(\frac{\|G_{\delta,L}(x, \xi) - g_{\delta,L}(x)\|_*^2}{\sigma^2} \right) \right] \leq \exp(1).$$
- ❸ Set Q is bounded with diameter $D = \max_{x, y \in Q} \|x - y\|$.

Additional assumptions

① $\xi_0, \dots, \xi_k$ are i.i.d random variables.

② $G_{\delta,L}(x, \xi)$ satisfies the condition

$$\mathbb{E}_{\xi} \left[\exp \left(\frac{\|G_{\delta,L}(x, \xi) - g_{\delta,L}(x)\|_*^2}{\sigma^2} \right) \right] \leq \exp(1).$$

③ Set Q is bounded with diameter $D = \max_{x,y \in Q} \|x - y\|$.

$\xi_{[k]} = (\xi_0, \dots, \xi_k)$ – history of the random process after k iterations.

Auxiliary result 1

Lemma 1 [Juditsky, Lan, Nemirovski, Shapiro]

Let $\xi_0, \dots, \xi_k$ be a sequence of realizations of the i.i.d. random variables $X_0, \dots, X_k$ and let $\Delta_i = \Delta_i(\xi_{[i]})$ be a deterministic function of $\xi_{[i]}$ such that for all $i \geq 0$:

$$\mathbb{E} \left[\exp \left(\frac{\Delta_i^2}{\sigma^2} \right) \mid \xi_{[i-1]} \right] \leq \exp(1)$$

and $c_0, \dots, c_k$ is a sequence of positive coefficients. Then we have for any $k \geq 0$ and any $\Omega \geq 0$:

$$\mathbb{P} \left(\sum_{i=0}^k c_i \Delta_i^2 \geq (1 + \Omega) \sum_{i=0}^k c_i \sigma^2 \right) \leq \exp(-\Omega).$$

Lemma 2 [Lan, Nemirovski, Shapiro]

Let $\xi_0, \dots, \xi_k$ be a sequence of realizations of the i.i.d. random variables $X_0, \dots, X_k$ and let Γ_i and η_i be a deterministic function of $\xi_{[i]}$ such that:

- 1 $\mathbb{E} [\Gamma_i | \xi_{[i-1]}] = 0.$
- 2 $|\Gamma_i| \leq c_i \eta_i$, where c_i is positive deterministic constant.
- 3 $\mathbb{E} \left[\exp \left(\frac{\eta_i^2}{\sigma^2} \right) | \xi_{[i-1]} \right] \leq \exp(1).$

Then for any $k \geq 0$ and any $\Omega \geq 0$:

$$\mathbb{P} \left(\sum_{i=0}^k \Gamma_i \geq \sqrt{3\Omega} \sigma \sqrt{\sum_{i=0}^k c_i^2} \right) \leq \exp(-\Omega).$$

Theorem 3

If the assumptions 1, 2, 3 are satisfied, then for all $k \geq 0$ and all $\Omega \geq 0$, the sequence generated by the SGM satisfies:

$$\begin{aligned} \mathbb{P} \left(\varphi(y_k) - \varphi^* \geq \frac{\beta_k d(x^*)}{A_k} + \frac{\sum_{i=0}^k B_i \delta}{A_k} + \right. \\ \left. + \frac{1+\Omega}{A_k} \sum_{i=0}^k \frac{B_i}{\beta_i - L} \sigma^2 + \frac{2D\sigma\sqrt{3\Omega}}{A_k} \sqrt{\sum_{i=0}^k \alpha_i^2} \right) \leq 3 \exp(-\Omega). \end{aligned}$$

Choice of the coefficients

Our goal is the rate of $\Theta \left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta \right)$, $p \in [1, 2]$.

Choice of the coefficients

Our goal is the rate of $\Theta \left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta \right)$, $p \in [1, 2]$.

Let $a = 2^{\frac{2p-1}{2}}$ and $b = 2^{\frac{5-2p}{4}} p^{\frac{1-2p}{2}}$, $R \geq \sqrt{2d(x^*)}$.

Choice of the coefficients

Our goal is the rate of $\Theta \left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta \right)$, $p \in [1, 2]$.

Let $a = 2^{\frac{2p-1}{2}}$ and $b = 2^{\frac{5-2p}{4}} p^{\frac{1-2p}{2}}$, $R \geq \sqrt{2d(x^*)}$.

Then the sequences

$$\alpha_i = \frac{1}{a} \left(\frac{i+p}{p} \right)^{p-1}, \quad \forall i \geq 0,$$

$$\beta_i = L + \frac{b\sigma}{R} (i+p+1)^{\frac{2p-1}{2}}, \quad \forall i \geq 0,$$

$$B_i = a\alpha_i^2 = \frac{1}{a} \left(\frac{i+p}{p} \right)^{2p-2}, \quad \forall i \geq 0.$$

satisfy all the requirements.

Mean rate of convergence

Theorem 4

If the sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ are chosen from relations above and $p \in [1, 2]$ then the sequence generated by the SIGM satisfies:

$$\begin{aligned} \mathbb{E}_{\xi_0, \dots, \xi_k} \varphi(y_k) - \varphi^* &\leq \\ &\leq \frac{LR^2 p^p 2^{\frac{2p-3}{2}}}{(k+p)^p} + \frac{\sigma R 2^{\frac{3+2p}{4}} \sqrt{p} (k+p+2)^{p-\frac{1}{2}}}{(k+p)^p} + \\ &+ 2^{2p-1} \left(\left(\frac{k+p}{p} \right)^{p-1} + 1 \right) \delta = \\ &= \Theta \left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1} \delta \right). \end{aligned}$$

Large deviations bound

Theorem 5

If the sequences $\{\alpha_i\}_{i \geq 0}$, $\{\beta_i\}_{i \geq 0}$, $\{B_i\}_{i \geq 0}$ are chosen from relations above and $p \in [1, 2]$ then the sequence generated by the SIGM satisfies:

$$\begin{aligned} & \mathbb{P} \left(\varphi(y_k) - \varphi^* > \right. \\ & > \frac{LR^2 p^p 2^{\frac{2p-3}{2}}}{(k+p)^p} + \frac{(1+\Omega)\sigma R 2^{\frac{3+2p}{4}} \sqrt{p}(k+p+2)^{p-\frac{1}{2}}}{(k+p)^p} + \\ & + 2^{2p-1} \left(\left(\frac{k+p}{p} \right)^{p-1} + 1 \right) \delta + \frac{2D\sigma\sqrt{6p\Omega}}{\sqrt{k+p}} \Big) \leq \\ & \leq 3 \exp(-3\Omega). \end{aligned}$$

SIGM: mean complexity

For SIGM we have $(\sqrt{V(x_0, x^*)} \leq R)$.

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \frac{c_1 LV(x_0, x^*)}{k^p} + \frac{c_2 \sigma R}{\sqrt{k}} + c_3 k^{p-1} \delta.$$

SIGM: mean complexity

For SIGM we have $(\sqrt{V(x_0, x^*)} \leq R)$.

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \frac{c_1 LV(x_0, x^*)}{k^p} + \frac{c_2 \sigma R}{\sqrt{k}} + c_3 k^{p-1} \delta.$$

If we choose $k \geq \max \left\{ \left(\frac{2c_1 LV(x_0, x^*)}{\varepsilon} \right)^{\frac{1}{p}}, \frac{4c_2^2 \sigma^2 R^2}{\varepsilon^2} \right\},$

SIGM: mean complexity

For SIGM we have $(\sqrt{V(x_0, x^*)} \leq R)$.

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \frac{c_1 LV(x_0, x^*)}{k^p} + \frac{c_2 \sigma R}{\sqrt{k}} + c_3 k^{p-1} \delta.$$

If we choose $k \geq \max \left\{ \left(\frac{2c_1 LV(x_0, x^*)}{\varepsilon} \right)^{\frac{1}{p}}, \frac{4c_2^2 \sigma^2 R^2}{\varepsilon^2} \right\}$, then

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \varepsilon + c_3 k^{p-1} \delta.$$

SIGM: mean complexity

For SIGM we have $(\sqrt{V(x_0, x^*)} \leq R)$.

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \frac{c_1 LV(x_0, x^*)}{k^p} + \frac{c_2 \sigma R}{\sqrt{k}} + c_3 k^{p-1} \delta.$$

If we choose $k \geq \max \left\{ \left(\frac{2c_1 LV(x_0, x^*)}{\varepsilon} \right)^{\frac{1}{p}}, \frac{4c_2^2 \sigma^2 R^2}{\varepsilon^2} \right\}$, then

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \varepsilon + c_3 k^{p-1} \delta.$$

The goal is to obtain for μ -strongly convex function

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \varepsilon + \tilde{c}_3 \left(\frac{L}{\mu} \right)^{\frac{p-1}{p}} \delta$$

in

SIGM: mean complexity

For SIGM we have $(\sqrt{V(x_0, x^*)} \leq R)$.

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \frac{c_1 LV(x_0, x^*)}{k^p} + \frac{c_2 \sigma R}{\sqrt{k}} + c_3 k^{p-1} \delta.$$

If we choose $k \geq \max \left\{ \left(\frac{2c_1 LV(x_0, x^*)}{\varepsilon} \right)^{\frac{1}{p}}, \frac{4c_2^2 \sigma^2 R^2}{\varepsilon^2} \right\}$, then

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \varepsilon + c_3 k^{p-1} \delta.$$

The goal is to obtain for μ -strongly convex function

$$\mathbb{E}\varphi(y_k) - \varphi^* \leq \varepsilon + \tilde{c}_3 \left(\frac{L}{\mu} \right)^{\frac{p-1}{p}} \delta$$

in

$$N(\varepsilon) = \tilde{c}_1 \left(\frac{L}{\mu} \right)^{\frac{1}{p}} \ln \frac{\mu R_0^2}{\varepsilon} + \tilde{c}_2 \frac{\sigma^2}{\mu \varepsilon}$$

oracle calls.

SIGM: strongly convex case

Assume that $\varphi(x)$ is strongly convex. Then

$$\varphi(x) - \varphi(x^*) \geq \frac{\mu}{2} \|x - x^*\|^2, \quad \forall x \in Q.$$

SIGM: strongly convex case

Assume that $\varphi(x)$ is strongly convex. Then

$$\varphi(x) - \varphi(x^*) \geq \frac{\mu}{2} \|x - x^*\|^2, \quad \forall x \in Q.$$

Assume that $V(x, z)$ has quadratic growth with parameter $\varkappa \geq 1$, i.e.:

$$V(x, z) \leq \frac{\varkappa}{2} \|x - z\|^2, \quad \forall x, z \in Q.$$

SIGM: strongly convex case

Assume that $\varphi(x)$ is strongly convex. Then

$$\varphi(x) - \varphi(x^*) \geq \frac{\mu}{2} \|x - x^*\|^2, \quad \forall x \in Q.$$

Assume that $V(x, z)$ has quadratic growth with parameter $\varkappa \geq 1$, i.e.:

$$V(x, z) \leq \frac{\varkappa}{2} \|x - z\|^2, \quad \forall x, z \in Q.$$

Then

$$\mathbb{E} V(y_k, x^*) \leq \frac{\varkappa}{\mu} (\mathbb{E} \varphi(y_k) - \varphi(x^*)).$$

SIGM: strongly convex case

Assume that $\varphi(x)$ is strongly convex. Then

$$\varphi(x) - \varphi(x^*) \geq \frac{\mu}{2} \|x - x^*\|^2, \quad \forall x \in Q.$$

Assume that $V(x, z)$ has quadratic growth with parameter $\varkappa \geq 1$, i.e.:

$$V(x, z) \leq \frac{\varkappa}{2} \|x - z\|^2, \quad \forall x, z \in Q.$$

Then

$$\mathbb{E} V(y_k, x^*) \leq \frac{\varkappa}{\mu} (\mathbb{E} \varphi(y_k) - \varphi(x^*)).$$

Let us change $G_{\delta,L}(x, \xi_j) \rightarrow \tilde{G}_{\delta,L}(x, \Xi) = \frac{1}{m} \sum_{j=1}^m G_{\delta,L}(x, \xi_j)$.

SIGM: strongly convex case

Assume that $\varphi(x)$ is strongly convex. Then

$$\varphi(x) - \varphi(x^*) \geq \frac{\mu}{2} \|x - x^*\|^2, \quad \forall x \in Q.$$

Assume that $V(x, z)$ has quadratic growth with parameter $\varkappa \geq 1$, i.e.:

$$V(x, z) \leq \frac{\varkappa}{2} \|x - z\|^2, \quad \forall x, z \in Q.$$

Then

$$\mathbb{E} V(y_k, x^*) \leq \frac{\varkappa}{\mu} (\mathbb{E} \varphi(y_k) - \varphi(x^*)).$$

Let us change $G_{\delta,L}(x, \xi_j) \rightarrow \tilde{G}_{\delta,L}(x, \Xi) = \frac{1}{m} \sum_{j=1}^m G_{\delta,L}(x, \xi_j)$.

Then $\sigma^2 \rightarrow \frac{\sigma^2}{m}$ and

$$\mathbb{E} \varphi(y_k) - \varphi^* \leq \frac{c_1 L V(x_0, x^*)}{k^p} + \frac{c_2 \sigma R}{\sqrt{mk}} + c_3 k^{p-1} \delta.$$

SIGM: strongly convex case

Assume that $\varphi(x)$ is strongly convex. Then

$$\varphi(x) - \varphi(x^*) \geq \frac{\mu}{2} \|x - x^*\|^2, \quad \forall x \in Q.$$

Assume that $V(x, z)$ has quadratic growth with parameter $\varkappa \geq 1$, i.e.:

$$V(x, z) \leq \frac{\varkappa}{2} \|x - z\|^2, \quad \forall x, z \in Q.$$

Then

$$\mathbb{E} V(y_k, x^*) \leq \frac{\varkappa}{\mu} (\mathbb{E} \varphi(y_k) - \varphi(x^*)).$$

Let us change $G_{\delta,L}(x, \xi_j) \rightarrow \tilde{G}_{\delta,L}(x, \Xi) = \frac{1}{m} \sum_{j=1}^m G_{\delta,L}(x, \xi_j)$.

Then $\sigma^2 \rightarrow \frac{\sigma^2}{m}$ and

$$\mathbb{E} \varphi(y_k) - \varphi^* \leq \frac{c_1 L V(x_0, x^*)}{k^p} + \frac{c_2 \sigma R}{\sqrt{mk}} + c_3 k^{p-1} \delta.$$

Let us use restart technique.

SIGM: strongly convex case

Denote $\Delta_k = \varphi(y_{N_k}) - \varphi^*$. Let us perform N_0 iterations with $R^2 = \frac{\kappa}{\mu} \Delta_0 \stackrel{\text{def}}{=} R_0^2$ and $m = m_0$.

SIGM: strongly convex case

Denote $\Delta_k = \varphi(y_{N_k}) - \varphi^*$. Let us perform N_0 iterations with $R^2 = \frac{\varkappa}{\mu} \Delta_0 \stackrel{\text{def}}{=} R_0^2$ and $m = m_0$. Then

$$\mathbb{E} \Delta_1 \leq \frac{c_1 L \varkappa \Delta_0}{\mu N_0^p} + \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \Delta_0}}{\sqrt{m_0 N_0}} + c_3 N_0^{p-1} \delta$$

SIGM: strongly convex case

Denote $\Delta_k = \varphi(y_{N_k}) - \varphi^*$. Let us perform N_0 iterations with $R^2 = \frac{\varkappa}{\mu} \Delta_0 \stackrel{\text{def}}{=} R_0^2$ and $m = m_0$. Then

$$\mathbb{E} \Delta_1 \leq \frac{c_1 L \varkappa \Delta_0}{\mu N_0^p} + \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \Delta_0}}{\sqrt{m_0 N_0}} + c_3 N_0^{p-1} \delta$$

Let us choose $N_0 = \left(\frac{4c_1 L \varkappa}{\mu} \right)^{\frac{1}{p}}$ and $m_0 \geq \max \left\{ 1, \frac{16c_2^2 \sigma^2 \varkappa}{\mu N_0 \Delta_0} \right\}$.

SIGM: strongly convex case

Denote $\Delta_k = \varphi(y_{N_k}) - \varphi^*$. Let us perform N_0 iterations with $R^2 = \frac{\varkappa}{\mu} \Delta_0 \stackrel{\text{def}}{=} R_0^2$ and $m = m_0$. Then

$$\mathbb{E} \Delta_1 \leq \frac{c_1 L \varkappa \Delta_0}{\mu N_0^p} + \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \Delta_0}}{\sqrt{m_0 N_0}} + c_3 N_0^{p-1} \delta$$

Let us choose $N_0 = \left(\frac{4c_1 L \varkappa}{\mu} \right)^{\frac{1}{p}}$ and $m_0 \geq \max \left\{ 1, \frac{16c_2^2 \sigma^2 \varkappa}{\mu N_0 \Delta_0} \right\}$. Denote $\hat{N} \stackrel{\text{def}}{=} \left(\frac{4c_1 L \varkappa}{\mu} \right)^{\frac{p-1}{p}}$

SIGM: strongly convex case

Denote $\Delta_k = \varphi(y_{N_k}) - \varphi^*$. Let us perform N_0 iterations with $R^2 = \frac{\varkappa}{\mu} \Delta_0 \stackrel{\text{def}}{=} R_0^2$ and $m = m_0$. Then

$$\mathbb{E} \Delta_1 \leq \frac{c_1 L \varkappa \Delta_0}{\mu N_0^p} + \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \Delta_0}}{\sqrt{m_0 N_0}} + c_3 N_0^{p-1} \delta$$

Let us choose $N_0 = \left(\frac{4c_1 L \varkappa}{\mu} \right)^{\frac{1}{p}}$ and $m_0 \geq \max \left\{ 1, \frac{16c_2^2 \sigma^2 \varkappa}{\mu N_0 \Delta_0} \right\}$. Denote $\hat{N} \stackrel{\text{def}}{=} \left(\frac{4c_1 L \varkappa}{\mu} \right)^{\frac{p-1}{p}}$. Then

$$\frac{c_1 L \varkappa \Delta_0}{\mu N_0^p} = \frac{\Delta_0}{4}, \quad \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \Delta_0}}{\sqrt{m_0 N_0}} \leq \frac{\Delta_0}{4},$$

SIGM: strongly convex case

Denote $\Delta_k = \varphi(y_{N_k}) - \varphi^*$. Let us perform N_0 iterations with $R^2 = \frac{\varkappa}{\mu} \Delta_0 \stackrel{\text{def}}{=} R_0^2$ and $m = m_0$. Then

$$\mathbb{E}\Delta_1 \leq \frac{c_1 L \varkappa \Delta_0}{\mu N_0^p} + \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \Delta_0}}{\sqrt{m_0 N_0}} + c_3 N_0^{p-1} \delta$$

Let us choose $N_0 = \left(\frac{4c_1 L \varkappa}{\mu}\right)^{\frac{1}{p}}$ and $m_0 \geq \max\left\{1, \frac{16c_2^2 \sigma^2 \varkappa}{\mu N_0 \Delta_0}\right\}$. Denote $\hat{N} \stackrel{\text{def}}{=} \left(\frac{4c_1 L \varkappa}{\mu}\right)^{\frac{p-1}{p}}$. Then

$$\frac{c_1 L \varkappa \Delta_0}{\mu N_0^p} = \frac{\Delta_0}{4}, \quad \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \Delta_0}}{\sqrt{m_0 N_0}} \leq \frac{\Delta_0}{4},$$

and

$$\mathbb{E}\Delta_1 \leq \frac{\Delta_0}{2} + c_3 \hat{N} \delta.$$

SIGM: strongly convex case

Also we have

$$\mathbb{E}V(y_{N_0}, x^*) \leq \frac{\kappa}{\mu} \mathbb{E}\Delta_1 \leq \frac{\kappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right).$$

SIGM: strongly convex case

Also we have

$$\mathbb{E}V(y_{N_0}, x^*) \leq \frac{\kappa}{\mu} \mathbb{E}\Delta_1 \leq \frac{\kappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right).$$

We make N_1 iterations with $R^2 = \frac{\kappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right) \stackrel{\text{def}}{=} R_1^2$ and $m = m_1$.

SIGM: strongly convex case

Also we have

$$\mathbb{E}V(y_{N_0}, x^*) \leq \frac{\varkappa}{\mu} \mathbb{E}\Delta_1 \leq \frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right).$$

We make N_1 iterations with $R^2 = \frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right) \stackrel{\text{def}}{=} R_1^2$ and $m = m_1$.

Then

$$\mathbb{E}\Delta_2 \leq \frac{c_1 L \varkappa}{\mu N_1^p} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right) + \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right)}}{\sqrt{m_1 N_1}} + c_3 N_1^{p-1} \delta$$

SIGM: strongly convex case

Also we have

$$\mathbb{E}V(y_{N_0}, x^*) \leq \frac{\varkappa}{\mu} \mathbb{E}\Delta_1 \leq \frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right).$$

We make N_1 iterations with $R^2 = \frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right) \stackrel{\text{def}}{=} R_1^2$ and $m = m_1$.

Then

$$\mathbb{E}\Delta_2 \leq \frac{c_1 L \varkappa}{\mu N_1^p} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right) + \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right)}}{\sqrt{m_1 N_1}} + c_3 N_1^{p-1} \delta$$

Let us choose $N_1 = N_0$ and $m_1 \geq \max \left\{ 1, \frac{16 c_2^2 \sigma^2 \varkappa}{\mu N_0 \left(\frac{\Delta_0}{2} + c_3 \hat{N} \delta \right)} \right\}$.

SIGM: strongly convex case

Also we have

$$\mathbb{E}V(y_{N_0}, x^*) \leq \frac{\varkappa}{\mu} \mathbb{E}\Delta_1 \leq \frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right).$$

We make N_1 iterations with $R^2 = \frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right) \stackrel{\text{def}}{=} R_1^2$ and $m = m_1$.

Then

$$\mathbb{E}\Delta_2 \leq \frac{c_1 L \varkappa}{\mu N_1^p} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right) + \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right)}}{\sqrt{m_1 N_1}} + c_3 N_1^{p-1} \delta$$

Let us choose $N_1 = N_0$ and $m_1 \geq \max \left\{ 1, \frac{16c_2^2 \sigma^2 \varkappa}{\mu N_0 \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right)} \right\}$. Then

$$\frac{c_1 L \varkappa}{\mu N_1^p} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right) = \frac{1}{4} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right), \quad \frac{c_2 \sigma \sqrt{\frac{\varkappa}{\mu} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right)}}{\sqrt{m_1 N_1}} \leq \frac{1}{4} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right),$$

and

$$\mathbb{E}\Delta_2 \leq \frac{1}{2} \left(\frac{\Delta_0}{2} + c_3 \hat{N}\delta \right) + c_3 \hat{N}\delta.$$

SIGM: strongly convex case

On the k -th iteration we have

$$\mathbb{E}\Delta_k \leq \frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta\left(1 - \frac{1}{2^k}\right).$$

SIGM: strongly convex case

On the k -th iteration we have

$$\mathbb{E}\Delta_k \leq \frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right).$$

We continue choosing on the k -th iteration

$$N_k = N_0, \quad m_k = \max \left\{ 1, \left\lceil \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \Delta_0} \right\rceil \right\} \geq \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right)},$$

SIGM: strongly convex case

On the k -th iteration we have

$$\mathbb{E}\Delta_k \leq \frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right).$$

We continue choosing on the k -th iteration

$$N_k = N_0, \quad m_k = \max \left\{ 1, \left\lceil \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \Delta_0} \right\rceil \right\} \geq \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right)},$$

and obtain

$$\mathbb{E}\Delta_{k+1} \leq \frac{1}{2} \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right) + c_3\hat{N}\delta = \frac{\Delta_0}{2^{k+1}} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^{k+1}}\right).$$

SIGM: strongly convex case

On the k -th iteration we have

$$\mathbb{E}\Delta_k \leq \frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right).$$

We continue choosing on the k -th iteration

$$N_k = N_0, \quad m_k = \max \left\{ 1, \left\lceil \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \Delta_0} \right\rceil \right\} \geq \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right)},$$

and obtain

$$\mathbb{E}\Delta_{k+1} \leq \frac{1}{2} \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right) + c_3\hat{N}\delta = \frac{\Delta_0}{2^{k+1}} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^{k+1}}\right).$$

If we perform $N = \log_2 \frac{\Delta_0}{\varepsilon} = \log_2 \frac{\mu R_0^2}{\kappa \varepsilon}$ outer iterations we will obtain the error

$$\mathbb{E}\Delta_N \leq \varepsilon + \tilde{c}_3 \left(\frac{L}{\mu} \right)^{\frac{p-1}{p}} \delta.$$

SIGM: strongly convex case

On the k -th iteration we have

$$\mathbb{E}\Delta_k \leq \frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right).$$

We continue choosing on the k -th iteration

$$N_k = N_0, \quad m_k = \max \left\{ 1, \left\lceil \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \Delta_0} \right\rceil \right\} \geq \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right)},$$

and obtain

$$\mathbb{E}\Delta_{k+1} \leq \frac{1}{2} \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right) + c_3\hat{N}\delta = \frac{\Delta_0}{2^{k+1}} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^{k+1}}\right).$$

If we perform $N = \log_2 \frac{\Delta_0}{\varepsilon} = \log_2 \frac{\mu R_0^2}{\kappa \varepsilon}$ outer iterations we will obtain the error

$$\mathbb{E}\Delta_N \leq \varepsilon + \tilde{c}_3 \left(\frac{L}{\mu} \right)^{\frac{p-1}{p}} \delta.$$

And the number of oracle calls will be

$$N(\varepsilon) = \sum_{i=0}^N N_i m_i$$

SIGM: strongly convex case

On the k -th iteration we have

$$\mathbb{E}\Delta_k \leq \frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right).$$

We continue choosing on the k -th iteration

$$N_k = N_0, \quad m_k = \max \left\{ 1, \left\lceil \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \Delta_0} \right\rceil \right\} \geq \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right)},$$

and obtain

$$\mathbb{E}\Delta_{k+1} \leq \frac{1}{2} \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right) + c_3\hat{N}\delta = \frac{\Delta_0}{2^{k+1}} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^{k+1}}\right).$$

If we perform $N = \log_2 \frac{\Delta_0}{\varepsilon} = \log_2 \frac{\mu R_0^2}{\kappa \varepsilon}$ outer iterations we will obtain the error

$$\mathbb{E}\Delta_N \leq \varepsilon + \tilde{c}_3 \left(\frac{L}{\mu} \right)^{\frac{p-1}{p}} \delta.$$

And the number of oracle calls will be

$$N(\varepsilon) = \sum_{i=0}^N N_i m_i \leq N_0 \sum_{i=0}^N \left(1 + \frac{16c_2^2\sigma^2\kappa 2^i}{\mu N_0 \Delta_0} \right)$$

SIGM: strongly convex case

On the k -th iteration we have

$$\mathbb{E}\Delta_k \leq \frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right).$$

We continue choosing on the k -th iteration

$$N_k = N_0, \quad m_k = \max \left\{ 1, \left\lceil \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \Delta_0} \right\rceil \right\} \geq \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right)},$$

and obtain

$$\mathbb{E}\Delta_{k+1} \leq \frac{1}{2} \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right) + c_3\hat{N}\delta = \frac{\Delta_0}{2^{k+1}} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^{k+1}}\right).$$

If we perform $N = \log_2 \frac{\Delta_0}{\varepsilon} = \log_2 \frac{\mu R_0^2}{\kappa \varepsilon}$ outer iterations we will obtain the error

$$\mathbb{E}\Delta_N \leq \varepsilon + \tilde{c}_3 \left(\frac{L}{\mu} \right)^{\frac{p-1}{p}} \delta.$$

And the number of oracle calls will be

$$N(\varepsilon) = \sum_{i=0}^N N_i m_i \leq N_0 \sum_{i=0}^N \left(1 + \frac{16c_2^2\sigma^2\kappa 2^i}{\mu N_0 \Delta_0} \right) \leq N_0 N + \frac{32c_2^2\sigma^2\kappa 2^N}{\mu \Delta_0} =$$

SIGM: strongly convex case

On the k -th iteration we have

$$\mathbb{E}\Delta_k \leq \frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right).$$

We continue choosing on the k -th iteration

$$N_k = N_0, \quad m_k = \max \left\{ 1, \left\lceil \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \Delta_0} \right\rceil \right\} \geq \frac{16c_2^2\sigma^2\kappa 2^k}{\mu N_0 \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right)},$$

and obtain

$$\mathbb{E}\Delta_{k+1} \leq \frac{1}{2} \left(\frac{\Delta_0}{2^k} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^k}\right) \right) + c_3\hat{N}\delta = \frac{\Delta_0}{2^{k+1}} + 2c_3\hat{N}\delta \left(1 - \frac{1}{2^{k+1}}\right).$$

If we perform $N = \log_2 \frac{\Delta_0}{\varepsilon} = \log_2 \frac{\mu R_0^2}{\kappa \varepsilon}$ outer iterations we will obtain the error

$$\mathbb{E}\Delta_N \leq \varepsilon + \tilde{c}_3 \left(\frac{L}{\mu} \right)^{\frac{p-1}{p}} \delta.$$

And the number of oracle calls will be

$$N(\varepsilon) = \sum_{i=0}^N N_i m_i \leq N_0 \sum_{i=0}^N \left(1 + \frac{16c_2^2\sigma^2\kappa 2^i}{\mu N_0 \Delta_0} \right) \leq N_0 N + \frac{32c_2^2\sigma^2\kappa 2^N}{\mu \Delta_0} = \left(\frac{4c_1 L \kappa}{\mu} \right)^{\frac{1}{p}} \log_2 \frac{\mu R_0^2}{\kappa \varepsilon} + \frac{32c_2^2\sigma^2\kappa}{\mu \varepsilon}.$$

Discussion

We have obtained the method with mean rate of convergence of

$\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can chose $p \in [1, 2]$ in advance. It has the following advantages.

Discussion

We have obtained the method with mean rate of convergence of $\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can chose $p \in [1, 2]$ in advance. It has the following advantages.

- ① Large deviation bounds with same asymptotic dependence on k .

We have obtained the method with mean rate of convergence of $\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can choose $p \in [1, 2]$ in advance. It has the following advantages.

- 1 Large deviation bounds with same asymptotic dependence on k .
- 2 It can be used for problems from rather general class of problems with stochastic inexact oracle.

We have obtained the method with mean rate of convergence of $\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can chose $p \in [1, 2]$ in advance. It has the following advantages.

- ① Large deviation bounds with same asymptotic dependence on k .
- ② It can be used for problems from rather general class of problems with stochastic inexact oracle.
 - ① Nonsmooth problems.

We have obtained the method with mean rate of convergence of $\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can chose $p \in [1, 2]$ in advance. It has the following advantages.

- 1 Large deviation bounds with same asymptotic dependence on k .
- 2 It can be used for problems from rather general class of problems with stochastic inexact oracle.
 - 1 Nonsmooth problems.
 - 2 Auxiliary randomization in initially deterministic problem.

We have obtained the method with mean rate of convergence of $\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can choose $p \in [1, 2]$ in advance. It has the following advantages.

- 1 Large deviation bounds with same asymptotic dependence on k .
- 2 It can be used for problems from rather general class of problems with stochastic inexact oracle.
 - 1 Nonsmooth problems.
 - 2 Auxiliary randomization in initially deterministic problem.
- 3 Choose $p \in [1, 2]$ for optimal trade-off between error accumulation and rate of convergence.

We have obtained the method with mean rate of convergence of $\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can choose $p \in [1, 2]$ in advance. It has the following advantages.

- 1 Large deviation bounds with same asymptotic dependence on k .
- 2 It can be used for problems from rather general class of problems with stochastic inexact oracle.
 - 1 Nonsmooth problems.
 - 2 Auxiliary randomization in initially deterministic problem.
- 3 Choose $p \in [1, 2]$ for optimal trade-off between error accumulation and rate of convergence.
- 4 Flexibility of optimal choice of the norm and prox-function.

We have obtained the method with mean rate of convergence of $\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can choose $p \in [1, 2]$ in advance. It has the following advantages.

- 1 Large deviation bounds with same asymptotic dependence on k .
- 2 It can be used for problems from rather general class of problems with stochastic inexact oracle.
 - 1 Nonsmooth problems.
 - 2 Auxiliary randomization in initially deterministic problem.
- 3 Choose $p \in [1, 2]$ for optimal trade-off between error accumulation and rate of convergence.
- 4 Flexibility of optimal choice of the norm and prox-function.
- 5 Allows to solve composite optimization problems.

We have obtained the method with mean rate of convergence of $\Theta\left(\frac{LR^2}{k^p} + \frac{\sigma R}{\sqrt{k}} + k^{p-1}\delta\right)$, where we can choose $p \in [1, 2]$ in advance. It has the following advantages.

- 1 Large deviation bounds with same asymptotic dependence on k .
- 2 It can be used for problems from rather general class of problems with stochastic inexact oracle.
 - 1 Nonsmooth problems.
 - 2 Auxiliary randomization in initially deterministic problem.
- 3 Choose $p \in [1, 2]$ for optimal trade-off between error accumulation and rate of convergence.
- 4 Flexibility of optimal choice of the norm and prox-function.
- 5 Allows to solve composite optimization problems.
- 6 Can be accelerated in the strongly convex case.

Conclusion

- 1 We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.

Conclusion

- 1 We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- 2 We've considered new SIGM with intermediate rate of convergence in stochastic case.

Conclusion

- 1 We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- 2 We've considered new SIGM with intermediate rate of convergence in stochastic case.
- 3 We have seen the following tools which give us the flexibility for solving optimization problems and constructing new methods:
 - 1 Choice of the norm and prox-function

Conclusion

- ① We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- ② We've considered new SIGM with intermediate rate of convergence in stochastic case.
- ③ We have seen the following tools which give us the flexibility for solving optimization problems and constructing new methods:
 - ① Choice of the norm and prox-function
 - ② Composite optimization

Conclusion

- 1 We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- 2 We've considered new SIGM with intermediate rate of convergence in stochastic case.
- 3 We have seen the following tools which give us the flexibility for solving optimization problems and constructing new methods:
 - 1 Choice of the norm and prox-function
 - 2 Composite optimization
 - 3 Auxiliary deterministic inexactness

Conclusion

- 1 We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- 2 We've considered new SIGM with intermediate rate of convergence in stochastic case.
- 3 We have seen the following tools which give us the flexibility for solving optimization problems and constructing new methods:
 - 1 Choice of the norm and prox-function
 - 2 Composite optimization
 - 3 Auxiliary deterministic inexactness
 - 4 Artificial randomization

Conclusion

- 1 We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- 2 We've considered new SIGM with intermediate rate of convergence in stochastic case.
- 3 We have seen the following tools which give us the flexibility for solving optimization problems and constructing new methods:
 - 1 Choice of the norm and prox-function
 - 2 Composite optimization
 - 3 Auxiliary deterministic inexactness
 - 4 Artificial randomization
 - 5 Trade-off between rate of convergence and error accumulation error

Conclusion

- 1 We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- 2 We've considered new SIGM with intermediate rate of convergence in stochastic case.
- 3 We have seen the following tools which give us the flexibility for solving optimization problems and constructing new methods:
 - 1 Choice of the norm and prox-function
 - 2 Composite optimization
 - 3 Auxiliary deterministic inexactness
 - 4 Artificial randomization
 - 5 Trade-off between rate of convergence and error accumulation error
 - 6 Restart technique

Conclusion

- ① We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- ② We've considered new SIGM with intermediate rate of convergence in stochastic case.
- ③ We have seen the following tools which give us the flexibility for solving optimization problems and constructing new methods:
 - ① Choice of the norm and prox-function
 - ② Composite optimization
 - ③ Auxiliary deterministic inexactness
 - ④ Artificial randomization
 - ⑤ Trade-off between rate of convergence and error accumulation error
 - ⑥ Restart technique
 - ⑦ Amplification

Conclusion

- ❶ We've considered three gradient methods (PGM, DGM, FGM) and how they perform in the presence of stochastic and deterministic errors.
- ❷ We've considered new SIGM with intermediate rate of convergence in stochastic case.
- ❸ We have seen the following tools which give us the flexibility for solving optimization problems and constructing new methods:
 - ❶ Choice of the norm and prox-function
 - ❷ Composite optimization
 - ❸ Auxiliary deterministic inexactness
 - ❹ Artificial randomization
 - ❺ Trade-off between rate of convergence and error accumulation error
 - ❻ Restart technique
 - ❼ Amplification
 - ❽ Using the problem structure

References

-  O. Devolder, F. Glineur and Yu. Nesterov. *Intermediate Gradient Methods for Smooth Convex Problems with Inexact Oracle*. CORE Discussion Paper 2013/17, available at http://www.uclouvain.be/cps/ucl/doc/core/documents/coredp2013_17web.pdf.
-  O. Devolder, F. Glineur and Yu. Nesterov. *First-order Methods of Smooth Convex Optimization with Inexact Oracle*. CORE Discussion Paper 2011/2, available at http://www.optimization-online.org/DB_FILE/2010/12/2865.pdf.
-  A. Juditsky, G. Lan, A. Nemirovski, A. Shapiro *Stochastic approximation approach to stochastic programming*. SIAM Journal on Optimization. 2009, 19(4), pp. 1574–1609.
-  G. Lan, A. Nemirovski and A. Shapiro. *Validation analysis of mirror descent stochastic approximation method*. Mathematical Programming Serie A, 2012, 134(2), pp. 425–458.
-  O. Devolder. *Exactness, Inexactness and Stochasticity in First-Order Methods for Large-Scale Convex Optimization*, PhD thesis (2013).
-  S.Ghadimi, G.Lan, *Optimal Stochastic Approximation Algorithms for Strongly Convex Stochastic Composite Optimization I: A Generic Algorithmic Framework*, SIAM J. Optim., 2012, 22(4), pp. 1469–1492.
-  S.Ghadimi, G.Lan, *Optimal Stochastic Approximation Algorithms for Strongly Convex Stochastic Composite Optimization II: Shrinking Procedures and Optimal Algorithms*, SIAM J. Optim., 2013, 23(4), pp. 2061–2089.

Thank you for your attention!